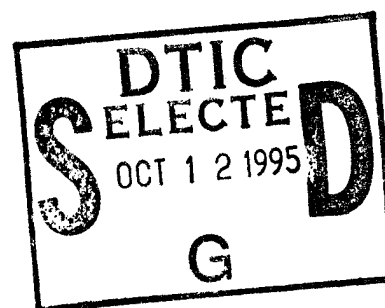


ARMY RESEARCH LABORATORY



Hydrocode Simulation of the Formation and Penetration of a Linear Shaped Demolition Charge Into an RHA Plate

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13. ABSTRACT (Maximum 200 words) This report presents the results of a combined experimental and numerical investigation of the formation and penetration of a linear shaped demolition charge into a rolled homogeneous armor (RHA) plate. The demolition charge is composed of a mild steel liner, filled with castable Composition-B high explosive. The numerical computations were conducted before the experiments using the Lagrangian hydrocode EPIC92 and predict a jet tip free flight velocity of about 5.2 km/s at 12 μ s. However, observed jet tip free flight velocities of the linear shaped charge (LSC) range from 3.3 to 3.5 km/s as determined from flash radiography, and 3.5 km/s using a special electrical makewire circuit test fixture. The reason for the large discrepancy between the predicted and observed jet tip free flight velocities appears to be related to computational inaccuracies resulting from the highly distorted computational mesh in the collapsing liner. Using the automatic rezone feature in the EPIC94 version of the hydrocode results in the reduction of the jet tip velocity from 4.7 km/s to 3.8 km/s at 4 μ s. However, computations beyond 4 μ s were not possible due to numerical instabilities associated with requiring a vanishingly small integration time increment resulting from an equation-of-state instability. Penetration depths into two rectangular, 2-in-thick (50.8 mm) RHA plates measure 17 and 18 mm respectively, whereas the hydrocode simulation predicts a greater penetration depth of 22.9 mm. The work attests to the importance of conducting experiments in order to verify baseline hydrocode simulations.				
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1. INTRODUCTION

Military demolition operations use a variety of shaped charge geometries (e.g., cylindrical, linear, curvilinear, and flexilinear) for the clearance of obstacles and barriers, the destruction of facilities and materiel, the construction of roads and trenches, and in land clearance and quarrying. The linear shaped charge (LSC) is commonly used in explosive ordnance disposal (EOD) as a means to initially cut open cases containing explosive-filled ordnance. The Mk-7 Mod 8 demolition charge (Figure 1) consists of an inert mild steel container (liner) filled with plastic explosive (e.g., C-4). A blasting cap is placed on the top surface of the explosive to prime the charge.

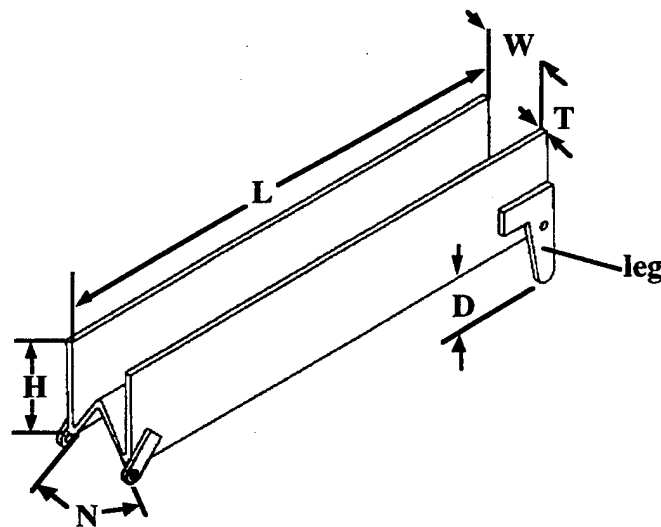


Figure 1. Critical dimensions of the Mk-7 Mod 8 demolition charge (Department of the Navy EODB/Department of the Army TM/U.S. Air Force TO 60A-2-1-51 1992).

The charges may be used individually or linked together in a continuous series if a long cut is desired. Linking several individual charges together in series is achieved by connecting the short leg of one charge to the long leg of an adjacent charge; in this configuration, the charge has a uniformly short standoff distance on the order of 28 mm (1.1 in), in the series arrangement (the dimensions of the Mk-7 Mod 8 charge are: $N = 80^\circ$, $W = 1.00$ in [25.4 mm], $T = 0.053$ in [1.35 mm], $H = 1.12$ in [28.45 mm], $L = 6.0$ in [152.4 mm], and $D = 1.06$ in [26.92 mm]).

The experimental determination of optimal jet cutting properties for a particular EOD application requires parametric variation of design variables such as the liner material, liner geometry, standoff distance, and explosive properties. Since experiments can be costly and hazardous to conduct, there is a strong motivation to develop numerical methods using hydrocodes to assist in the development of EOD procedures. Even though the Mk-7 series of demolition charges have a well-defined penetration depth

into steel and aluminum, these LSCs are known to produce low-order or high-order detonations (see Department of the Navy EODB/Department of the Army TM/U.S. Air Force TO 60A-2-1-51 1992). In this study, we use the Lagrangian-based hydrocode EPIC92 (Elastic Plastic Impact Calculations) (Johnson et al. 1992a, 1992b) to model the formation of an LSC (Mk-7 Mod 8 demolition charge), and its subsequent penetration into a 2-in (51 mm)-thick rolled-homogeneous-armor (RHA) plate. The incorporation of slideline erosion algorithms has permitted Lagrangian computations in large-scale penetration problems (Johnson 1984); nonetheless, Raftenberg (1994) points out that there are a paucity of shaped charge jet (SCJ) penetration studies using EPIC in the open literature. The Raftenberg (1994) study primarily concentrates on failure modeling of a thin RHA target perforated by a shaped charge of relatively long standoff distance; in that work, a 7.73 km/s particulated-copper jet tip is simulated by a 5-parameter geometric model using flash radiographic data. In this study, however, the jet is continuous and has a short standoff distance. Since the jet tip begins interacting with the RHA target almost immediately after it is formed, it is difficult to characterize the jet geometry using radiographic methods. For this reason, in this study, we model *both* the formation and penetration of the LSC using the EPIC92 hydrocode.

Experiments were performed for which the jet tip free flight velocity data are obtained from flash radiographs, and from a test fixture that is specially designed to measure the free flight velocity of the jet using a makewire circuit. These data are compared with the hydrocode velocity predictions in order to assess EPIC92 computational accuracy for the jet *formation* problem. The hydrocode computations were performed first, followed by the experiments, in order to avoid the bias inherent in studies which "tweak" the simulation parameters so as to exactly fit the experiment. Indeed, one of the motivations of the current study is to assess the accuracy of the hydrocode in instances where experimental data are lacking, such as in demolition work where data can be hazardous or costly to obtain. In addition, we compare the depth of penetration into the RHA target with the penetration depth predicted by the hydrocode. Finally, the accuracy in predicting the penetration depth will be shown to be a direct function of our ability to accurately model the formation of the jet.

2. COMPUTATIONS

Computations were performed using the Lagrangian-based explicit EPIC92 hydrocode (Johnson 1977; Johnson et al. 1992a, 1992b) that has been primarily used in the analysis of terminal ballistic or hypervelocity impact problems.

In the current case, we are trying to idealize the jet from an Mk-7 LSC, so that a rezoned version of the problem, without the difficulties associated with the distorted grid, may be employed to simulate the jet penetration. Our problem is further complicated by the fact that the jet must be idealized at a relatively late point in the jet formation process (chosen at 12 μ s), so that the rear of the jet is formed,

and is thus characterizable; yet the penetration simulation to follow is at such a short standoff that the resultant idealization must be backed up in time (to $7.2 \mu\text{s}$) to the onset of penetration. The initial grid for the jet formation problem appears in Figure 2. It consists of 1,485 nodes and 2,732 finite elements. The initial finite element grid was generated from the charge geometry given in the Introduction. The input deck and computational results out to $20 \mu\text{s}$ appear in Appendix A.

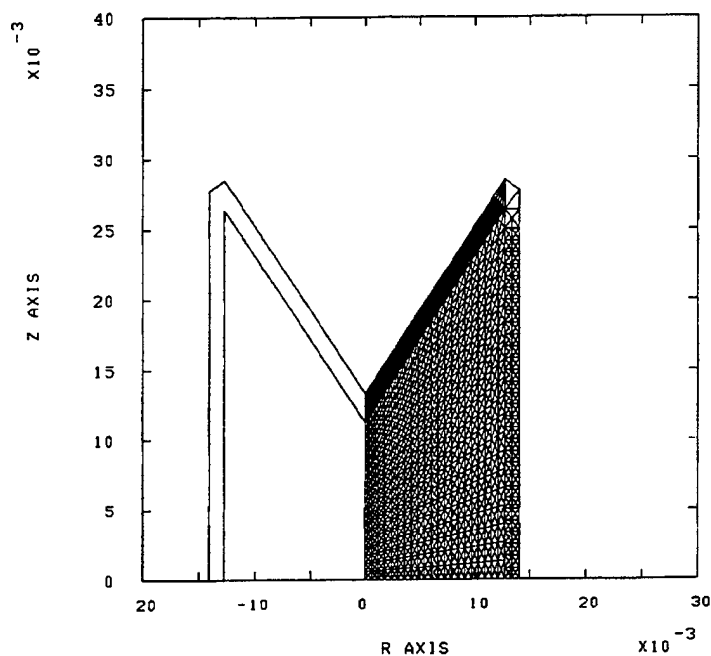


Figure 2. Computational mesh for jet formation problem (in meters).

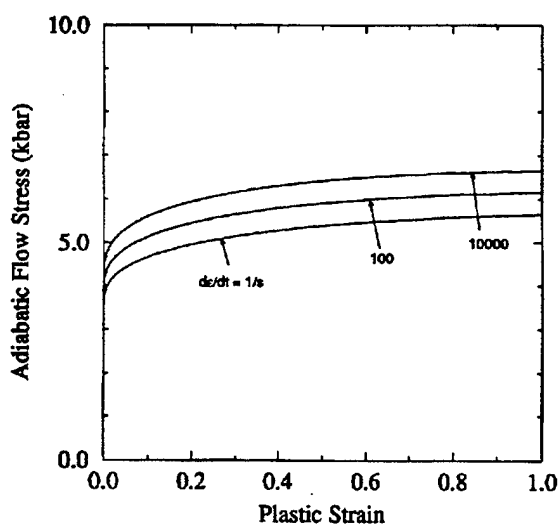


Figure 3. Adiabatic flow stress versus equivalent plastic strain for 1006 mild steel as a function of strain rate.

The distortional behavior of the mild steel liner material is modeled using the Johnson-Cook viscoplastic constitutive model (Johnson and Cook 1985) together with a von Mises initial yield condition (EPIC92 material model 6, 1006 steel, Figure 3). An isotropic hardening rule governs subsequent yield surface behavior together with a radial-return algorithm (Johnson 1984; Cook, Rajendran, and Grove 1992). Because of the high strain rates encountered in impact problems, the temperature fields in bodies modeled using EPIC92 are adiabatic ($dQ = 0$, i.e., there is no heat flow within the body) and thermal softening of a material element is directly proportional to the amount of accumulated plastic work. The dilatational behavior of the Comp-B high explosive is modeled using the Jones-Wilkins-Lee (JWL) equation of state (EPIC92 material model 43, Figure 4). The entire cross section of the finite element charge is simultaneously detonated in order to approximate a 2-D plane detonation wave traveling along the length of the charge.

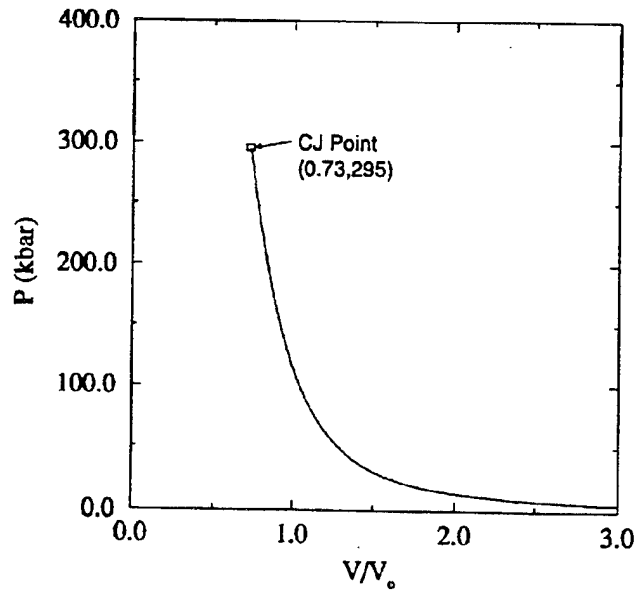


Figure 4. JWL equation-of-state isentrope for Comp-B.

The damage criterion in EPIC92 is assumed to be a scalar function of the incremental (cumulative) equivalent plastic strain, normalized with respect to the fracture strain (Johnson et al. 1992a, 1992b). If the damage threshold is exceeded in a particular finite element, the element behaves as a fluid, and cannot sustain shear or tensile stresses. EPIC92 has the capability of handling severe distortions encountered in SCJ penetration problems using an element erosion algorithm that eliminates

element volume, but retains element mass (e.g., when a critical value of the equivalent plastic strain is exceeded).

The initial mesh geometry for the penetration computations is illustrated in Figure 5. The initial geometry was derived based on the results of the jet formation simulation to be subsequently described. At the start of the computation, both the tip of the LSC jet and RHA target are in normal contact.

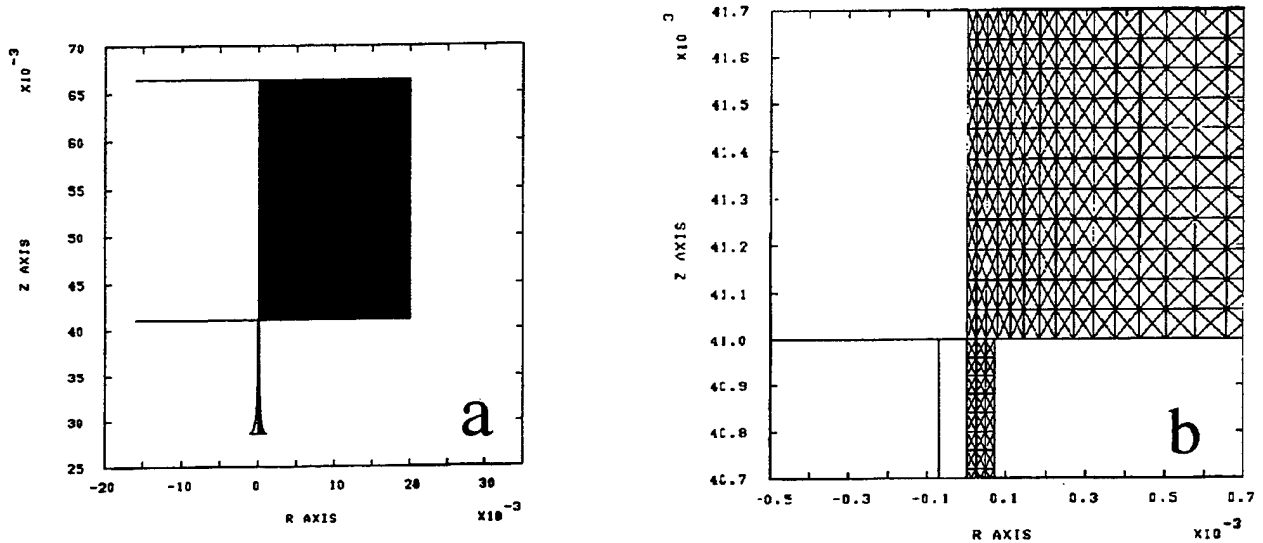


Figure 5. a) Computational mesh. b) Magnified computational mesh in the vicinity of the shaped charge jet tip (in meters).

The linear contact region between jet tip and target describes a locus of slideline points wherein both the jet tip and the target have been alternately defined as master and slave erosional surfaces. This procedure permits both the jet and the target to erode during the penetration process. The entire jet penetration simulation consists of 37,224 finite elements and 19,300 nodes; however, 3,720 elements and 2,170 nodes comprise the jet geometry, while the remainder are in the target. The finite elements are 2-D plane strain constant strain triangles (CSTs), with an assumed displacement field which varies linearly within each finite element. The jet *penetration* computations are described in detail in Section 2.2. In the next section, we more fully describe the details and difficulties encountered in modeling the jet *formation* problem.

2.1 LSC Jet Formation. When simulating the collapse and jet formation of a shaped charge, the resultant velocity distribution in the simulated jet is a function not only of axial location (which the idealized theories assume), but also of radial distance (Walters and Zukas 1989). Similarly, the discretized nature of Lagrangian simulations is such that additional velocity scatter along the simulated

jet occurs. This scattered velocity distribution poses problems when trying to idealize the jet in one dimension for subsequent modeling and/or analysis. The problem is modeled in 2-D plane strain, and therefore, to simulate a plane detonation wave traveling normal to the cross section of the LSC, all of the Comp-B is assumed to simultaneously detonate at the start of the simulation.

We first fit a curve directly to the cumulative mass distribution as a function of jet velocity, thus obtaining $M(v)$. Unfortunately, the velocity scatter inherent in the jet formation simulation caused the poor resultant fit, when viewed in terms of mass versus position (i.e., jet geometry). An enlarged view of this poor fit is shown in Figure 6, where the curve predicting the outer contour of the jet is compared to the liner's node points of the computer simulation at 12 μ s.

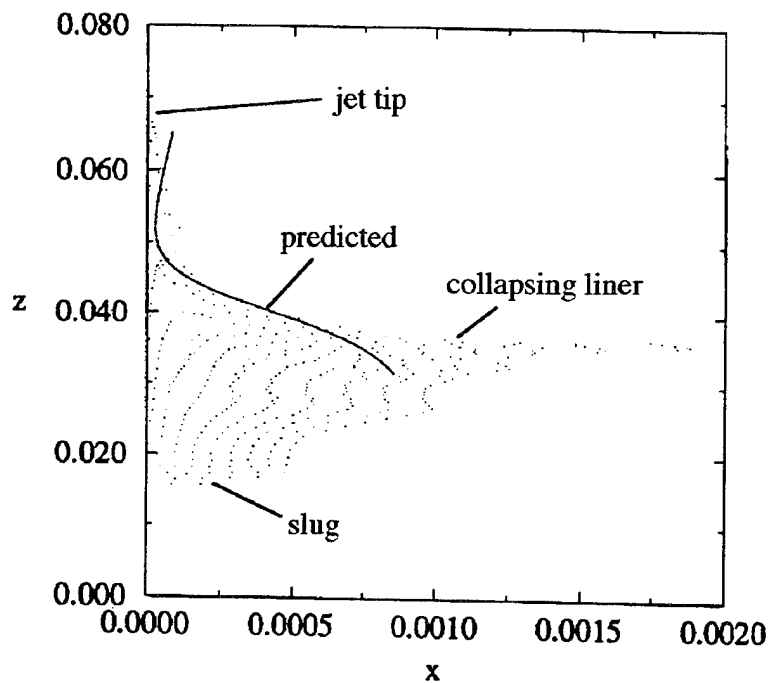


Figure 6. Prediction of jet contour at 12 μ s (solid line) versus hydrocode simulation (dots)
(length dimensions in meters, not to scale).

The full grid of the jet formation simulation at 12 μ s is shown in Figure 7. The original inner steel liner consists of 446 nodes and 800 elements. In light of this unacceptable fit, a second approach was taken, whereby cumulative jet mass was fit as a function of axial jet coordinate at the selected fitting time, $\bar{t} = 12 \mu$ s, giving $M(\bar{z})$ (see Figure 8). Use of this fit to axial location should guarantee a good fit to the jet geometry. If a reasonable fit can be made to the scattered data of axial position versus jet velocity, $\bar{z} = \bar{z}(v)$ (see Figure 9), then the fit to cumulative mass versus velocity may be derived by combining

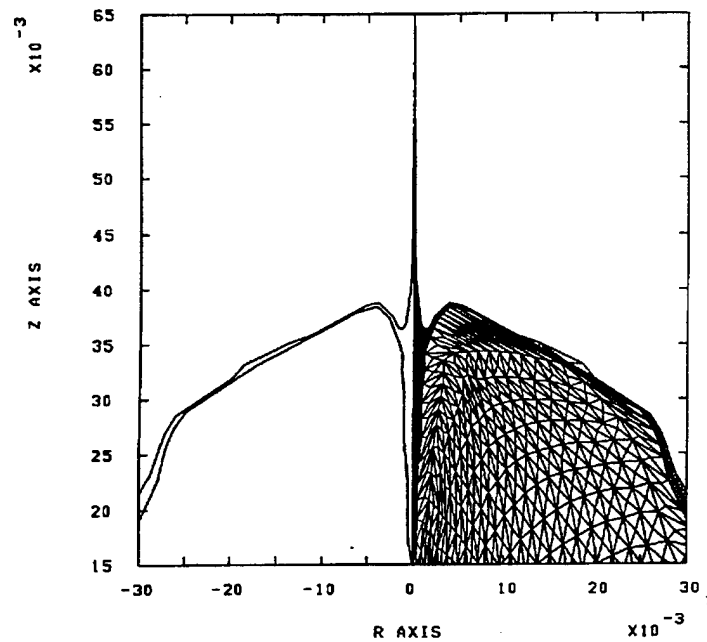


Figure 7. LSC jet geometry at 12 μ s (in meters).

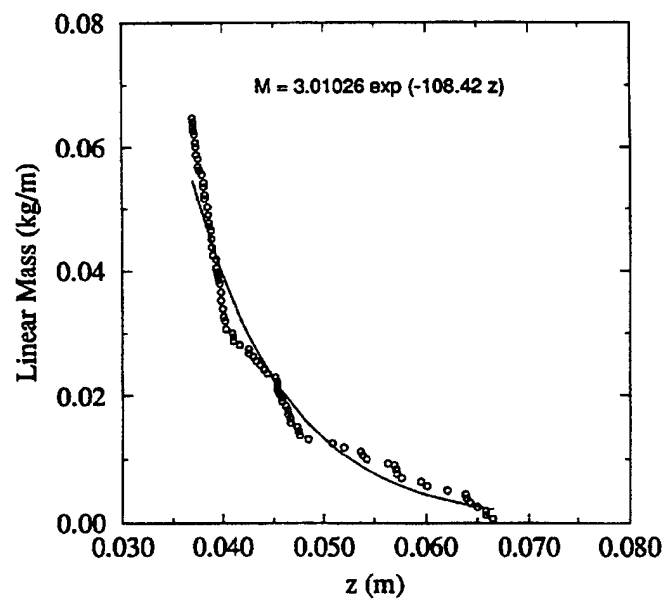


Figure 8. Cumulative jet mass versus position at 12 μ s.

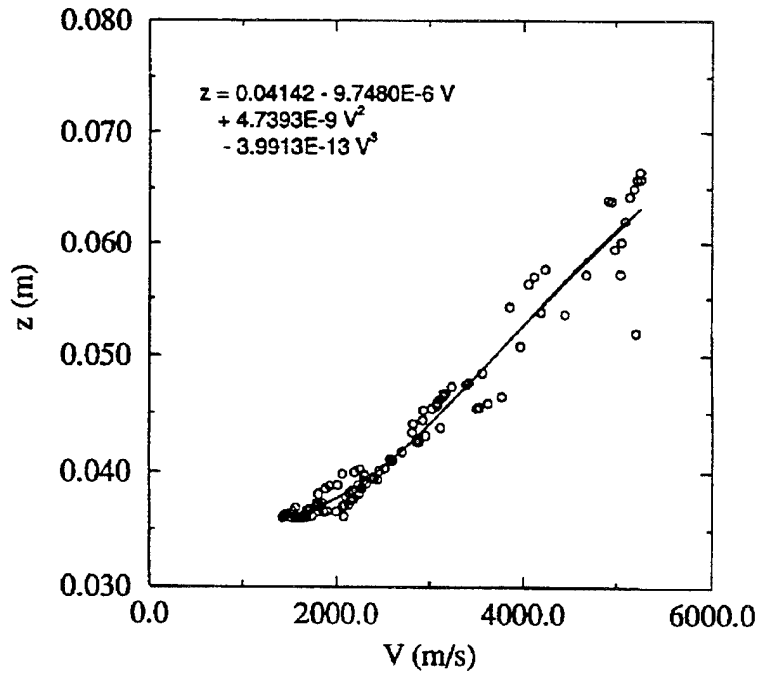


Figure 9. Axial velocity versus position at 12 μs .

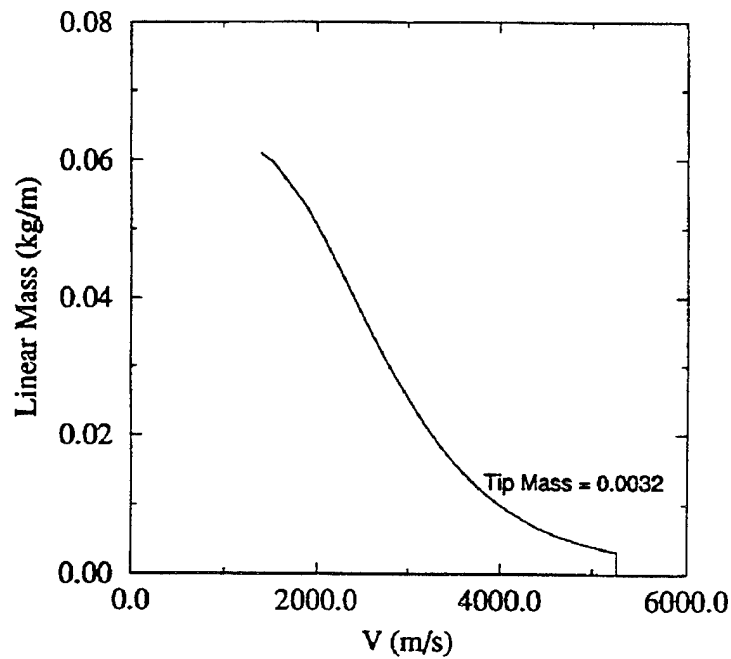


Figure 10. Cumulative mass versus velocity at 12 μs .

the two fits; thus, $M(v) = M(\bar{z}(v))$ (see Figure 10). The following fitting forms have been employed for this particular data set in question:

$$M(\bar{z}) = Ke^{-B\bar{z}} \quad (1)$$

$$\bar{z}(v) = C_0 + C_1v + C_2v^2 + C_3v^3 \quad , \quad (2)$$

where K, B and the C terms are fitting constants. Thus, cumulative mass is obtainable in terms of jet velocity, and its derivative also, given by

$$\frac{dM}{dv} = -KB \frac{d\bar{z}}{dv} e^{-B\bar{z}} \quad (3)$$

for the fitting forms proposed.

For a linear shaped charge jet of unit depth, density ρ , and half-thickness d , the derivative of the cumulative mass curve is described by

$$\frac{dM}{dz} = -2\rho d \quad . \quad (4)$$

If the cumulative mass distribution is known, and it is the jet half thickness to be determined, simple algebraic manipulation and the use of the chain rule provide that

$$d = \frac{-dM/dv}{2\rho dz/dv} \quad . \quad (5)$$

The cumulative mass derivative is given above in Equation 3, using parameters from the fits, while the position derivative will now be described.

The axial coordinate, \bar{z} , applies specifically at the fitting time of 12 μs . By assuming that the jet particles do not accelerate after the jet is formed (i.e., constant velocity jet particles), the axial coordinate of a jet particle at any time may be directly obtained from

$$z = \bar{z} + v(t - \bar{t}) \quad . \quad (6)$$

With this equation, the derivative of position versus velocity is simply

$$\frac{dz}{dv} = \frac{d\bar{z}}{dv} + (t - \bar{t}) \quad . \quad (7)$$

Again, the \bar{z} derivative is obtainable from the data fit in Equation 2. Combining and substituting these terms gives the fit to the jet half thickness as

$$d(v, t) = \frac{KB(d\bar{z} / dv)e^{-B\bar{z}}}{2\rho(d\bar{z} / dv + t - \bar{t})} \quad . \quad (8)$$

For the jet tip of given mass, M_0 , a half diameter $d_0 = d(v_0)$ is assumed and length L_0 is computed via

$$L_0 = \frac{M_0}{2\rho d_0} \quad . \quad (9)$$

The geometric fit, using the current technique, is shown at 12 μ s (Figure 11). The fit is good from the jet tip back to the location $\bar{z} = 0.041$ m, corresponding to a jet velocity of approximately 2.5 km/s. It is believed that the relative jet thickness is large enough at this jet location so that the “effective” tail of the jet will lie ahead of this location. Thus, the divergent fit behind this location should not affect the penetration capability of the jet. Figure 12 depicts the jet fit, backed up in time to 8 μ s, and compares it to the hydrocode results at that time. As can be seen, the fit to the jet contour, and thus the technique for backing up the idealization in time, properly accounts for mass continuity over time. Figure 13 provides a not-to-scale geometrical representation of the idealized jet contour impinging upon the monolithic target at 7.2 μ s in time. The target location was chosen 12.7 mm (0.5 in) from the original Mk-7 liner base, which is a representative standoff at which the device is employed. Again, Figure 5b shows the computational grid in a closeup at the jet/target interface, depicting the grid resolution. In the current configuration, the jet penetration simulation has 26,444 elements and 13,855 nodes (Figure 5a).

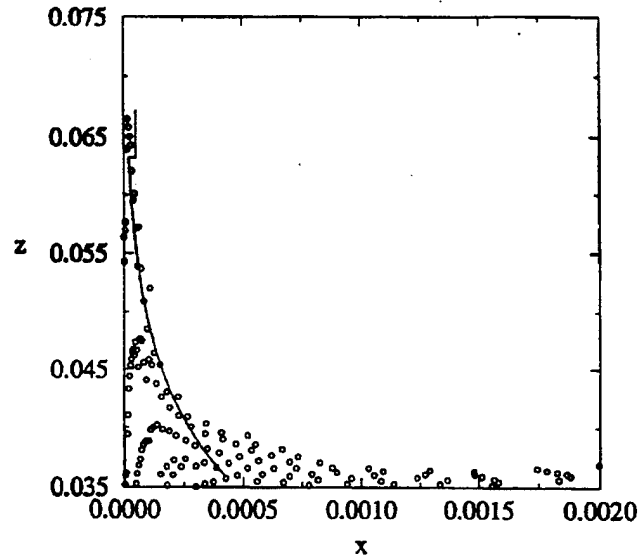


Figure 11. Nodal mass points in simulated jet compared to fit using (v,z) and dM/dz data at 12 μ s (length dimensions in meters, not to scale).

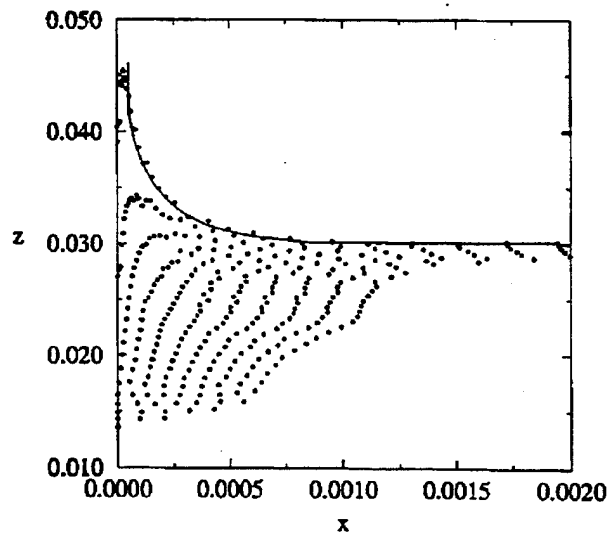


Figure 12. Nodal mass points in simulated jet compared to fit using (v,z) and dM/dz data interpolated back to 8 μ s (length dimensions in meters, not to scale).

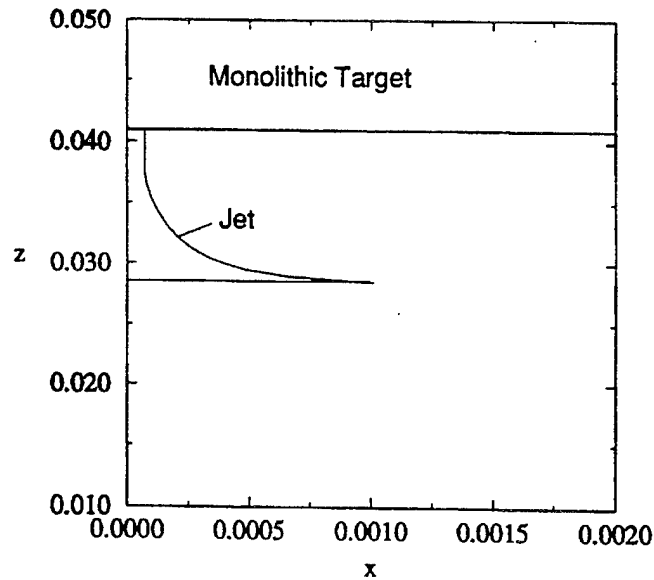


Figure 13. Idealized jet contour impinging upon monolithic target at 7.2 μ s (length dimensions in meters, not to scale).

2.2 LSC Jet Penetration. Having fully characterized the LSC jet geometry and initial velocity, we proceed to solve the *penetration* problem. The complete LSC penetration simulation is illustrated at 4 μ s time intervals in Appendix B. Although the RHA plate used in the experiment was 2-in (50.8 mm)-thick, we chose to reduce the size of the total problem by modeling a plate of only half the actual plate thickness (i.e., a 1-in [25.4 mm]-thick plate). We felt justified in using a reduced plate thickness in our simulation since the documented cutting depth for the Mk-7 Mod 8 LSC is only 18 mm (0.70 in) (see Department of the Navy EODB/Department of the Army TM/U.S. Air Force TO 60A-2-1-51 1992). The EPIC92 input deck for the LSC jet penetration problem can also be found in Appendix B. The penetration depth of the jet is 24.5 mm when measured from the front plane of the target. If one accounts for target bulge as unpenetrated material, then penetrated thickness = original thickness - unpenetrated thickness = 25.4 mm - 2.5 mm = 22.9 mm.

3. EXPERIMENTS

3.1 Free Flight LSC Jet Tip Velocity (Makewire Circuit). The free flight velocity of the LSC was determined at ARL Range 17 by measuring the travel time of the jet as it consecutively severed three parallel double-lead wires, fastened to a plexiglas test fixture (Figure 14). As each wire is impinged by the electrically conductive jet, a circuit is completed sending a signal to an oscilloscope from which the travel time and velocity of the jet can be deduced. A breakwire circuit was not used because it might interact with the electrically conductive jet. A uniform standoff distance is assured by elevating the short legs of the liner with wooden spacers. The charge is detonated at one end by hotwire initiation

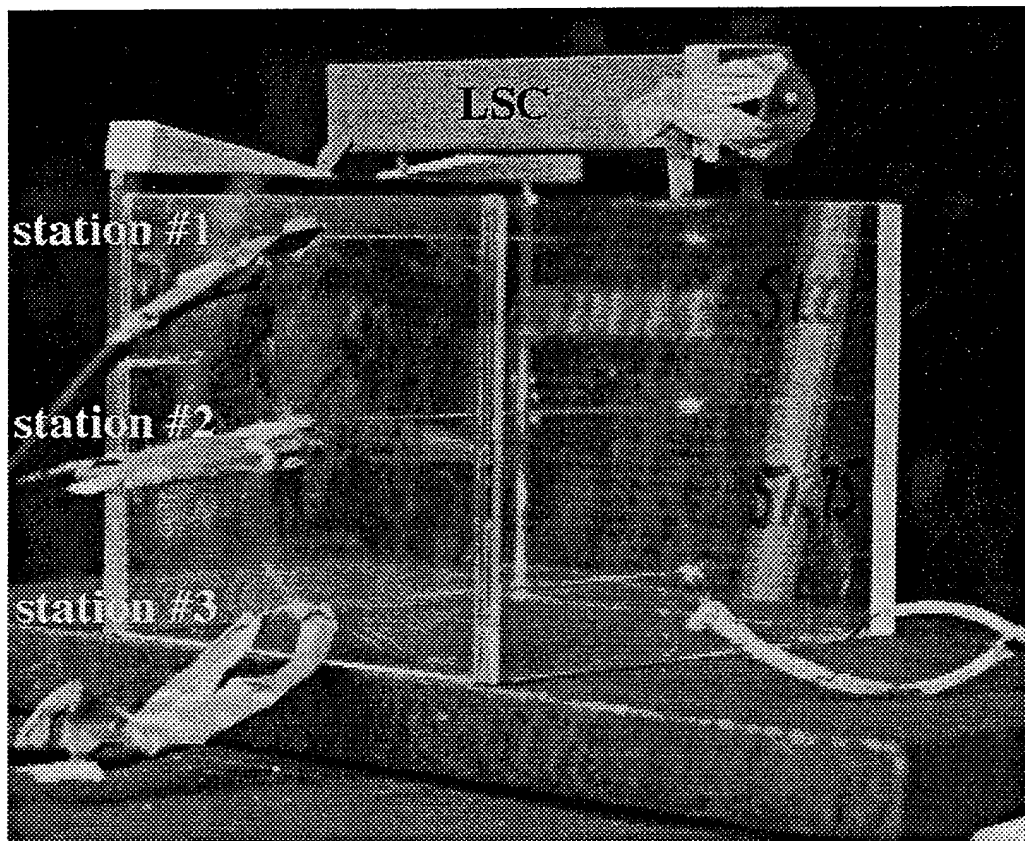


Figure 14. Plexiglas makewire test fixture for free flight velocity measurement
(RHA witness plate is 1-in [25.4 mm]-thick).

of two layers of C-6 Detasheet explosive that are press fit onto the Comp-B; each layer of Detasheet is about 6-mm thick. Detasheet is manufactured by Dupont and is composed of 68% PETN, 28% acetyl tributyl citrate, and 8 % nitrocellulose (Asay et al. 1994). The test fixture stands on a 1-in (25.4 mm)-thick rectangular witness plate composed of RHA. As the jet tip cuts through each double-lead, the wires are bridged, which completes the electrical *makewire* circuit. When the circuit is completed, a 67.5-volt signal is simultaneously discharged from a battery to a Nicolet model 2090 oscilloscope. Prior to detonating the charge, the oscilloscopes are triggered and begin to collect data at a sampling rate of 50 ns/pt. Two separate experiments were conducted to estimate the free-flight velocity of the jet. For Shot #1, the jet tip severs the first wire at station 1 (Figure 13), and oscilloscopes #1 and #3 record signals after 23.2 μ s and 22.8 μ s respectively (Figure 14). The jet tip severs the second wire at station 2, and oscilloscopes #1 and #2 record signals after 38.0 μ s respectively. Finally, the jet tip severs the third wire

at station 3, and oscilloscopes # 2 and #3 record signals at 52.95 μs and 52.5 μs respectively. A similar sequence of events occurs for Shot # 2 but with slightly different interstation distances and travel times (Figure 15). Jet velocities are deduced from these data. The test results are compiled in Table 1. The free flight jet tip velocity is found to average 3.52 ± 0.10 km/sec and is relatively constant over a total flight distance of about 4 in (100 mm).

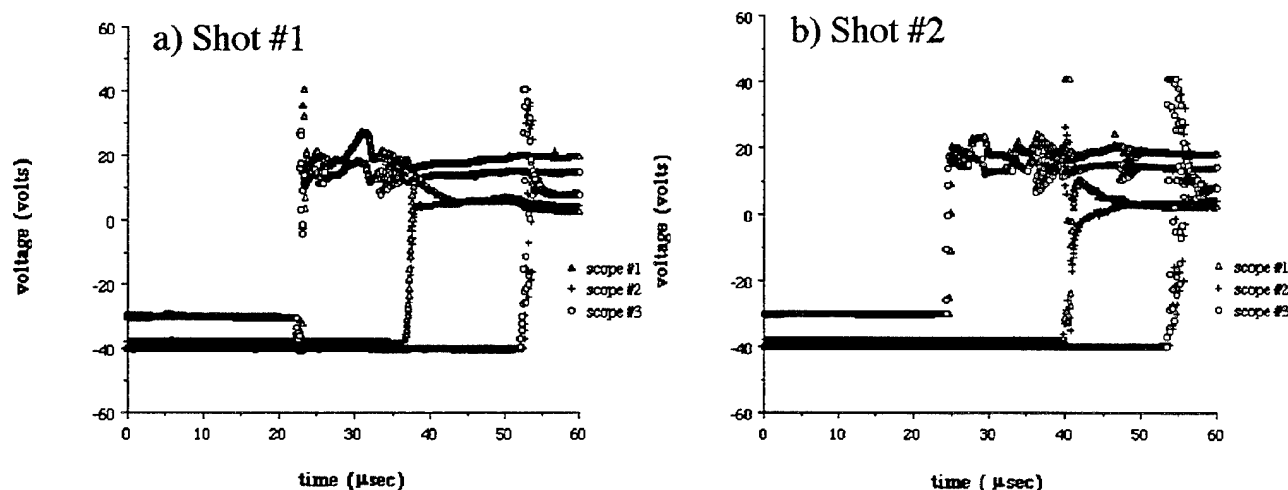


Figure 15. Oscilloscope traces.

Table 1. Free Flight Velocity Measurements

Shot #	Stations	Interstation Distance (mm)	Travel Time (μs)	Jet Tip Velocity (km/s)
1	1 to 2	51.0	14.8	3.445
	2 to 3	51.75	14.95	3.46
	1 to 3	102.75	29.7	3.46
2	1 to 2	51.5	14.9	3.456
	2 to 3	51.5	13.9	3.7
	1 to 3	103.0	28.85	3.57
average:				3.52

3.2 Free Flight LSC Jet Tip Velocity (Orthogonal X-rays). The free flight velocity of the LSC was also determined at ARL Range 16 by an orthogonal x-ray measurement method so that a direct comparison could be made to the electrical makewire measurement method. The experimental test configuration is illustrated in Figure 16. The LSC is shown suspended by two nylon ropes with radiographic film cassettes oriented at right angles relative to the charge. Our attempts to obtain orthogonal radiographs of the jet as it formed were unsuccessful because the radiographic film cassettes were damaged by laterally projected fragments of the steel liner (Figure 17). In one test, such a fragment remained relatively intact and created a rectangular imprint on the interior wall of the test facility (Figure 18). A shield was then constructed by cutting a rectangular hole in a 2-in (50.8 mm)-thick RHA plate. The LSC was suspended within the hole in an attempt to prevent the side fragments of the liner from puncturing the photographic plate; this test configuration was also relatively ineffectual in preventing photographic plate damage, so jet tip velocity had to be estimated from a single radiograph (Figure 19). Knowing the distance from the base of the LSC to the tip of the jet, one can determine the jet tip velocity from information about the test system time delays. Test system time delays were estimated at 3 μ s for predetonation electrical delay, 3 μ s for Detasheet burn delay, 3 μ s to 6 μ s for Comp-B burn delay, and 5 μ s for jet formation delay. The jet formation delay is the time required for the jet to emerge from the base of the LSC at a given cross section, once the detonation wave reaches that cross section, and is included in the delay times since all distance measures were made from the base of the LSC. The jet formation delay was determined from the hydrocode computations (see Appendix A).

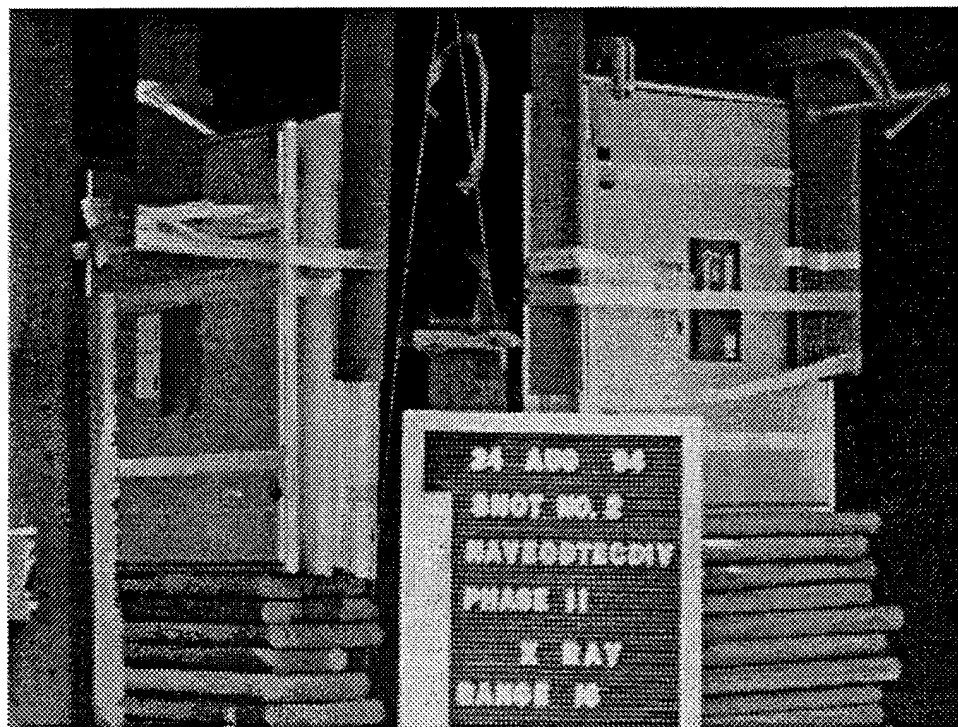


Figure 16. Test configuration for free flight velocity measurement.



Figure17. Radiographic film cassette damaged by LSC liner fragment.

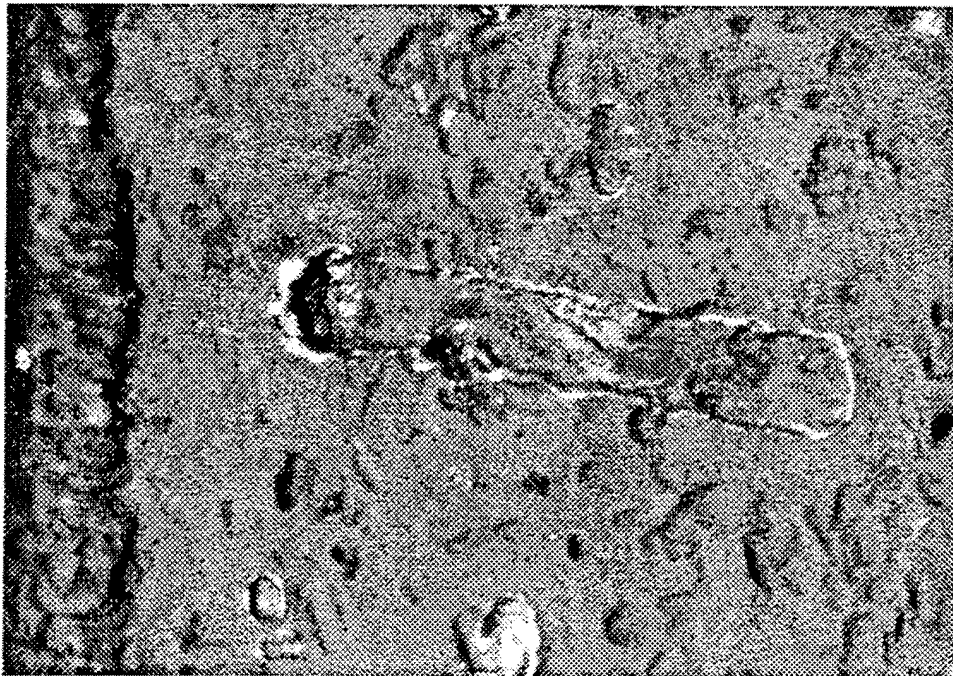


Figure 18. Liner imprint on wall of test facility

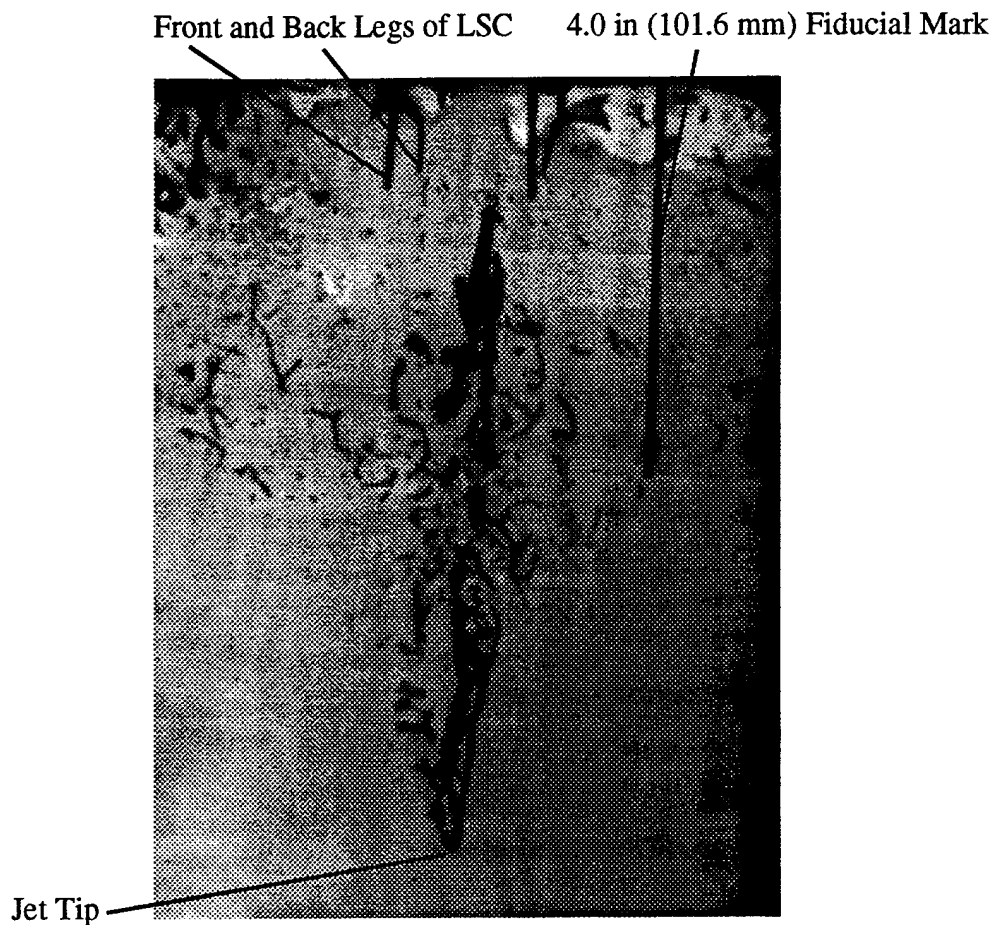


Figure 19. X-ray radiograph of LSC (axial view) at 73.5 μ s.

The total time delay thus ranges from 14 μ s to 17 μ s. The radiograph flash time occurred at 73.5 μ s so that the total travel time ranged from 56.5 μ s to 59.5 μ s. The distance traveled by the jet is estimated at 197.9 mm from the radiograph so that jet tip velocity is estimated to range from 3.3 km/s to 3.5 km/s.

3.3 LSC Jet Penetration Measurements. The penetration performance of the LSC into RHA plates that measure 450x200x51 mm is characterized using two test configurations. In the first test configuration (Figure 20a), the LSC has a nonuniform standoff distance in which the liner base makes an angle of about 8.6° with the surface of the RHA plate. In the second test configuration, shortening the long legs, and elevating the short legs of the LSC with wooden spacers (Figure 20b) creates a uniform standoff distance on the order of 12.7 mm. The Comp-B within the liner is detonated normal to its long axis by precursively detonating two, 5-mm thick Detasheet explosive wafers at one end of the charge; this same explosive initiation procedure was used in the free flight experiments. Figure 21 shows a plan view of the damaged RHA plate experiments from the nonuniform standoff test. A relatively straight narrow cut is seen, 10-mm wide at the center, and about 170-mm long. The cut in the RHA is

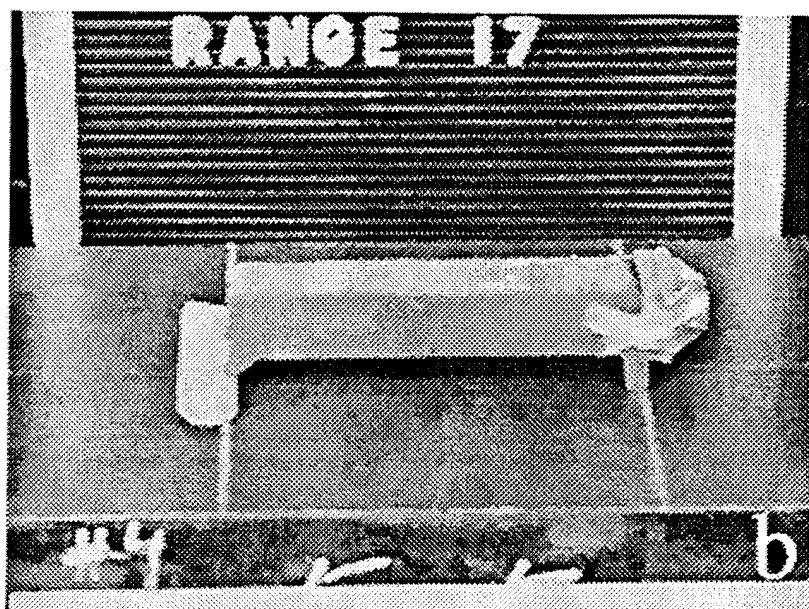
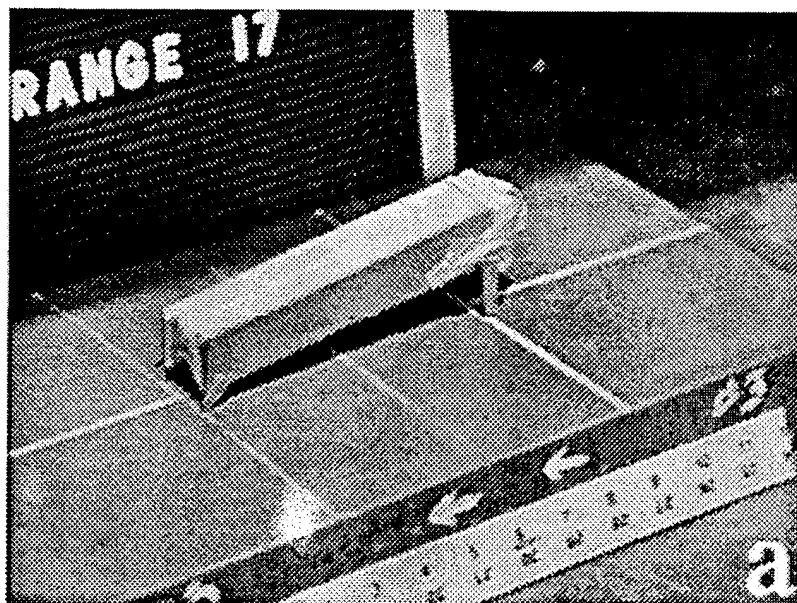


Figure 20. LSC test configurations, a) nonuniform, and b) uniform.

virtually the same in both the uniform and the nonuniform standoff test. A relatively straight narrow cut is seen, 10-mm wide at the center, and about 170-mm long. The cut in the RHA is virtually the same in both the uniform and nonuniform charge configurations. However, the jet penetrated to a depth of 18 mm in the nonuniform charge configuration, and to a depth of only 17 mm for the uniform charge configuration; the penetration measurements were made by sectioning the RHA plates normal to the long axis of symmetry of the cut, and then measuring the distance from the bottom surface of the plate to the

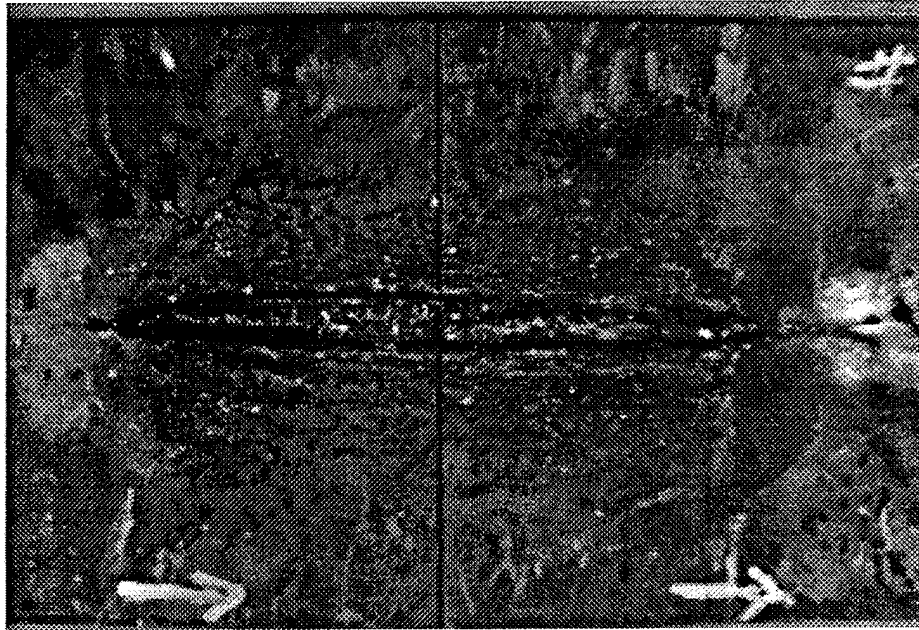


Figure 21. Damaged RHA plate (plan view) for nonuniform standoff test.
Detonation wave traveled from left to right (indicated by arrows).

bottom of the cut and subtracting this distance from the initial plate thickness of 51 mm. Figure 22a shows a closeup view of the sectioned plate for the nonuniform standoff test; residual liner material is visible at the base of each of the cuts. An experiment was also conducted using a 25.4-mm-thick mild steel target. The cut is wider (15 mm) in the mild steel plate than in the RHA plate. In addition, the jet nearly penetrated through the mild steel plate and caused it to bulge and crack longitudinally along the lower surface (Figure 22b). The 152-mm-long LSC creates a cut in the mild steel that is about the same length as the cut in the RHA (i.e., about 170 mm).

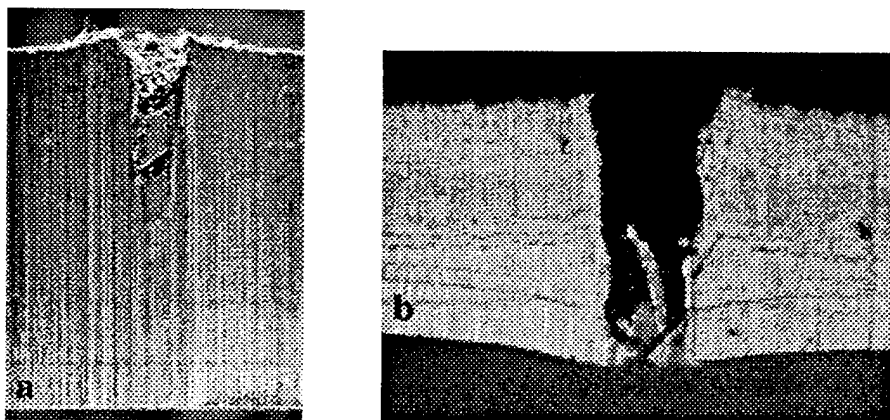


Figure 22. Cross sections through a) RHA plate 2-in (50.8 mm)-thick, and b) Mild steel plate 1-in (25.4 mm)-thick.

4. COMPARISON OF COMPUTATIONS AND EXPERIMENTS

The hydrocode simulations predict a jet tip free flight velocity of about 5.2 km/s. However, observed jet tip free flight velocities of the LSC range from 3.3 to 3.5 km/s as determined from flash radiography, and 3.52 km/s using a special makewire circuit test fixture. Furthermore, the simulations predict a greater penetration depth of 22.9 mm, whereas penetration depths into two rectangular, 2-in-thick RHA plates measure about 17 and 18 mm respectively. The greater predicted plate penetration depth is expected since the predicted jet tip velocities were greater than those observed. We decided to rerun the jet *formation* problem by varying certain input parameters in an attempt to reduce the predicted jet tip velocity. The following additional simulations were conducted, yet all were relatively unsuccessful in significantly decreasing the jet velocity; a synopsis of these results appears as snapshots of the jet velocity versus axial position at 4 μ s and 12 μ s for each of the following conditions:

- (1) Original liner mesh density with element erosion = 0.0 (Figure 23a).
- (2) A mesh density increase through the liner thickness by a factor of two (dense mesh) (Figure 23b).
- (3) A dense mesh with a flat inner liner mesh geometry (Figure 23c).
- (4) A modified dense mesh with a flat inner liner mesh geometry and apex angle = 82° (Figure 23d).

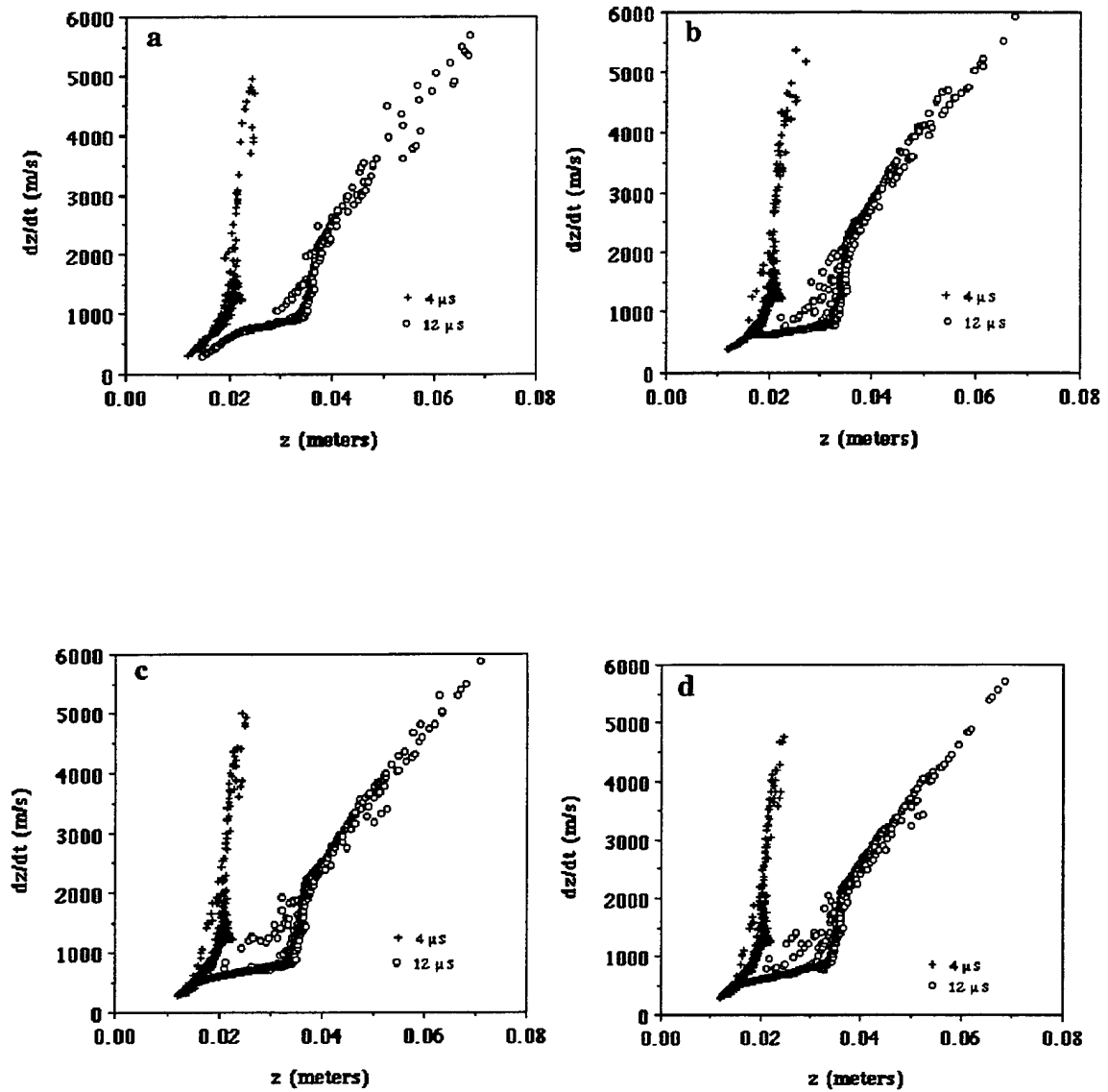


Figure 23. Jet velocity versus axial position at $4 \mu s$ and $12 \mu s$. a) Original liner with element erosion = 0.0, b) Dense mesh, c) Dense mesh with flat liner, d) Modified dense mesh, flat inner liner with apex angle = 82° .

Magnified views in the vicinity of the liner apex of both the dense mesh, and the modified dense mesh at 0 μ s and 4 μ s appear in Figures 24 and 25, respectively. The effect of increasing the finite element density in the liner is to increase the jet velocity (e.g., compare maximum jet tip velocity in Figures 23b, c, and d with that in Figure 23a) rather than to decrease jet velocity; similar spatial resolution effects are reported in Walters and Zukas (1989) in some EPIC lead hemispherical liner computations. The Walters and Zukas (1989) computations predict jet tip velocities to within 5.3% of the experimentally measured velocities, yet our computations overpredict the jet tip velocity by 33%. The good agreement between the predicted and experimental results of Walters and Zukas (1989) could be a result of the smoothly varying surface geometry of the hemispherical liner. Altering the LSC liner geometry from v-notch to flat, however, only slightly reduced the maximum jet tip velocity (e.g., compare maximum jet tip velocity in Figure 23b with that in Figure 23c).

We also attempted to rezone the liner at 2 μ s, since the triangular elements in the jet tip become highly distorted and may artificially affect mesh stiffness and hence nodal displacements and velocities. We were unsuccessful in using the EPIC92 rezoner. We also hypothesized that in the fully 3-D problem, a pressure-release wave might closely follow the detonation wave as it travels along the axis of the LSC; the pressure-release wave would have the effect of reducing the total momentum transferred to the liner and thus decrease the jet tip velocity. The pressure-release phenomenon might affect the computational results for our 2-D plane strain model, so several simulations were also conducted, whereby the explosive material was dropped from the analysis at 4 μ s, 6 μ s, and 8 μ s (effectively modeling the pressure release phenomenon); dropping the explosive material at these times did not appreciably decrease the jet tip velocities. Finally, we reran the problem using the EPIC94 version of the hydrocode which has an automatic mesh rezone feature. This attempt provided successful computations to 4 μ s with the original mesh density. The jet tip velocity was reduced from 4.7 km/s at 4 μ s in the original problem (see Figure 23a) to 3.8 km/s in the rezoned problem at 4 μ s (Figure 26b). We were unable to obtain results beyond 4 μ s because of numerical instabilities associated with requiring a vanishingly small integration time increment as a result of an equation-of-state instability. It is interesting to note that these numerical instabilities were not encountered when the problem was initially run without rezoning. Unstable numerical behavior was also encountered when we doubled the mesh density and used the EPIC94 automatic rezoner.

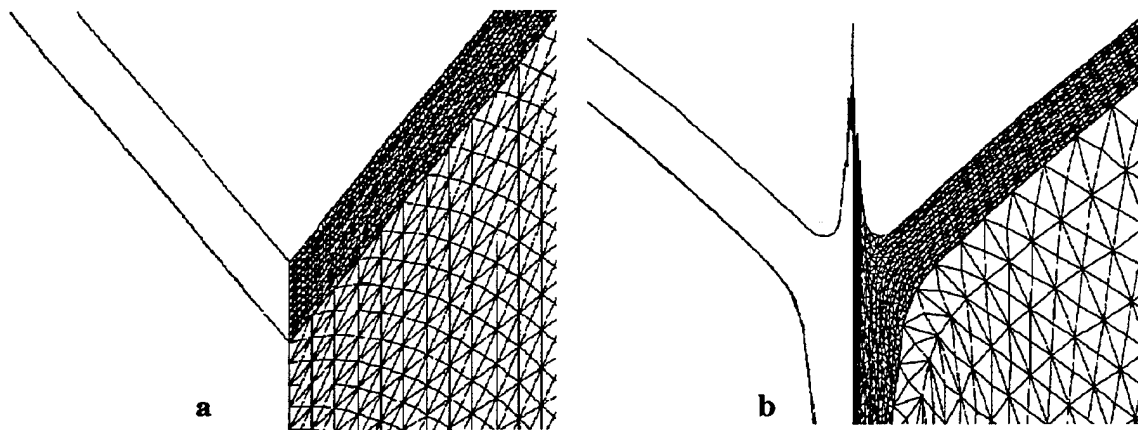


Figure 24. Computational mesh (magnified) for the dense liner in the vicinity of the liner apex at: a) $t = 0 \mu s$, and b) $t = 4 \mu s$.

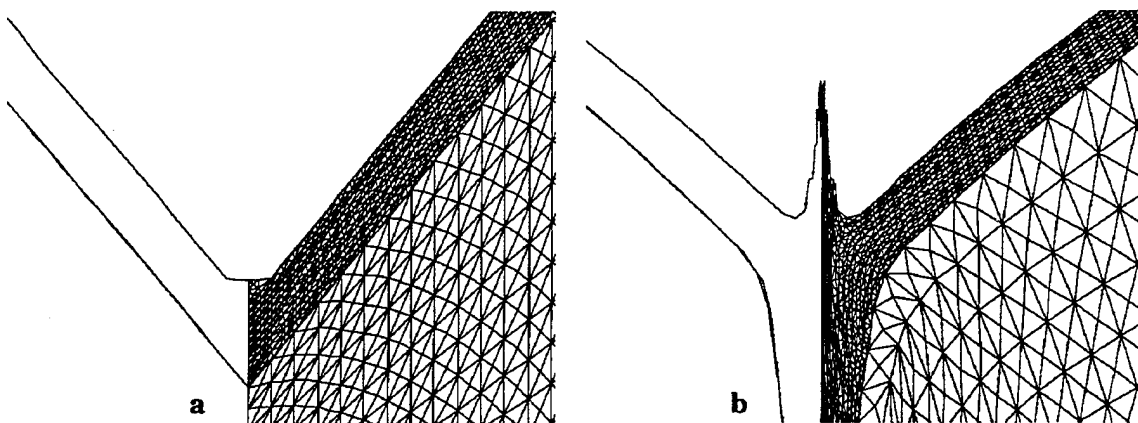


Figure 25. Computational mesh (magnified) for the modified dense mesh in the vicinity of the liner apex at: a) $t = 0 \mu s$, and b) $t = 4 \mu s$.

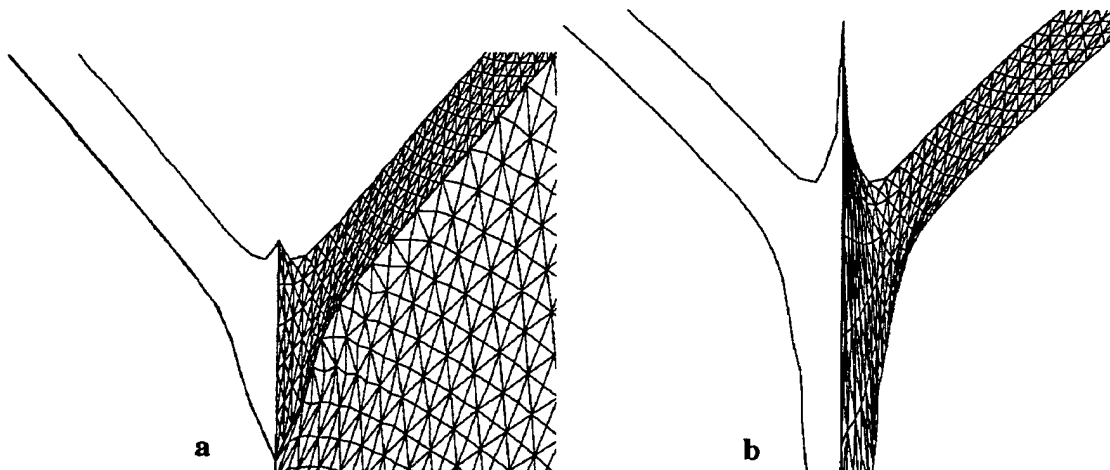


Figure 26. Computational mesh (magnified) rezoned at: a) $t = 2 \mu s$, and b) $t = 4 \mu s$.

5. CONCLUSIONS

(1) Lagrangian hydrocode computations in 2-D plane strain using EPIC92 predict an early time jet tip velocity of 5.2 km/s at 12 μ s for the Mk-7 Mod 8 demolition charge; this result greatly overpredicts the observed later time jet tip free flight velocities which range from 3.3 to 3.5 km/s at nearly 60 μ s using flash radiography, and 3.52 km/s averaged from 20 μ s to 60 μ s using an electrical makewire circuit.

(2) Jet tip velocity was not constant in the simulation, rising from 4.7 km/s at 4 μ s to 5.2 km/s at 12 μ s. After the jet has formed, such accelerations are nonphysical, based upon our understanding of the jet formation process, and likely result from the overly stiff nature of the constant strain triangles used to simulate the jet formation process.

(3) Parametric attempts to reduce the jet tip velocity prediction by: a) eliminating jet erosion (i.e., setting the element erosion feature = 0.0), b) doubling liner mesh density, c) flattening the liner apex angle, and d) increasing the liner apex angle from 80° to 82°, were unsuccessful.

(4) Use of the automatic rezone feature in the EPIC94 version of the hydrocode resulted in a reduction of the jet tip velocity from 4.7 km/s to 3.8 km/s at 4 μ s in the coarse mesh. The computations thus overpredict the observed jet tip velocity by 8 % if one assumes a constant velocity jet. Computations beyond 4 μ s were not possible due to numerical instabilities associated with requiring a vanishingly small integration time increment resulting from an equation-of-state instability. This behavior was also observed in the denser mesh. We were unsuccessful in utilizing the *manual* EPIC92 rezoner.

(5) Penetration depths into two rectangular, 2-in (50.8 mm)-thick RHA plates measured 17 and 18 mm respectively, whereas the hydrocode simulation predicted a greater penetration depth of 22.9 mm. The overprediction in the computed penetration depth is expected since jet tip velocities were also overpredicted by the hydrocode. The work attests to the importance of conducting experiments in order to verify baseline hydrocode simulations.

6. REFERENCES

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APPENDIX A:

SHAPED CHARGE JET FORMATION
INPUT DECK AND COMPUTATIONAL RESULTS

INTENTIONALLY LEFT BLANK.

```

3      1 NEOD Linear Shaped Charge - S. Segletes & George Gazonas - NOV 1993
$
$ This restart run will start at 0 us and continue to 12 microseconds
$
$$ main run data *****
$
$ cycl.ncpu.....time.....dtmax.....dtmin.....ssf.....tmax.....cpmax.....emax
   0   0 0000.0e-6      1.0   0.1e-9      0.80   12.0e-6   10800.00
$ tplt.drop..add.pres.push..hrg....vfract.....vnref...nabfact...sphdist/////////
   1   0   0   0   0   0
$ .sys.nplt.lplt.dplt.....dtsys.....tsys.....dtnode.....tnode.....dtdyn.....tdyn
   1   0      1.0e-6      0.0   0.25e-6      0.0
$ .....time....echeck....ncheck....rdamp.save.burn.yprt.ndat.slpr.proj..pat.rzne
  02.0E-06   1001.0      999      0.0   3   0   1  500   2   0   0   0
  04.0E-06   1001.0      999      0.0   3   0   1  500   2   0   0   0
  06.0E-06   1001.0      999      0.0   3   0   1  500   2   0   0   0
  08.0E-06   1001.0      999      0.0   3   0   1  500   2   0   0   0
  10.0E-06   1001.0      999      0.0   3   0   1  500   2   0   0   0
  999.0E-06   1001.0      999      0.0   3   0   1  500   2   0   0   0

$$ preprocessor data *****
$      Target is: UNCLASSIFIED, Linear Shaped Charge Detonation
$      Mk-7 is:
$          - Mild Steel Liner ASTM-A569
$          - Explosive C-4
$
$ type.case.....problem description.....]
   1   1 NEOD TARGET - S. Segletes & George Gazonas - NOV 1993
$ geom.prnt.save.nslid.nmas.nrst.nrig.nchk.load.nzonPCrtz.splt..dp3.unit/////..per
   5   1   3   2   0   1   0   0   0   0   0 1100   0   0   1   0
$ material data
$ solids from library
$ matl....0..dam.fail.dfrc.efal.SOLIDS FROM LIBRARY
   6   0   1   0      999. 1006 Steel (Mild Steel Simulant)
$ MATL   0   DAM FAIL      EFAL solids
  43   0   1   0      999. JWL Comp B (C-4 Simulant)
      $ end of material
$/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/
$ projectile nodes (Liner/Case)
$ .x/rscale....yscale....zscale..x/rshift....zshift....rotate....slant.x/r0...z0
   0.0254   0.0254   0.0254   0.00000   0.00   000.0   0.0   0   0
$ Rod nodes
$ ...2..nor..nir.npln..rad...ax.cros.join...n1.ntop.....ztop.....zbot....expand
   2   6   1  41   2   2   1   0 5001   0   1.03755   .44167   1.
$ .....RT1.....RT2.....RT3.....RT4.....RT5.....RT6 (FOR rad=2)
   .4594   .467526   .47564   .483763   .49188   .500
$ .....RB1.....RB2.....RB3.....RB4.....RB5.....RB6 (FOR rad=2)
   .000   .000   .000   0.000   .000   .000
$ .....ZT1.....ZT2.....ZT3.....ZT4.....ZT5.....ZT6 (FOR ax=2)
   1.0716   1.064798   1.057986   1.051174   1.044362   1.03755
$ .....ZB1.....ZB2.....ZB3.....ZB4.....ZB5.....ZB6 (FOR ax=2)
   .5241   .507614   .491128   .474642   .458156   .44167
$ ...1.nnod..rtzxxxxxxxxxxxxxxxxxxxxxxxxxxxxx...n1..inc.....exp
   1   1 000      5447   0   1.

```



```

$...2.mat1...n1.diag.noer.nier.nlay.....shel.plac//////////.....thick
      2   43 7001   5   21   1   20       0   0
      $ end of projectile elements
$//////////
$ begin slide line data
$
$ slide #1
$ master: target (liner/case) inner surface
$ slave : projectile (explosive) surface
$.nmg..nmn..nsg..nsn..nsr.type.mbot..isr..it1..it2...ref vel.....erode..friction
      2   0   2   0   0   1 0000   0   1   0          999.
$.mlg..mng..inc
      6151 6001   -5          $ inside of case
$.mlg..mng..inc
      5006 5446   11          $ inside of liner
$.slg..sng..inc
      7001 7022   1          $ explosive next to liner
$.slg..sng..inc
      7065 7882   43          $ explosive next to case
$
$ slide #2
$ master: projectile (explosive) surface
$ slave : target (liner/case) inner surface
$.nmg..nmn..nsg..nsn..nsr.type.mbot..isr..it1..it2...ref vel.....erode..friction
      2   0   2   0   0   1 0000   0   1   0          999.
$.mlg..mng..inc
      7001 7022   1          $ explosive next to liner
$.mlg..mng..inc
      7065 7882   43          $ explosive next to case
$.slg..sng..inc
      6151 6001   -5          $ inside of case
$.slg..sng..inc
      5006 5446   11          $ inside of liner
$
$//////////
$ Restraints (Ties liner nodes to axis of symmetry)
      6   1 100
      5441 5446   1
$ detonation (By detonating at t=-1, all explosive will simultaneously
$ detonate at t=0, at the start of the simulation)
$.x/rdet.....ydet.....zdet.....tburn.shad.npnt
      0.0   0.0   0.0   -1.0
$ initial velocity data
$.px/rdot...py/tdot....pzdot...tx/rdot...ty/tdot.....tzdot.....dt1.vfld/////
      -000.00   0.0   0.0   0.0   0.0   0.0
$$ preprocessor data *****
$
$type.case.....problem description.....]
$   3   1 NEOD Linear Shaped Charge - S. Segletes & George Gazonas - NOV 1993
$
$$ main run data *****
$
$ cycl.ncpu.....time.....dtmax.....dtmin.....ssf.....tmax.....cpmax.....emax
      0   0 0000.0e-6   1.0   0.1e-9   0.80   20.0e-6 10800.00
$ tplt.drop..add.pres.push..hrg....vfract.....vnref...nabfact...sphdist//////////
      1   0   0   0   0   0

```

```

$.sys.nplt.lplt.dplt.....dtsys.....tsys....dtnode.....tnode.....dtdyn.....tdyn
  1      0                      1.0e-6      0.0    0.25e-6      0.0

```

```

$stype.case.....problem description.....]
  3      1 NEOD Linear Shaped Charge - S. Segletes & George Gazonas - NOV 1993

```

```

$
$ This restart run will start at 0 us and continue to 12 microseconds
$

```

```

$$ main run data *****

```

```

$scycl.ncpu.....time.....dtmax.....dtmin.....ssf.....tmax.....cpmax.....emax
  0      0 0000.0e-6      1.0    0.1e-9      0.80    12.0e-6    10800.00

```

```

$stplt.drop..add.pres.push..hrg....vfract.....vnref...nabfact...sphdist////////
  1      0      0      0      0      0

```

```

$.sys.nplt.lplt.dplt.....dtsys.....tsys....dtnode.....tnode.....dtdyn.....tdyn
  1      0                      1.0e-6      0.0    0.25e-6      0.0

```

```

$.....time....echeck....ncheck.....rdamp.save.burn.yprt.ndat.slpr.proj..pat.rzne
02.0E-06    1001.0      999      0.0    3    0    1  500    2    0    0    0
04.0E-06    1001.0      999      0.0    3    0    1  500    2    0    0    0
06.0E-06    1001.0      999      0.0    3    0    1  500    2    0    0    0
08.0E-06    1001.0      999      0.0    3    0    1  500    2    0    0    0
10.0E-06    1001.0      999      0.0    3    0    1  500    2    0    0    0
999.0E-06    1001.0      999      0.0    3    0    1  500    2    0    0    0

```

```

$stype.case.....problem description.....]
  3      1 NEOD Linear Shaped Charge - S. Segletes & George Gazonas - NOV 1993

```

```

$
$ This restart run will restart at 12 us and then drop the explosive and
$ casing at 12.1 microseconds, continuing on until 20 microseconds.
$

```

```

$$ main run data *****

```

```

$scycl.ncpu.....time.....dtmax.....dtmin.....ssf.....tmax.....cpmax.....emax
  0      0 0012.0e-6      1.0    0.1e-9      0.80    20.0e-6    10800.00

```

```

$stplt.drop..add.pres.push..hrg....vfract.....vnref...nabfact...sphdist////////
  1      1      0      0      0      0

```

```

$.sys.nplt.lplt.dplt.....dtsys.....tsys....dtnode.....tnode.....dtdyn.....tdyn
  1      0                      1.0e-6      0.0    0.25e-6      0.0

```

```

$....tdrop.nnod.nnab.nele.nslld.nrig.nchk.load.nzon.nplt.lplt**RYZ.nfal*****.per
0012.1e-6  446    0  800    0    0    0    0    0    0    0    0  100    20    0

```

```

$.ef1..ef2..ef3..ef4..ef5..ef6..ef7..ef8..ef9.ef10.ef11.ef12.ef13.ef14.ef15.ef16
  1      2      3      4      5      6      7      8      9    10    11    12    13    14    15    16

```

```

$ef17.ef18.ef19.ef20
  17    18    19    20

```

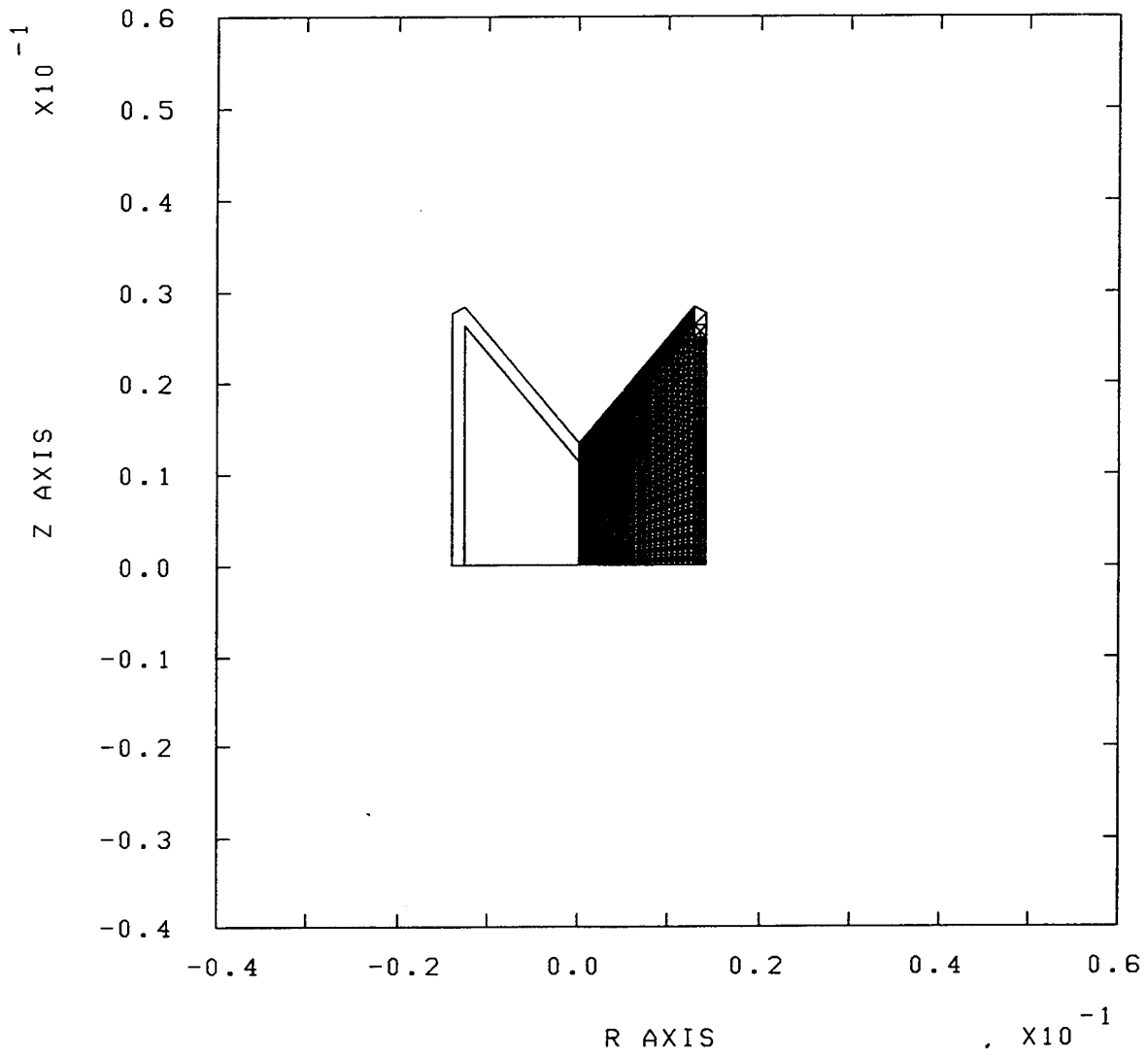
```

$.....time....echeck....ncheck.....rdamp.save.burn.yprt.ndat.slpr.proj..pat.rzne
14.0E-06    1001.0      999      0.0    3    0    1  500    2    0    0    0
16.0E-06    1001.0      999      0.0    3    0    1  500    2    0    0    0
18.0E-06    1001.0      999      0.0    3    0    1  500    2    0    0    0
21.0E-06    1001.0      999      0.0    3    0    1  500    2    0    0    0

```

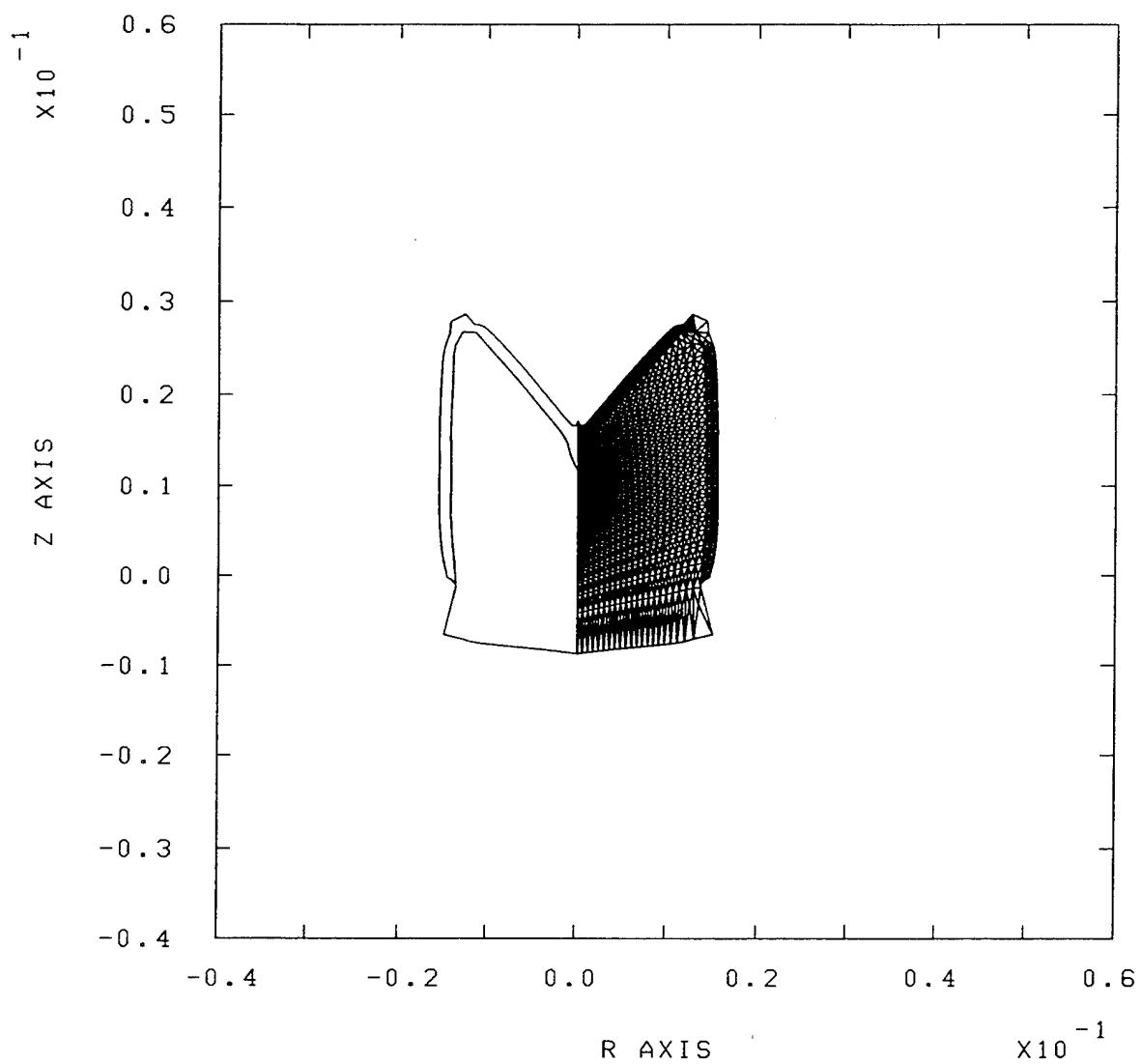
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2-D PLANE STRAIN GEOMETRY

Linear SC Formation ; CASE = 1; TIME = 0.00000000; CYCLE = 0



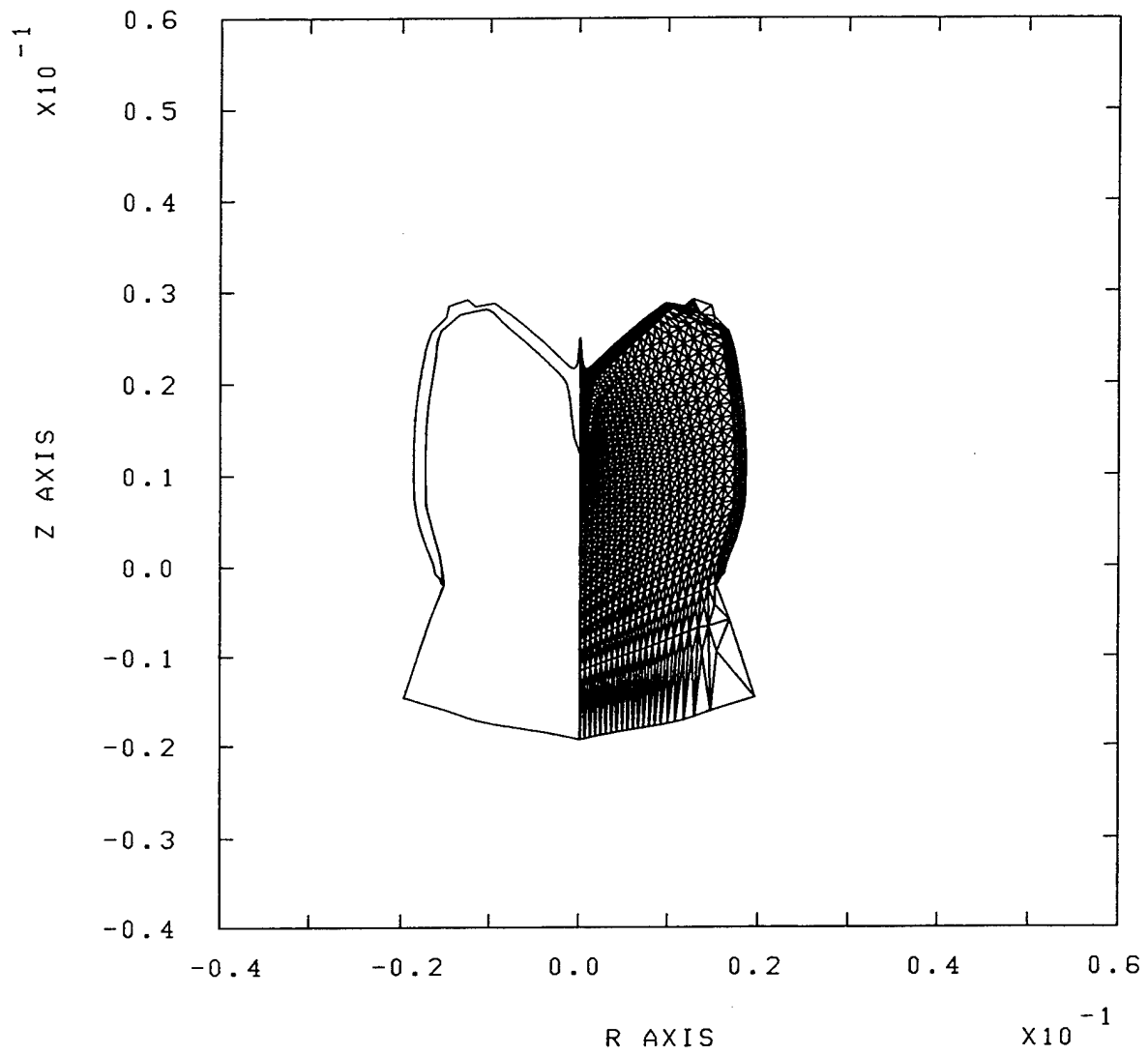
EPIC POST PROCESSOR, POST1 (1992-2) 16:00:17 09-Dec-93
2-D PLANE STRAIN GEOMETRY

Linear SC Formation ; CASE = 1; TIME = 0.00000200; CYCLE = 374



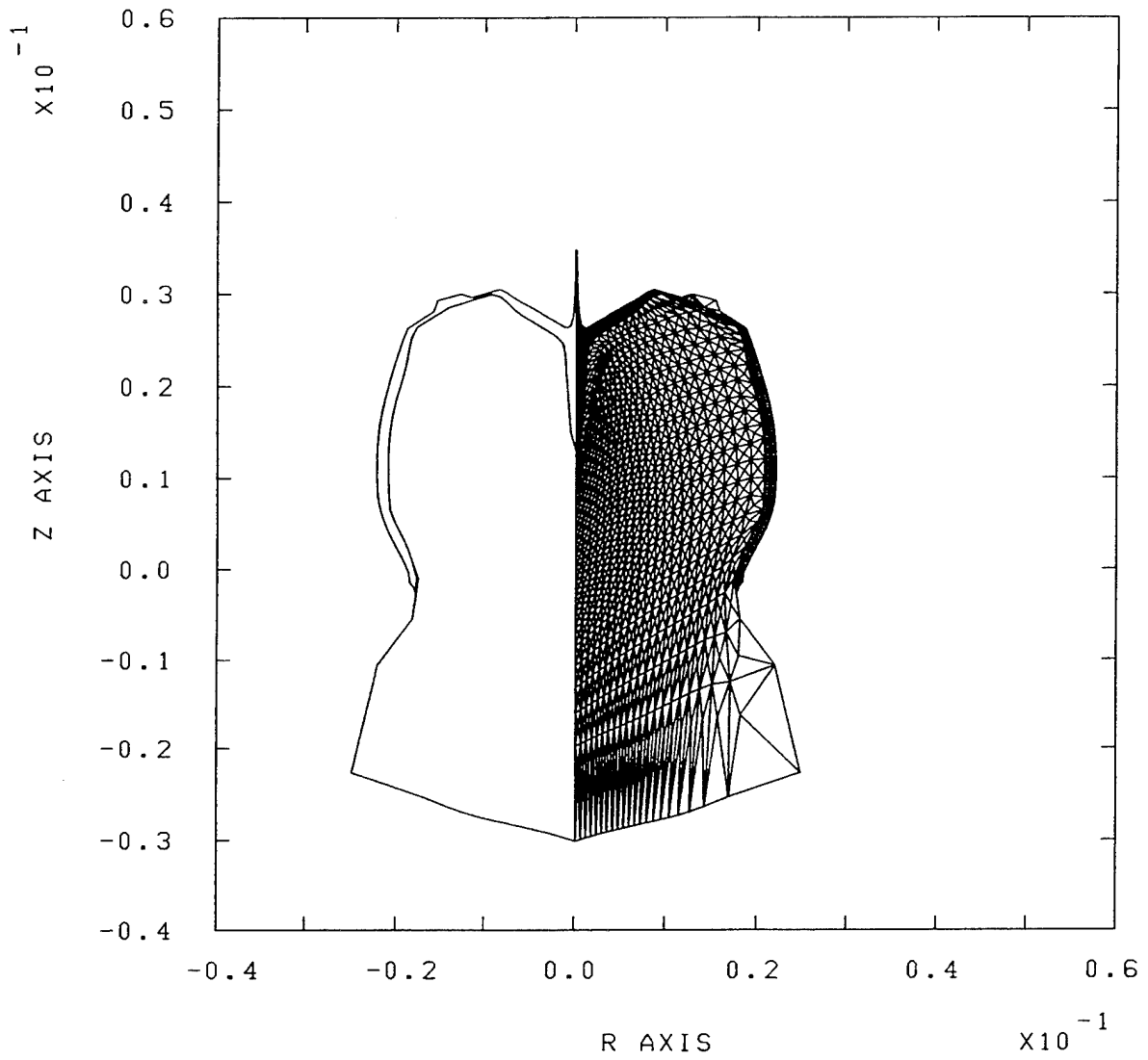
EPIC POST PROCESSOR, POST1 (1992-2) 16:00:21 09-Dec-93
2-D PLANE STRAIN GEOMETRY

Linear SC Formation ; CASE = 1; TIME = 0.00000400; CYCLE = 1937



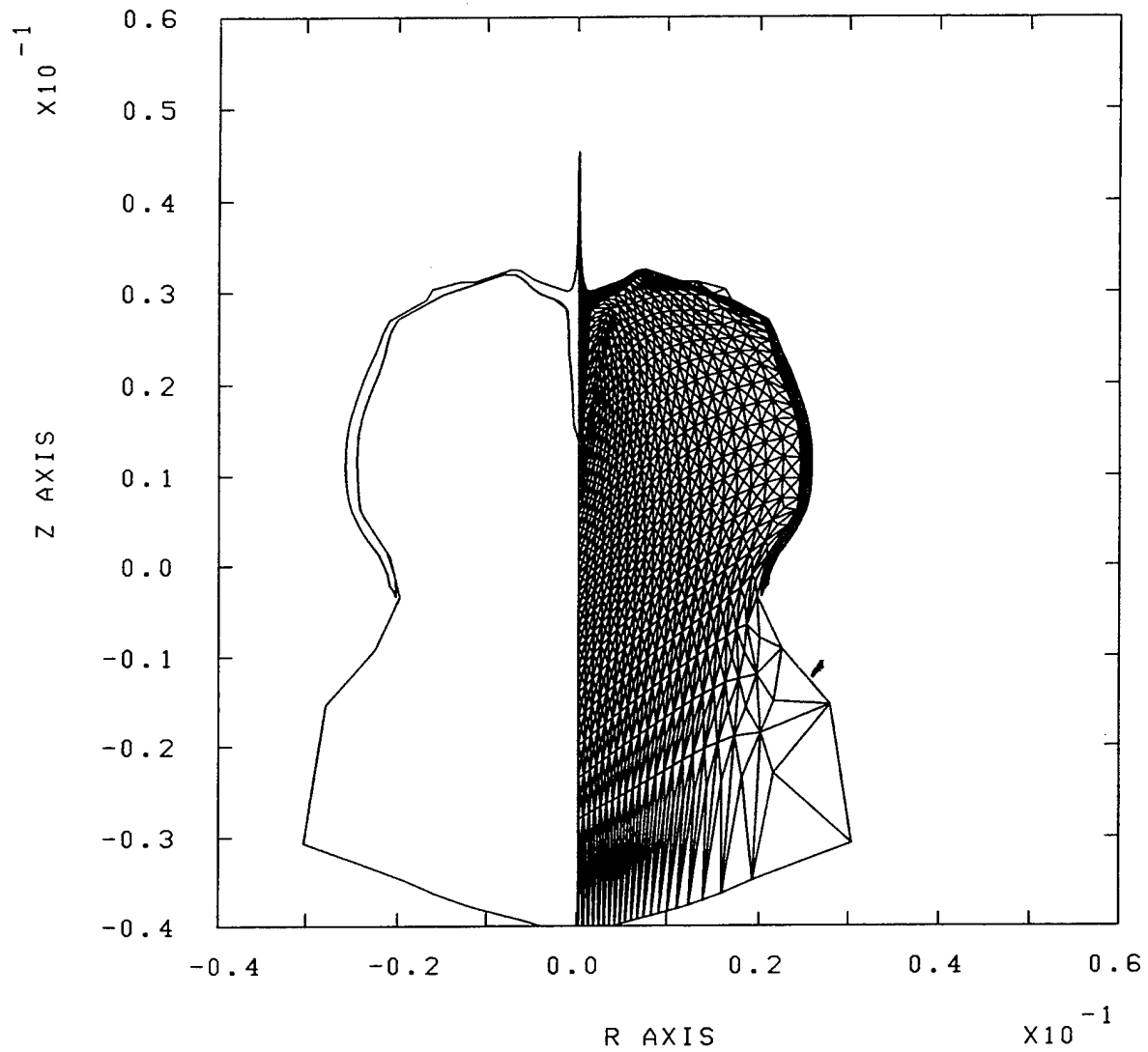
EPIC POST PROCESSOR, POST1 (1992-2) 16:00:25 09-Dec-93
2-D PLANE STRAIN GEOMETRY

Linear SC Formation ; CASE = 1; TIME =0.00000600; CYCLE = 5027



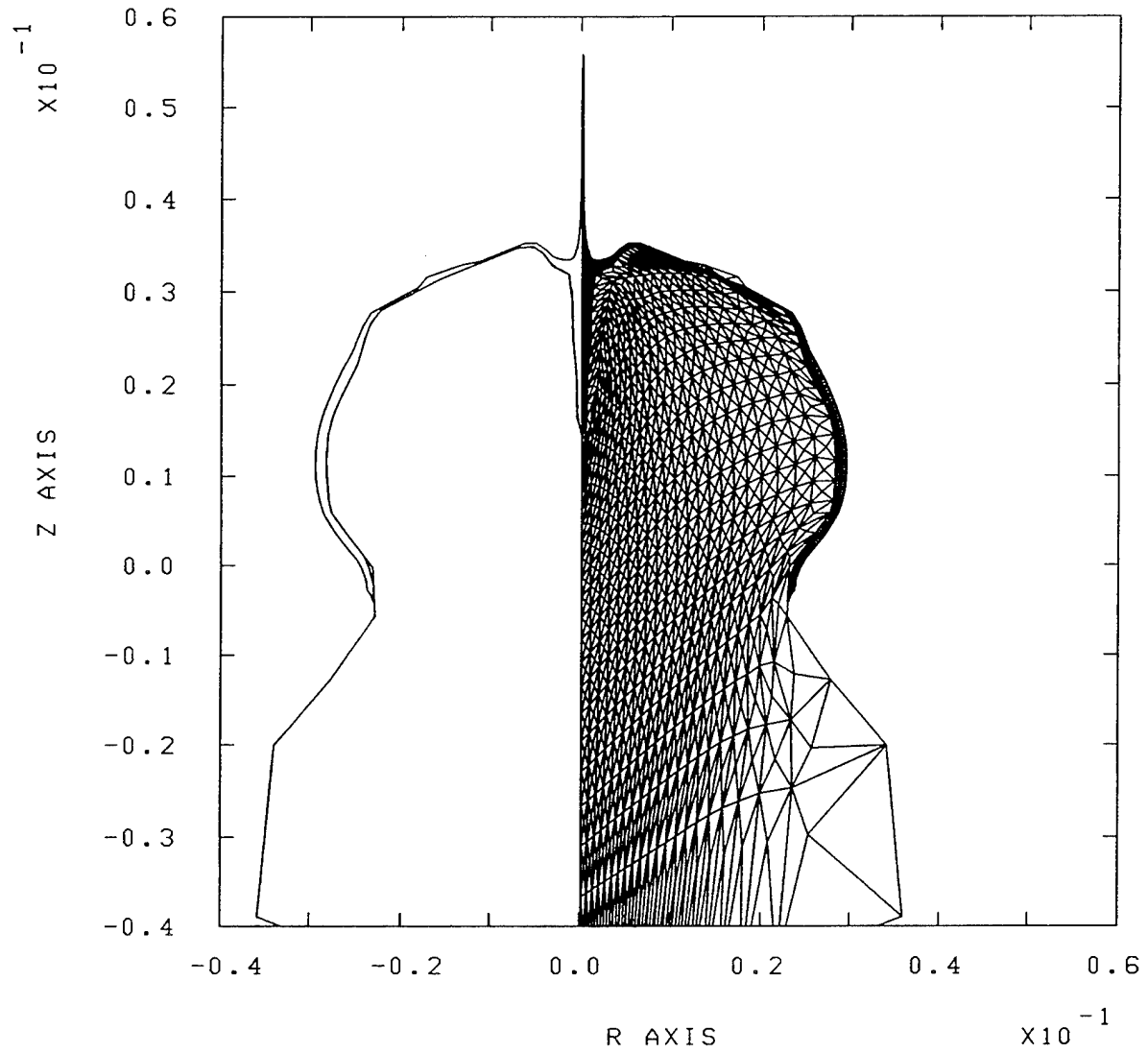
EPIC POST PROCESSOR, POST1 (1992-2) 16:00:29 09-Dec-93
2-D PLANE STRAIN GEOMETRY

Linear SC Formation ; CASE = 1; TIME = 0.00000800; CYCLE = 9690



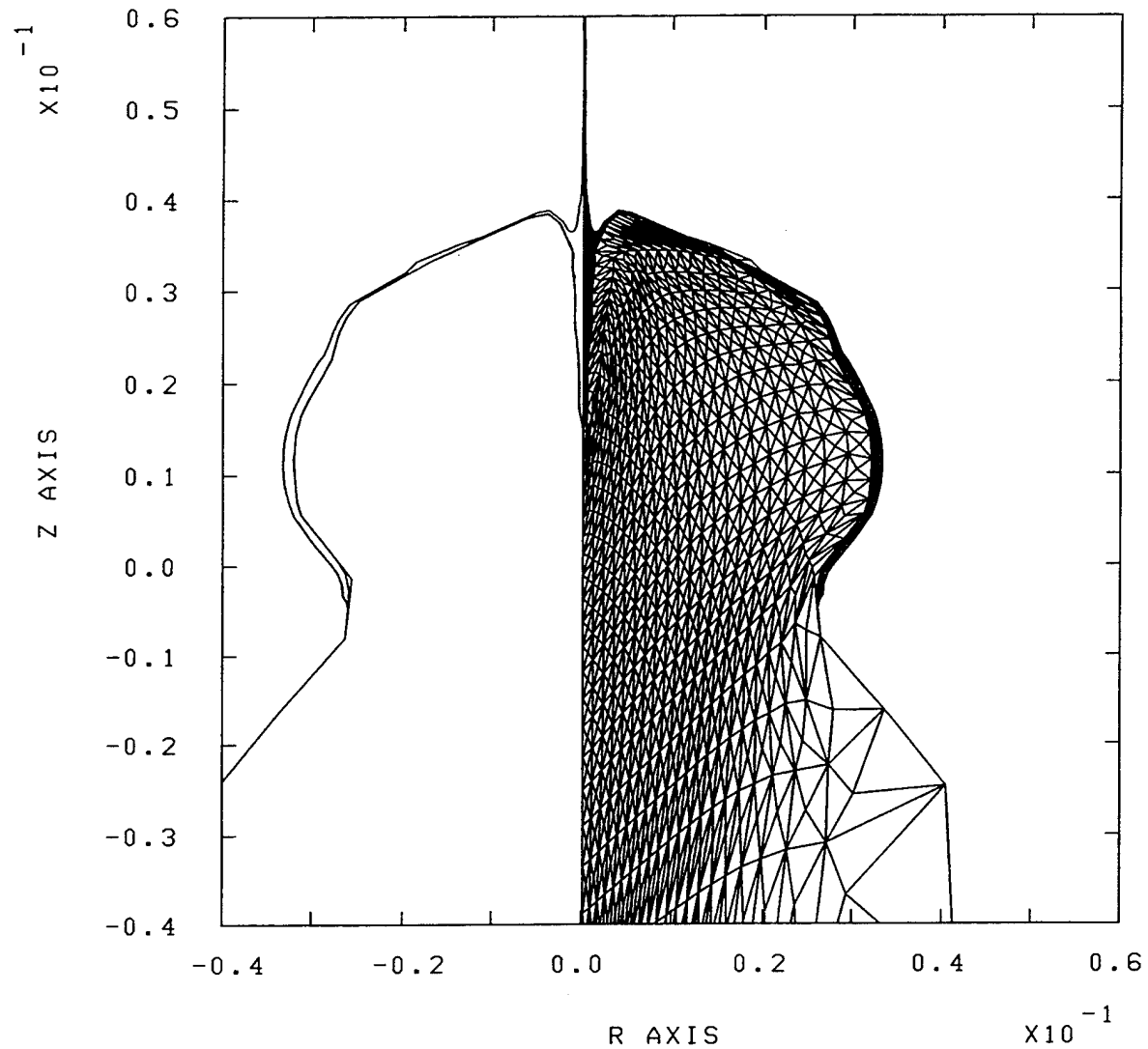
EPIC POST PROCESSOR, POST1 (1992-2) 16:00:32 09-Dec-93
2-D PLANE STRAIN GEOMETRY

Linear SC Formation ; CASE = 1; TIME =0.00001000; CYCLE = 15948



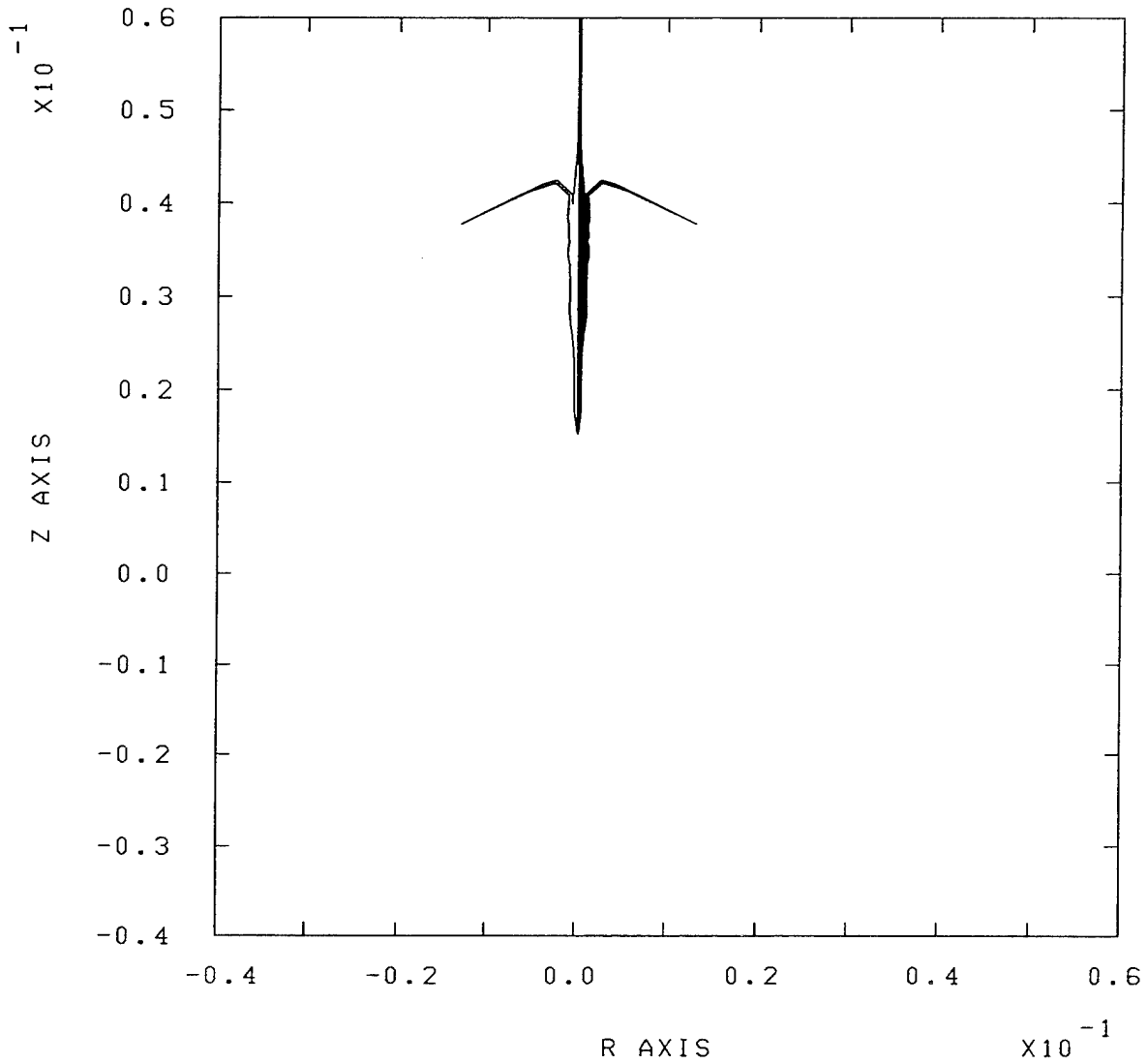
EPIC POST PROCESSOR, POST1 (1992-2) 16:00:36 09-Dec-93
2-D PLANE STRAIN GEOMETRY

Linear SC Formation ; CASE = 1; TIME = 0.00001200; CYCLE = 23942



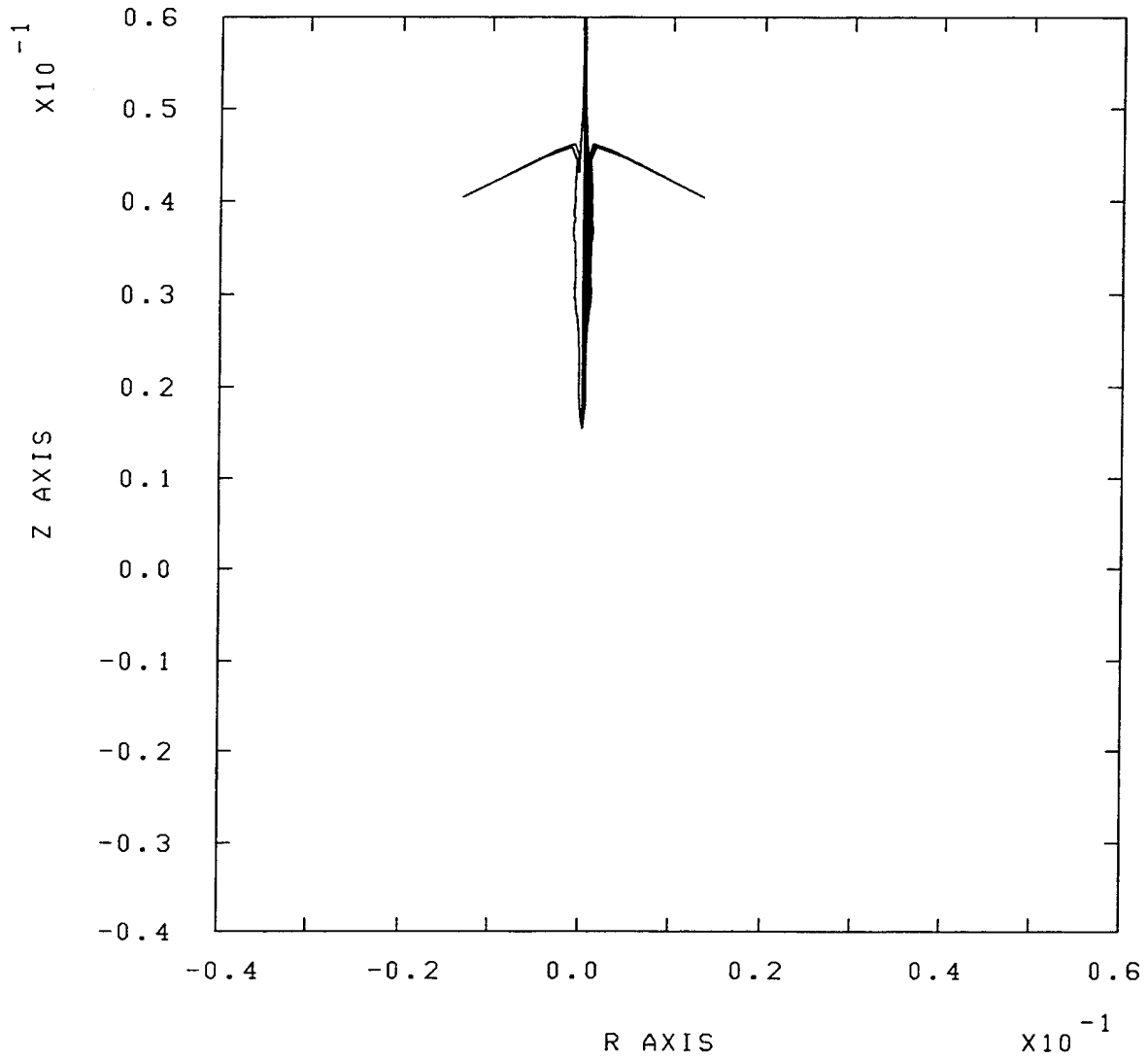
EPIC POST PROCESSOR, POST1 (1992-2) 16:00:39 09-Dec-93
2-D PLANE STRAIN GEOMETRY

Linear SC Formation ; CASE = 1; TIME = 0.00001400; CYCLE = 33746



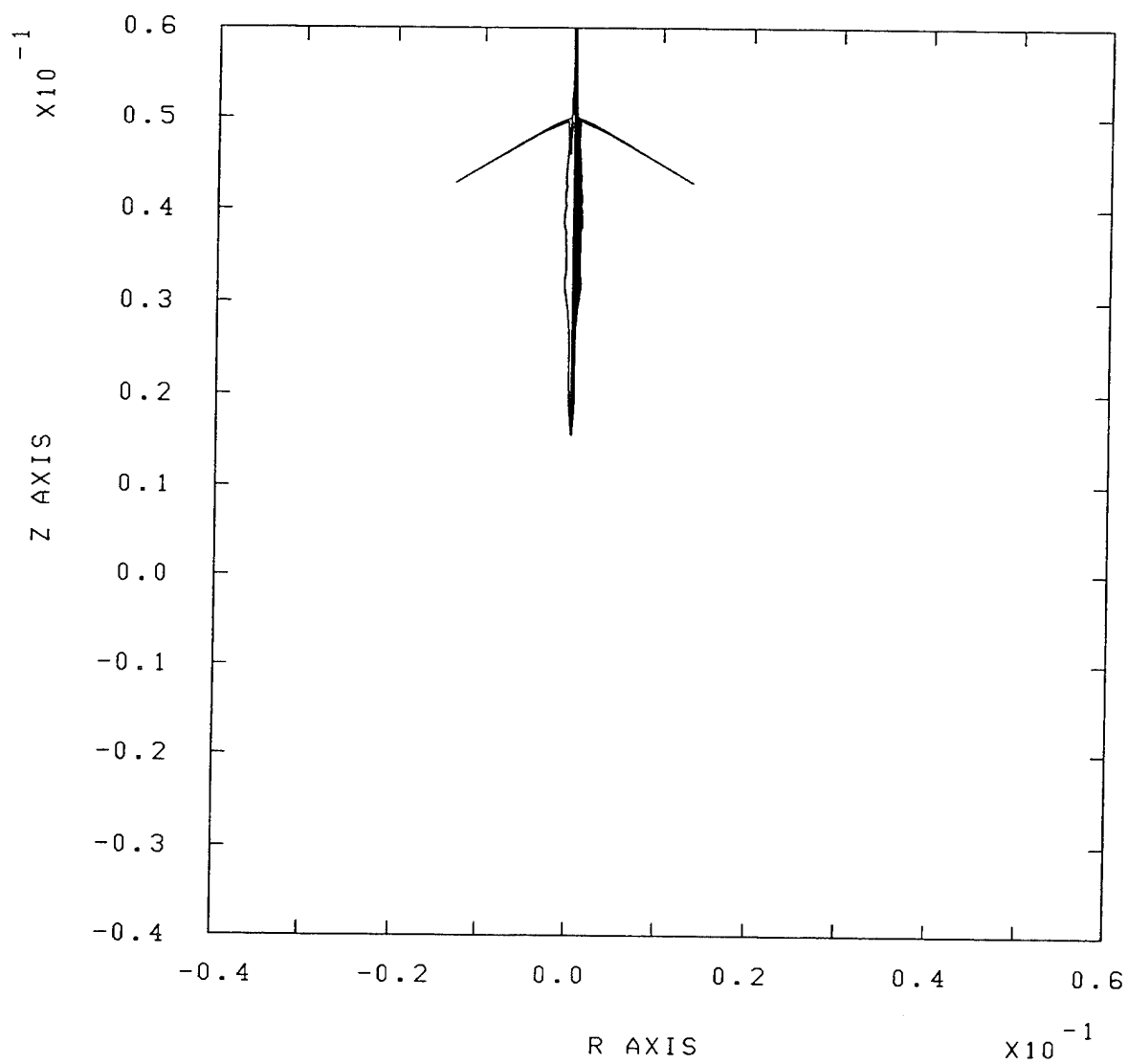
EPIC POST PROCESSOR, POST1 (1992-2) 16:00:42 09-Dec-93
2-D PLANE STRAIN GEOMETRY

Linear SC Formation ; CASE = 1; TIME =0.00001600; CYCLE = 45319



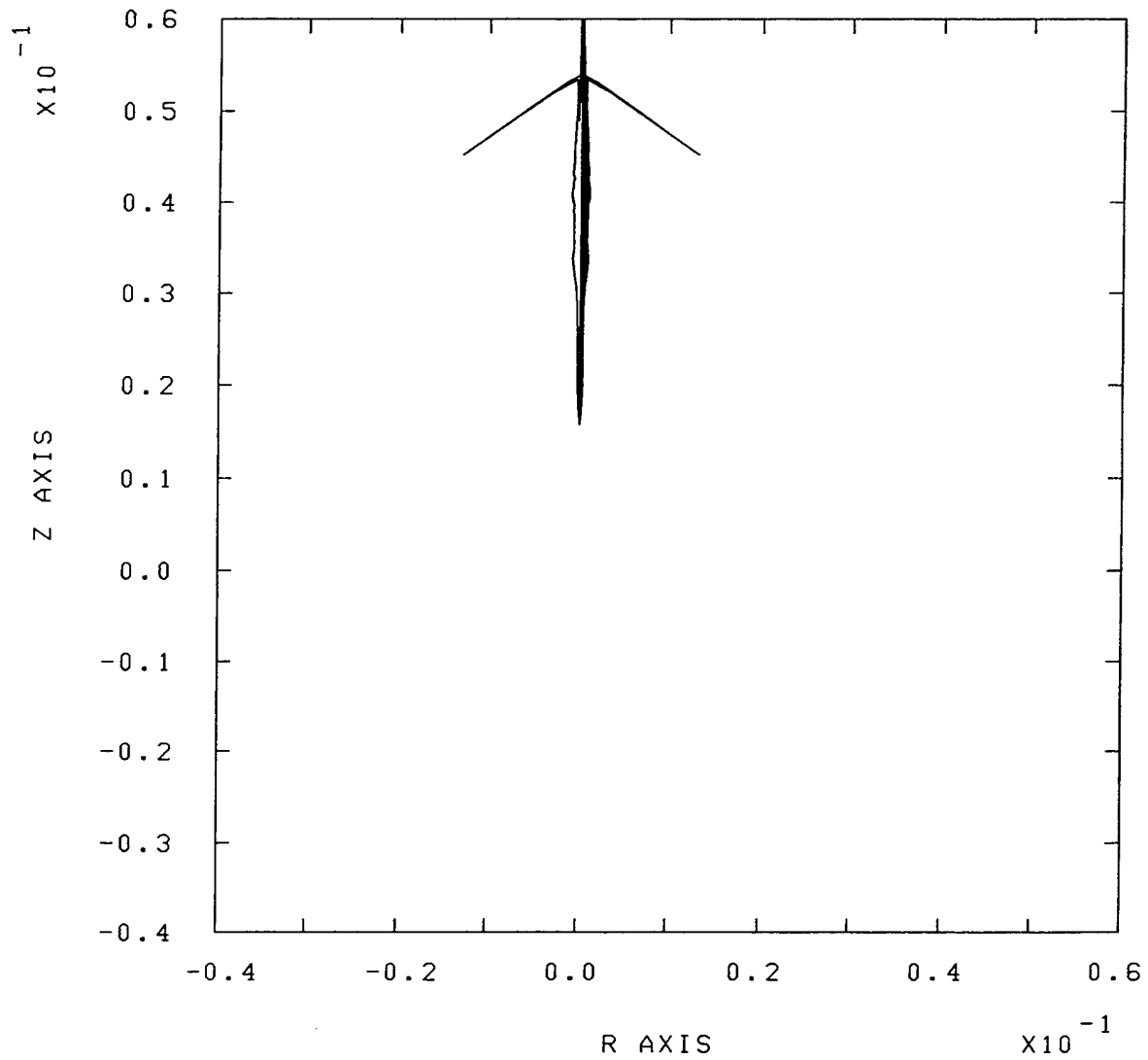
EPIC POST PROCESSOR, POST1 (1992-2) 16:00:46 09-Dec-93
2-D PLANE STRAIN GEOMETRY

Linear SC Formation ; CASE = 1; TIME = 0.00001800; CYCLE = 58707



EPIC POST PROCESSOR, POST1 (1992-2) 16:00:49 09-Dec-93
2-D PLANE STRAIN GEOMETRY

Linear SC Formation ; CASE = 1; TIME =0.00002000; CYCLE = 73975



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APPENDIX B:

**SHAPED CHARGE JET PENETRATION
INPUT DECK AND COMPUTATIONAL RESULTS**

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[illegible]

[illegible]


```

311 1553 621          $ jet tip
$.mlg..mng..inc
2174 1864 -1          $ jet side
$.mlg..mng..inc
1243 1 -621          $ jet tail
$.slg..sng..inc
1962619602 -1        $ target plate front surface
$
$/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/\/
$ Restraints
$ Tie liner nodes to axis of symmetry
311 1 100             $ 311 nodes, 1 set, R-constraint
0001 0311 1           $ First=1, Last=311, Increment=1
$ Restrain Target Outer Nodes in R
350 1 100             $ 350 nodes, 1 set, R-constraint
252519626 49          $ First=2525, Last=19626, Increment=49
$ detonation
$.x/rdet.....ydet.....zdet.....tburn.shad.npnt
0.0 0.0 0.0 0.0
$ initial velocity data
$.px/rdot...py/tdot....pzdot...tx/rdot...ty/tdot.....tzdot.....dt1.vfld/////
-000.00 0.0 0.0 0.0 0.0 0.0 0.0 -1
$
$ NOTE: SPECIAL SUBROUTINE USED TO INPUT VELOCITY FIELD, TRIGGERED BY VFELD=-1

```

```

$$ Main Processor data *****
$
$type.case.....problem description.....]
3 1 NEOD Linear Shaped Charge Penetration - S. Segletes JUN 1994
$
$$ main run data *****
$
$scyl.ncpu.....time.....dtmax.....dtmin.....ssf.....tmax.....cpmax.....emax
0 0 0000.0e-6 1.0 1.e-11 0.80 15.0e-6 00000.00
$stplt.drop..add.pres.push..hrg...vfract.....vnref...nabfact...sphdist////////
1 0 0 0 0 0
$.sys.nplt.lplt.dplt....dtsys.....tsys....dtnode....tnode....dtdyn.....tdyn
1 0 1.0e-6 0.0 0.25e-6 0.0
$....time...echeck...ncheck....rdamp.save.burn.yprt.ndat.slpr.proj..pat.rzne
00.4E-06 1001.0 999 0.0 3 0 1 500 0 0 0 0
00.8E-06 1001.0 999 0.0 3 0 1 500 0 0 0 0
01.2E-06 1001.0 999 0.0 3 0 1 500 0 0 0 0
01.6E-06 1001.0 999 0.0 3 0 1 500 0 0 0 0
02.0E-06 1001.0 999 0.0 3 0 1 500 0 0 0 0
04.0E-06 1001.0 999 0.0 3 0 1 500 0 0 0 0
06.0E-06 1001.0 999 0.0 3 0 1 500 0 0 0 0
08.0E-06 1001.0 999 0.0 3 0 1 500 0 0 0 0
10.0E-06 1001.0 999 0.0 3 0 1 500 0 0 0 0
15.1E-06 1001.0 999 0.0 3 0 1 500 0 0 0 0

```

```

$$ Main Processor data *****
$
$type.case.....problem description.....]

```

[illegible]

52

```

& 5051.104, 5036.811, 5022.705, 5008.770, 4995.006,
& 4981.402, 4967.948, 4954.640, 4941.470, 4928.432,
& 4915.522, 4902.730, 4890.058, 4877.499, 4865.044/
data f2 (101:200)/
& 4852.695, 4840.443, 4828.293, 4816.229, 4804.255,
& 4792.370, 4780.569, 4768.847, 4757.201, 4745.629,
& 4734.132, 4722.703, 4711.340, 4700.047, 4688.817,
& 4677.646, 4666.537, 4655.483, 4644.486, 4633.543,
& 4622.653, 4611.813, 4601.025, 4590.284, 4579.589,
& 4568.938, 4558.335, 4547.771, 4537.249, 4526.767,
& 4516.324, 4505.918, 4495.553, 4485.220, 4474.923,
& 4464.657, 4454.425, 4444.227, 4434.060, 4423.919,
& 4413.810, 4403.728, 4393.673, 4383.646, 4373.641,
& 4363.665, 4353.709, 4343.778, 4333.874, 4323.984,
& 4314.120, 4304.275, 4294.449, 4284.642, 4274.856,
& 4265.087, 4255.335, 4245.596, 4235.875, 4226.173,
& 4216.479, 4206.805, 4197.142, 4187.492, 4177.854,
& 4168.226, 4158.610, 4149.006, 4139.414, 4129.829,
& 4120.253, 4110.687, 4101.126, 4091.576, 4082.031,
& 4072.493, 4062.959, 4053.431, 4043.913, 4034.394,
& 4024.881, 4015.372, 4005.866, 3996.359, 3986.856,
& 3977.356, 3967.855, 3958.356, 3948.855, 3939.354,
& 3929.855, 3920.353, 3910.849, 3901.341, 3891.831,
& 3882.318, 3872.799, 3863.280, 3853.754, 3844.221/
data f3 (201:300)/
& 3834.684, 3825.138, 3815.587, 3806.028, 3796.463,
& 3786.886, 3777.305, 3767.709, 3758.105, 3748.493,
& 3738.867, 3729.229, 3719.582, 3709.917, 3700.242,
& 3690.552, 3680.849, 3671.128, 3661.395, 3651.639,
& 3641.872, 3632.084, 3622.281, 3612.458, 3602.614,
& 3592.750, 3582.864, 3572.957, 3563.029, 3553.076,
& 3543.100, 3533.097, 3523.072, 3513.018, 3502.937,
& 3492.827, 3482.693, 3472.525, 3462.327, 3452.100,
& 3441.836, 3431.540, 3421.210, 3410.843, 3400.439,
& 3389.999, 3379.520, 3369.000, 3358.439, 3347.835,
& 3337.187, 3326.496, 3315.757, 3304.969, 3294.135,
& 3283.246, 3272.307, 3261.312, 3250.263, 3239.155,
& 3227.989, 3216.759, 3205.468, 3194.111, 3182.687,
& 3171.193, 3159.625, 3147.983, 3136.264, 3124.465,
& 3112.583, 3100.617, 3088.560, 3076.413, 3064.168,
& 3051.824, 3039.376, 3026.822, 3014.156, 3001.373,
& 2988.468, 2975.438, 2962.275, 2948.973, 2935.527,
& 2921.930, 2908.173, 2894.251, 2880.155, 2865.874,
& 2851.396, 2836.715, 2821.818, 2806.689, 2791.314,
& 2775.681, 2759.770, 2743.559, 2727.032, 2710.160/
data f4 (301:311)/
& 2692.922, 2675.279, 2657.195, 2638.635, 2619.551,
& 2599.880, 2579.562, 2558.512, 2536.633, 2513.806,
& 2489.873/

```

```

C
  write (*,100) field
100 format (5f10.3)
  mjdelt = 311
  idelt = 621
C
  DO FOR NODES IN JET ONLY
  do 10 n = 1, 2174
    index = mod(n-1,idelt) + 1

```

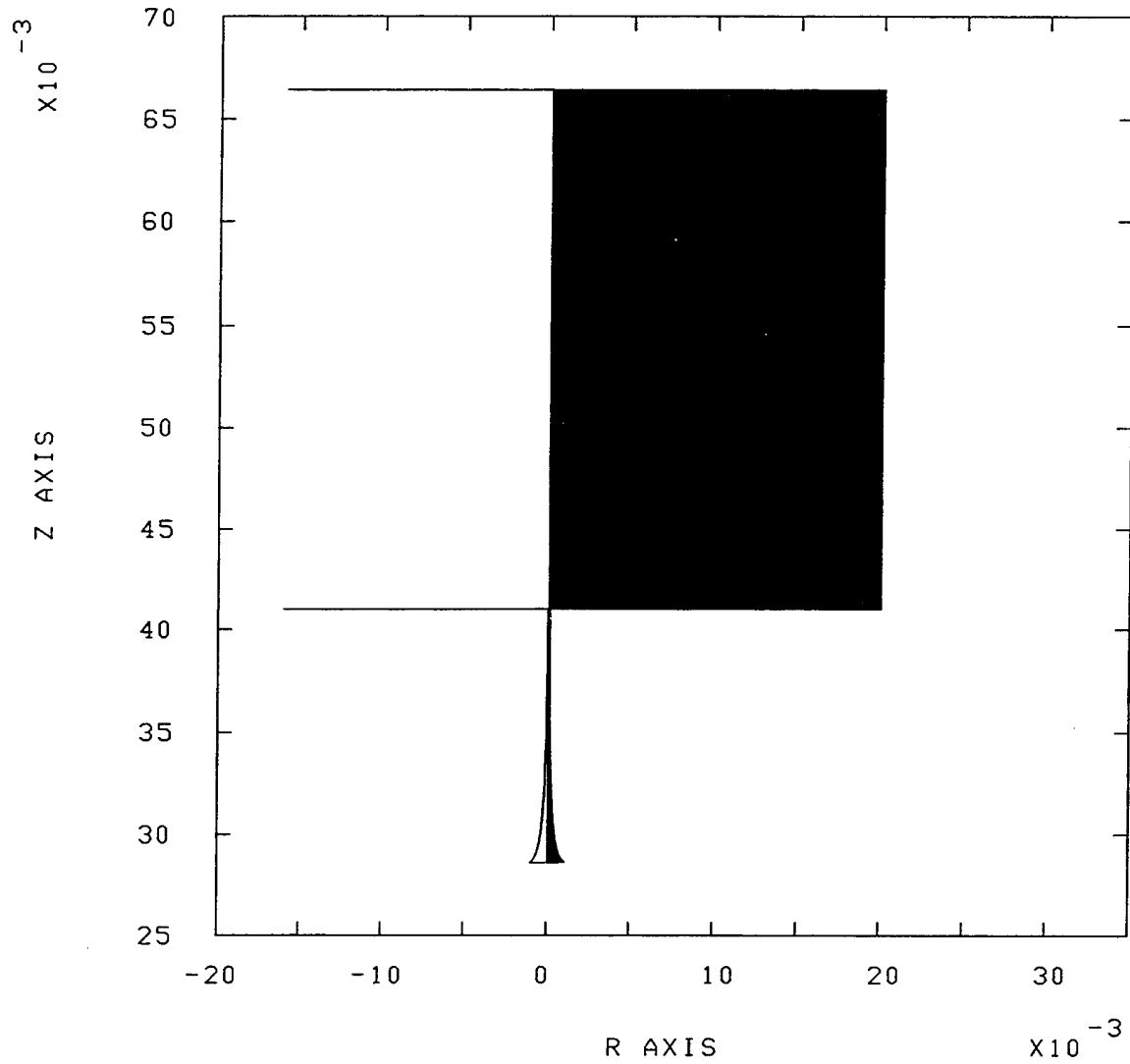
```

c      print *, 'index=',index
      if (index .le. mjdelt) then
c        print *, 'i2=',i2
        zdot(n) = field(i2)
      else
        i1 = index - mjdelt
        i2 = mjdelt + 1 - i1
c        print *, 'i1,i2=',i1,i2
        zdot(n) = (field(i2) + field(i2-1)) * 0.5
      end if
10 continue
      return
      end

```

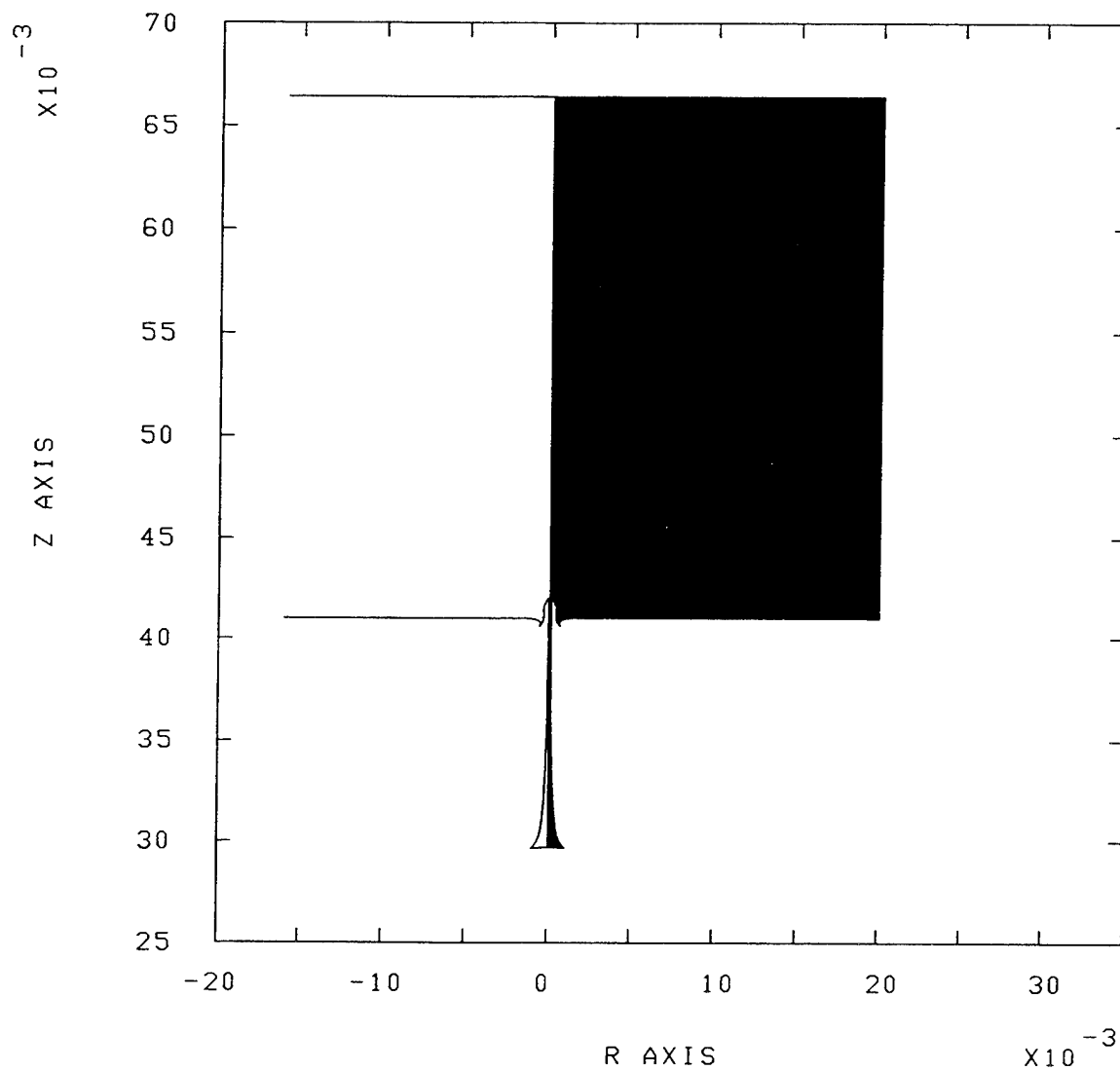

EPIC POST PROCESSOR, POST1 (1992-2) 09:31:15 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00000000; CYCLE = 0



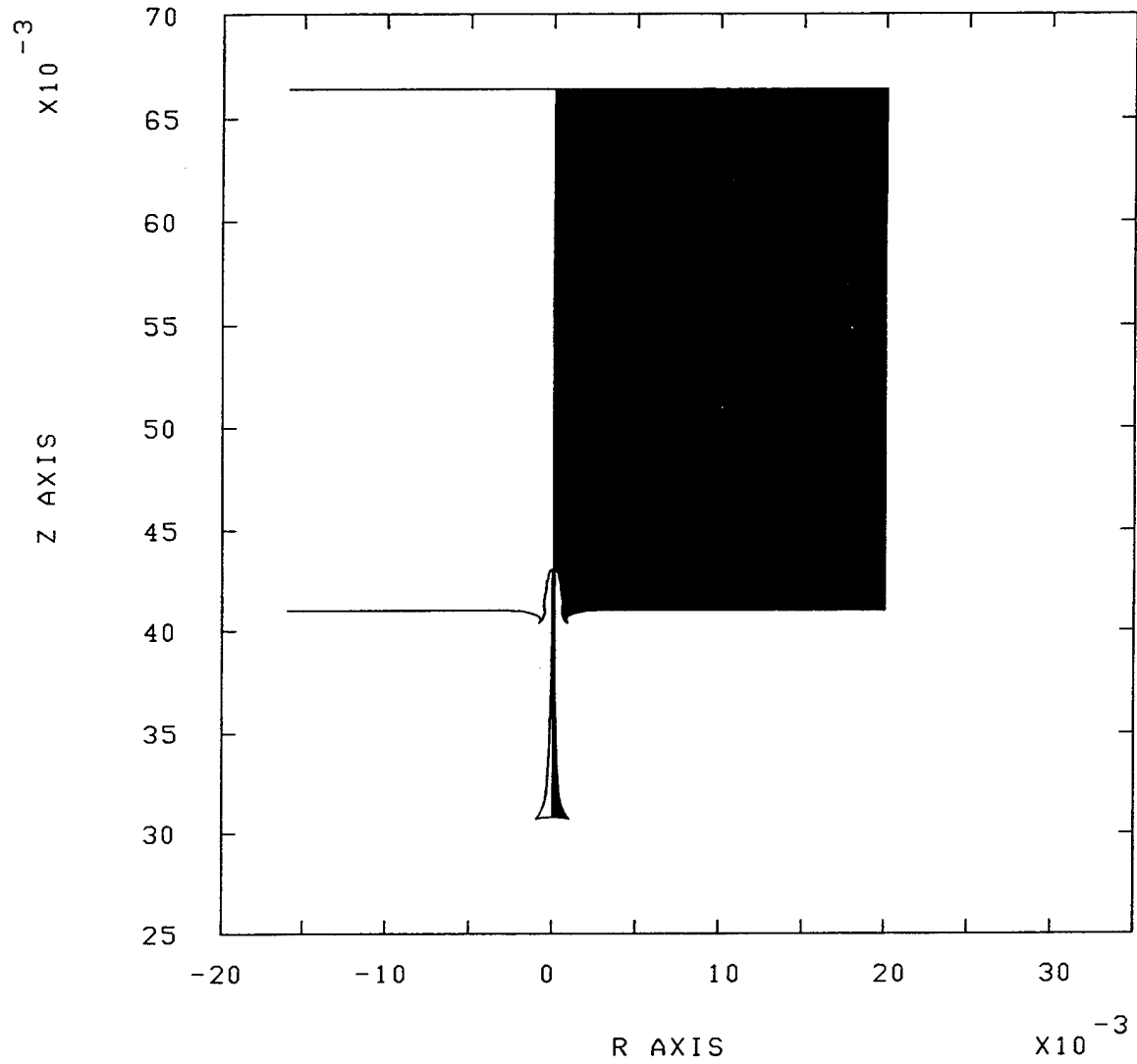
EPIC POST PROCESSOR, POST1 (1992-2) 09:31:57 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00000040; CYCLE = 809



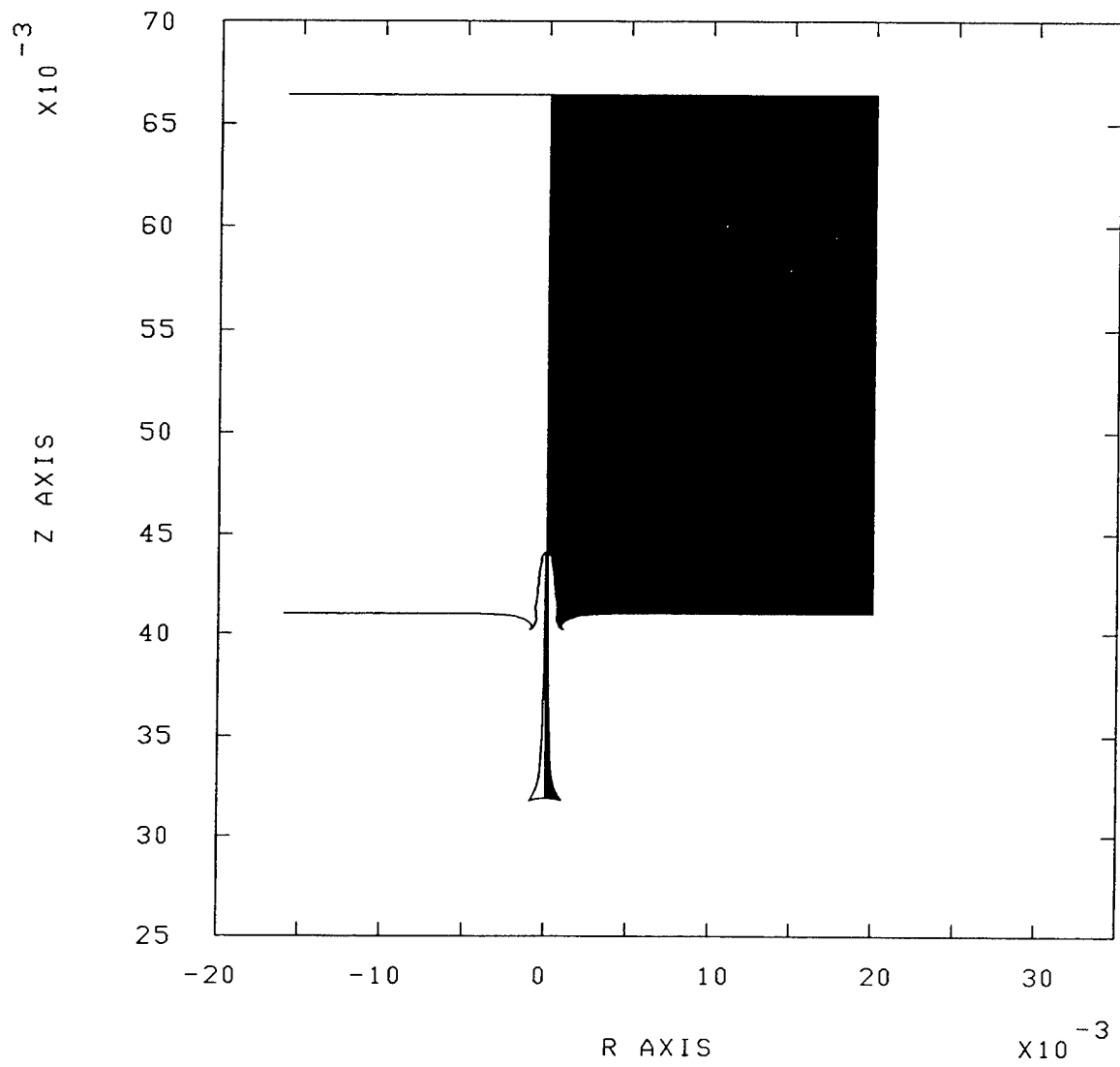
EPIC POST PROCESSOR, POST1 (1992-2) 09:32:38 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00000080; CYCLE = 1601



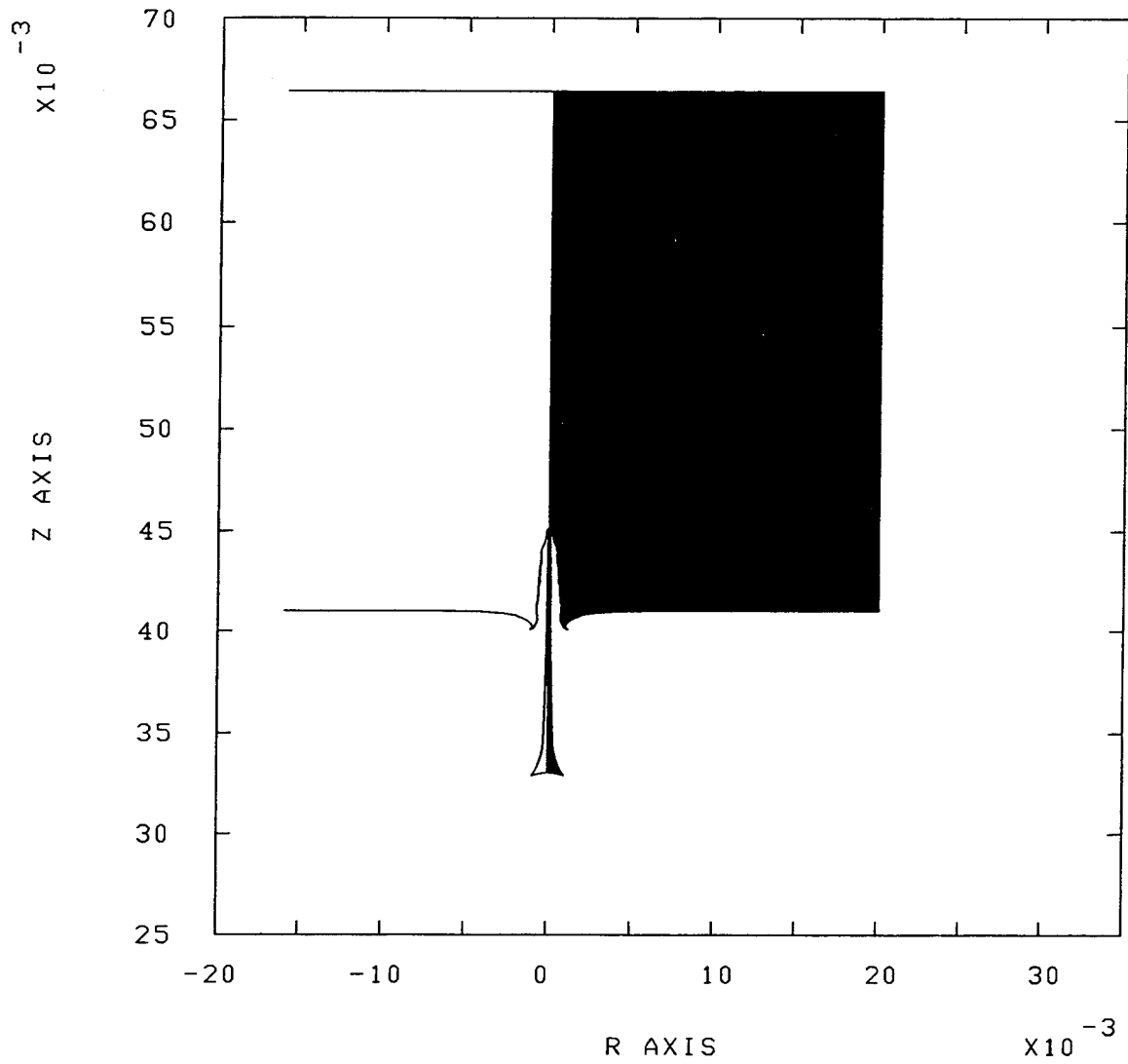
EPIC POST PROCESSOR, POST1 (1992-2) 09:33:18 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00000120; CYCLE = 2339



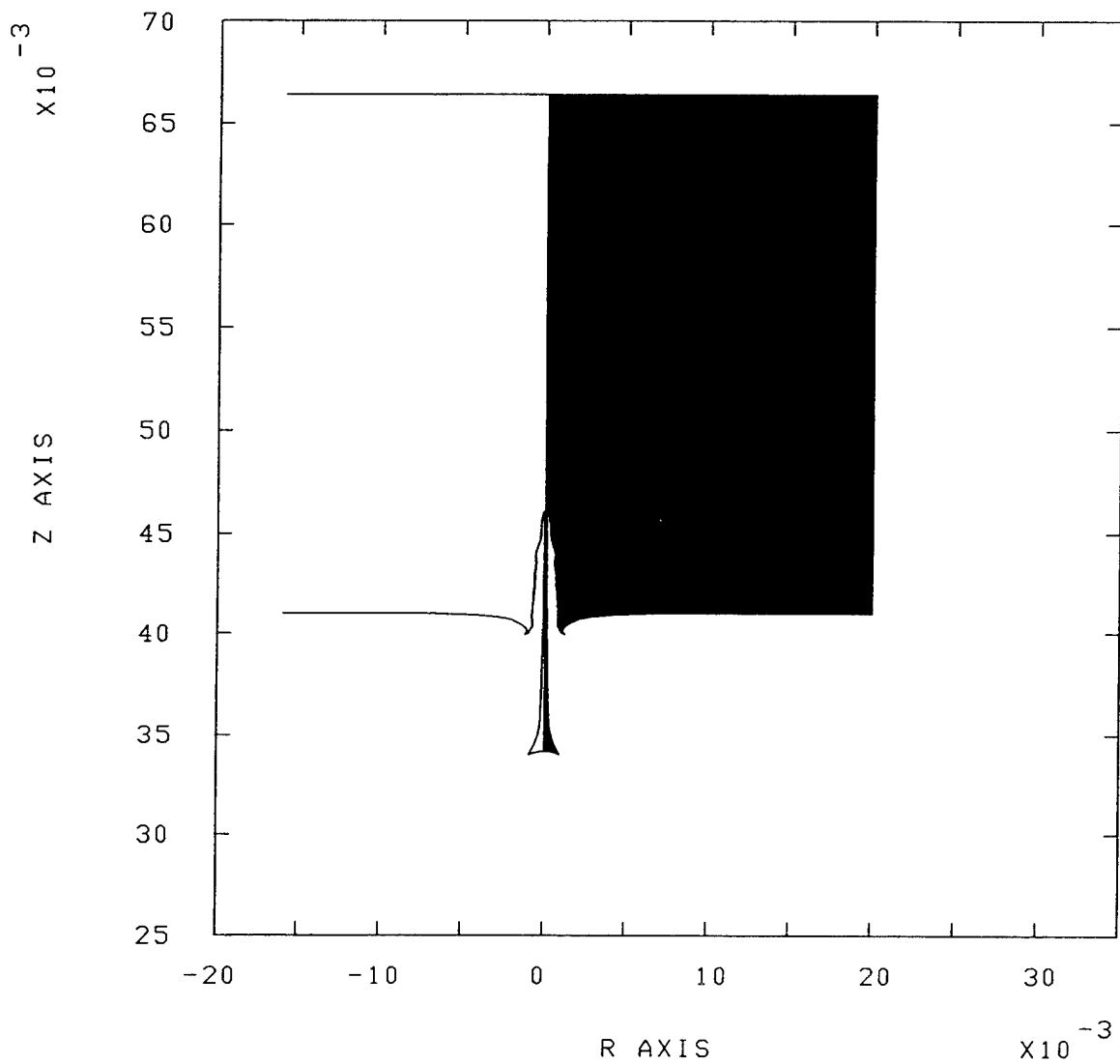
EPIC POST PROCESSOR, POST1 (1992-2) 09:33:55 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00000160; CYCLE = 2910



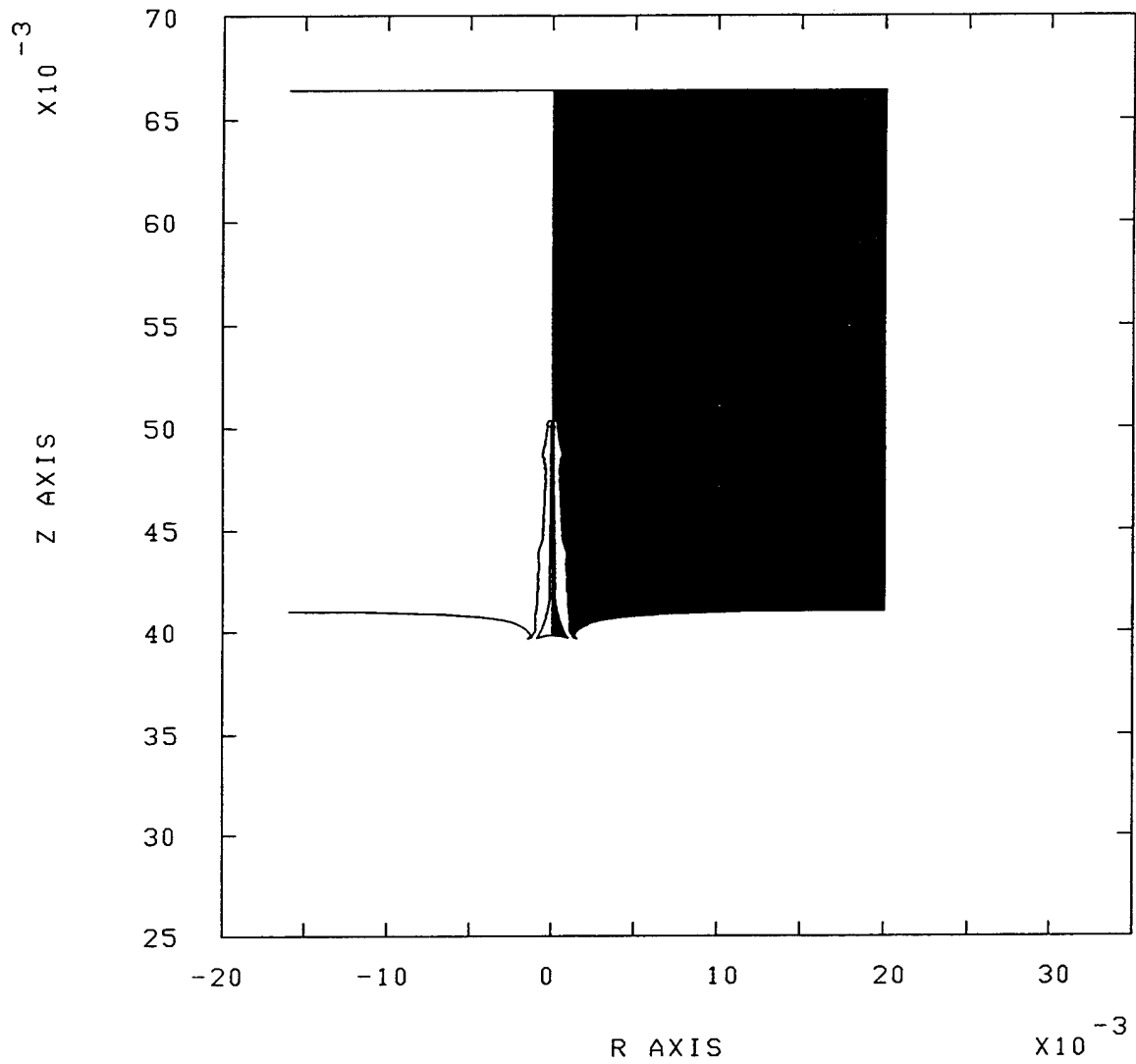
EPIC POST PROCESSOR, POST1 (1992-2) 09:34:45 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00000200; CYCLE = 3474



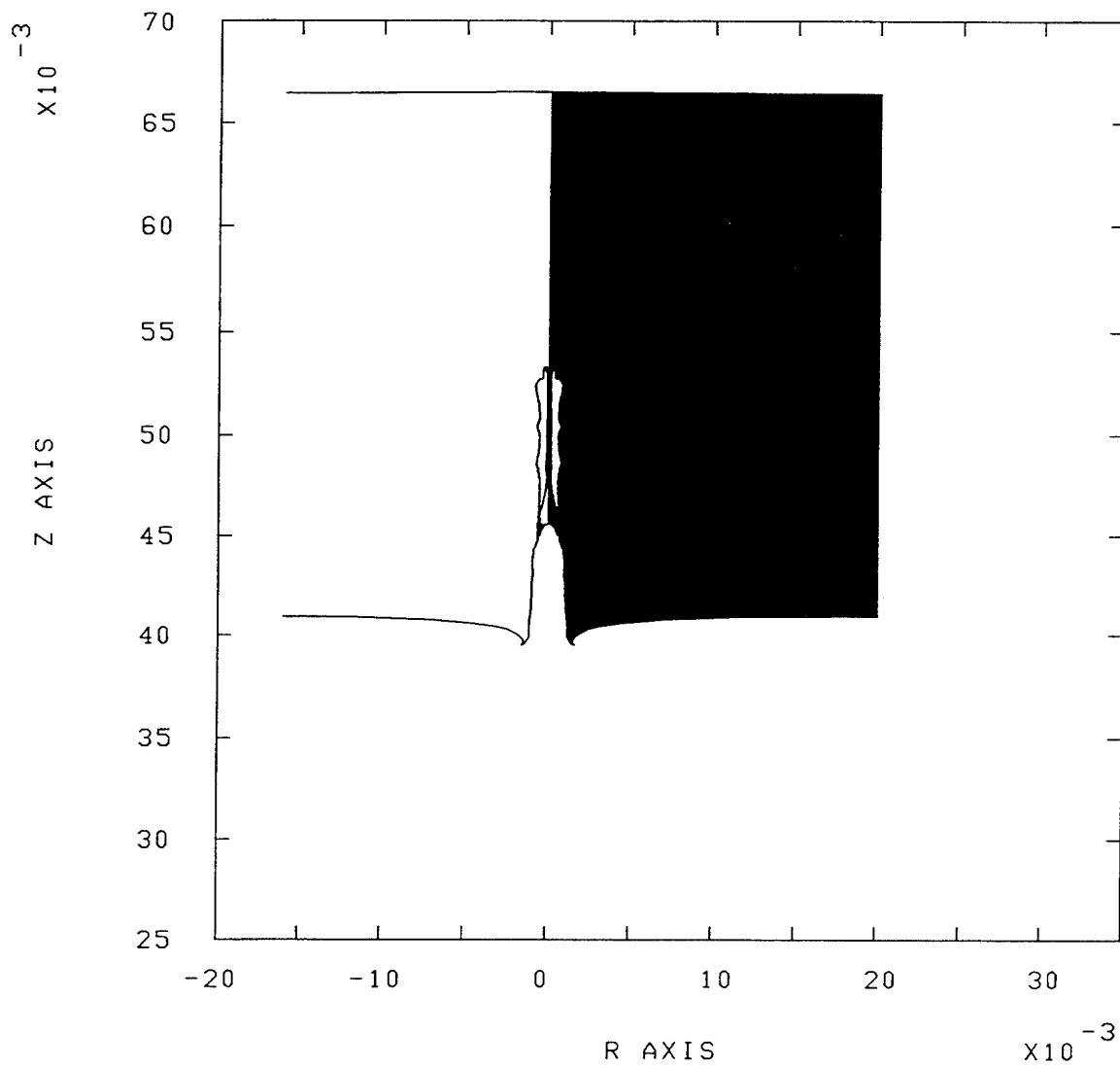
EPIC POST PROCESSOR, POST1 (1992-2) 09:35:29 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00000400; CYCLE = 6111



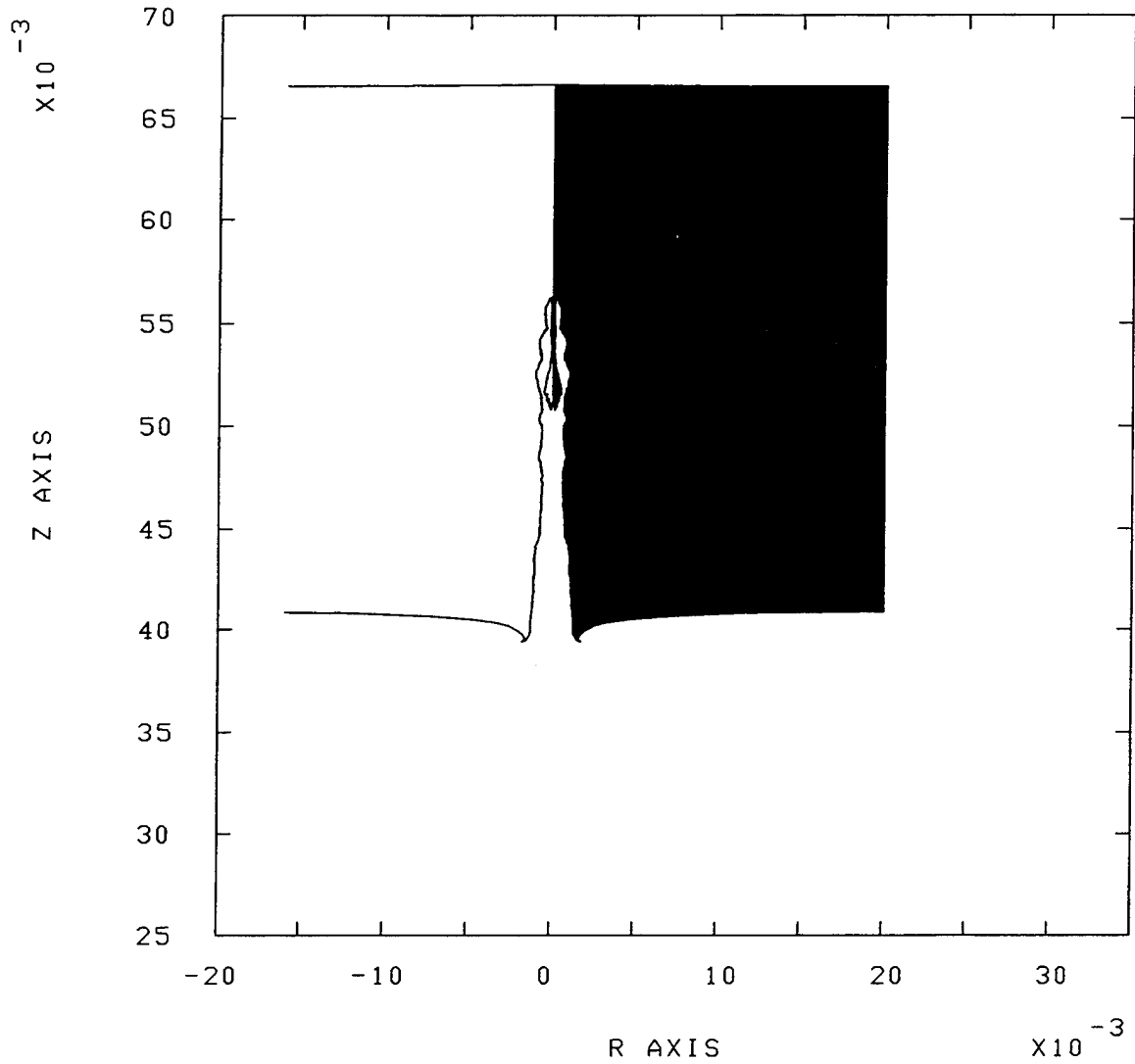
EPIC POST PROCESSOR, POST1 (1992-2) 09:36:00 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00000600; CYCLE = 8646



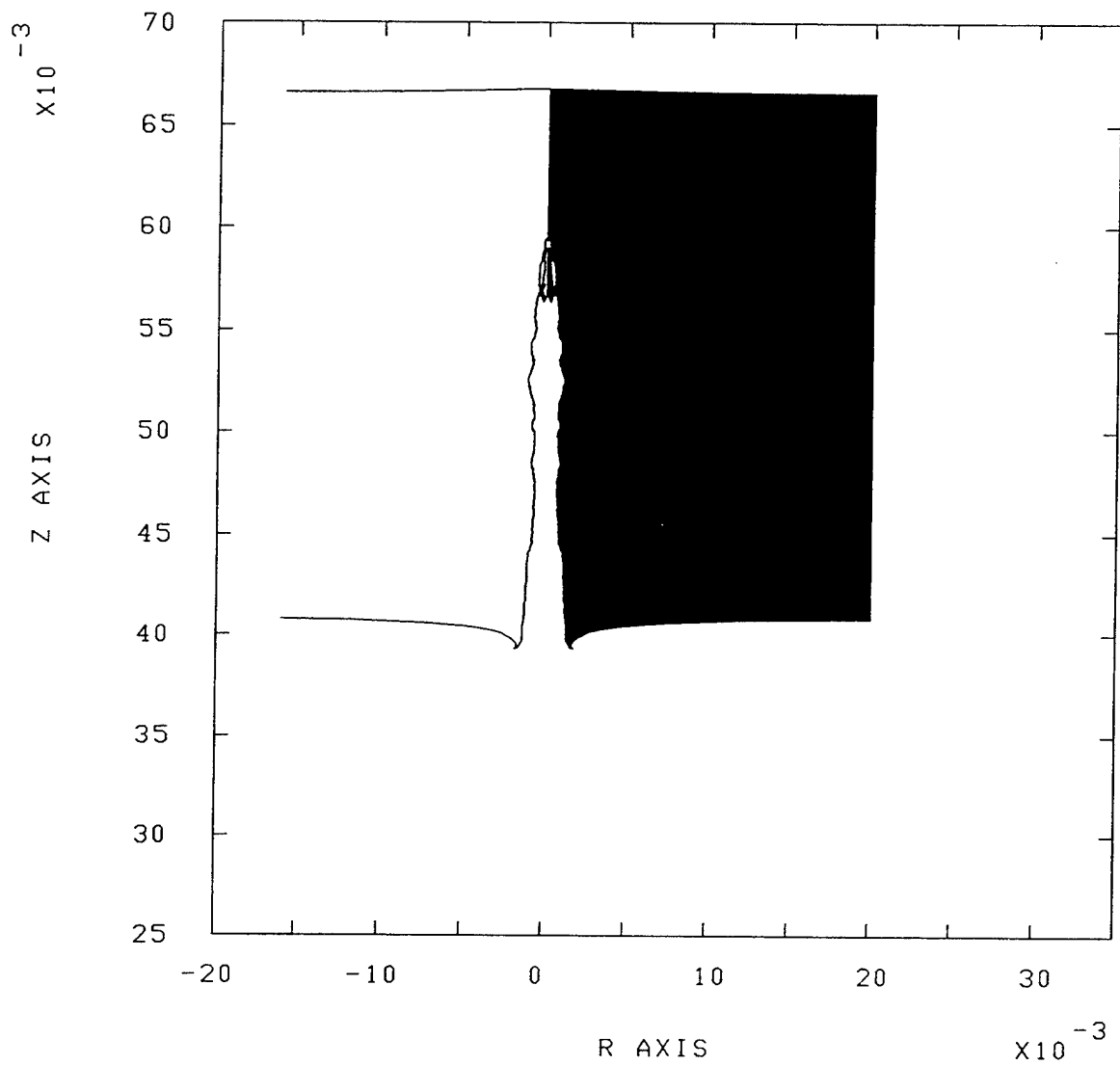
EPIC POST PROCESSOR, POST1 (1992-2) 09:36:23 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00000800; CYCLE = 11163



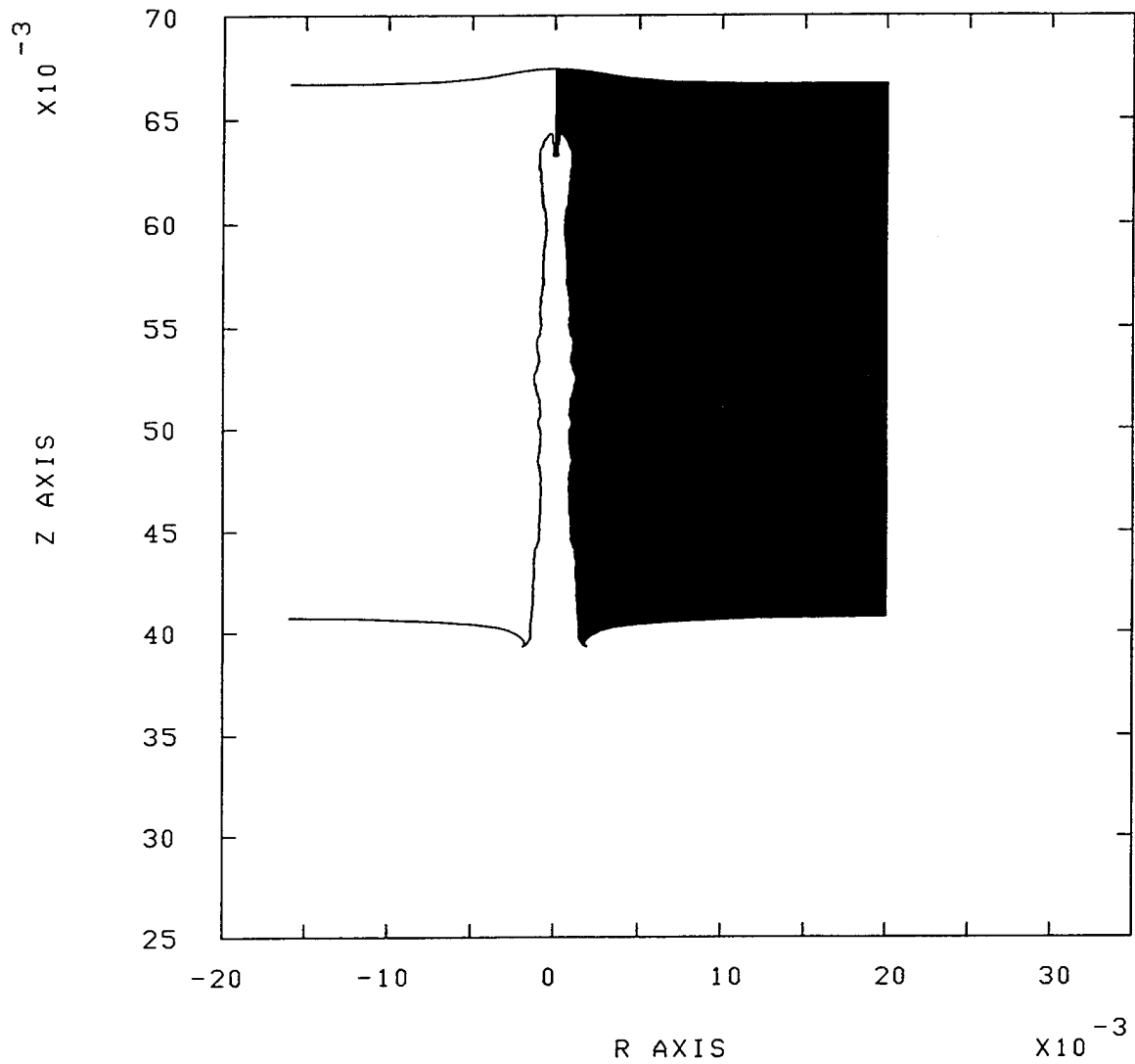
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2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00001000; CYCLE = 13670



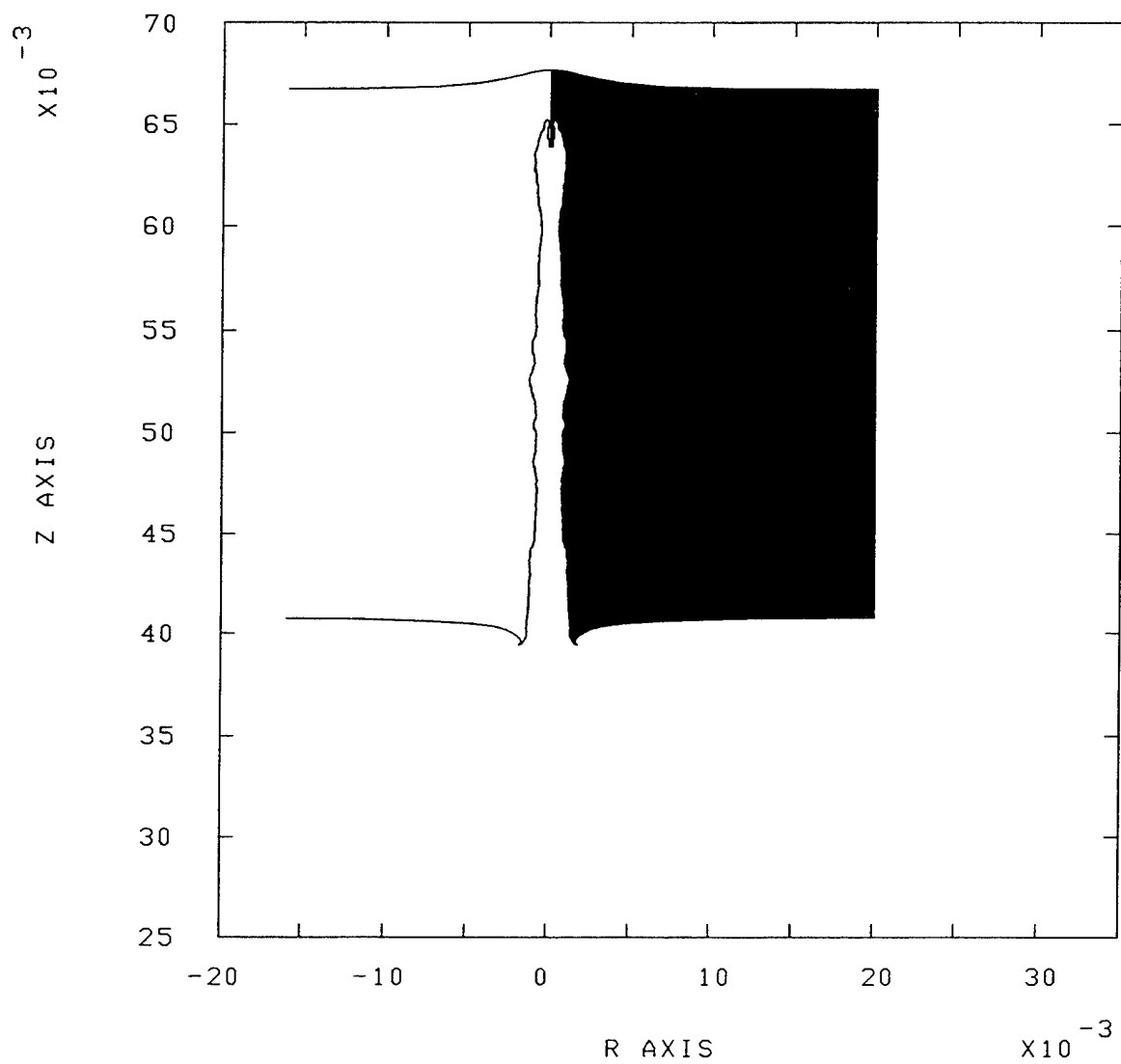
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2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00001500; CYCLE = 19897



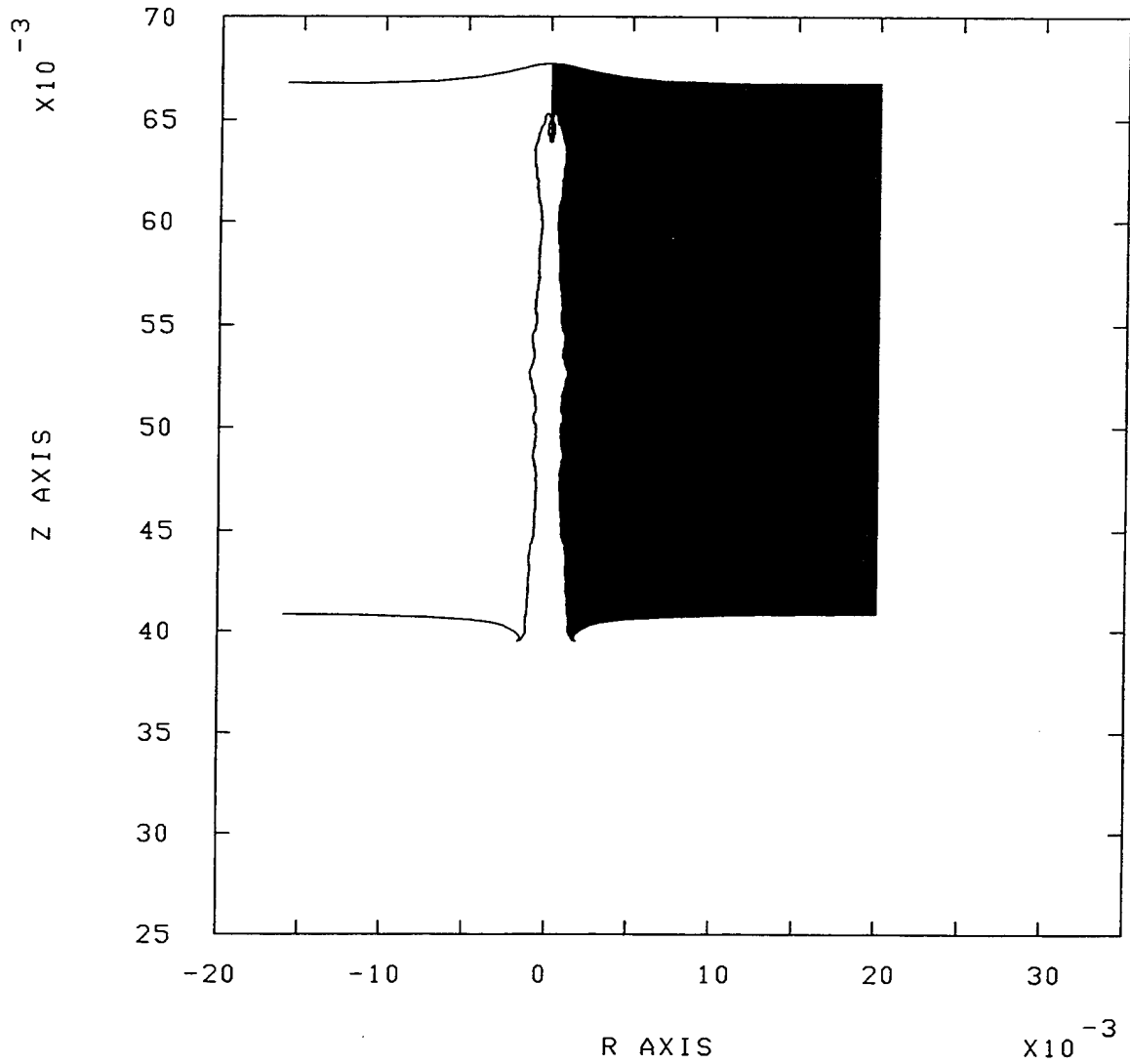
EPIC POST PROCESSOR, POST1 (1992-2) 10:52:37 10-Aug-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00002000; CYCLE = 24520



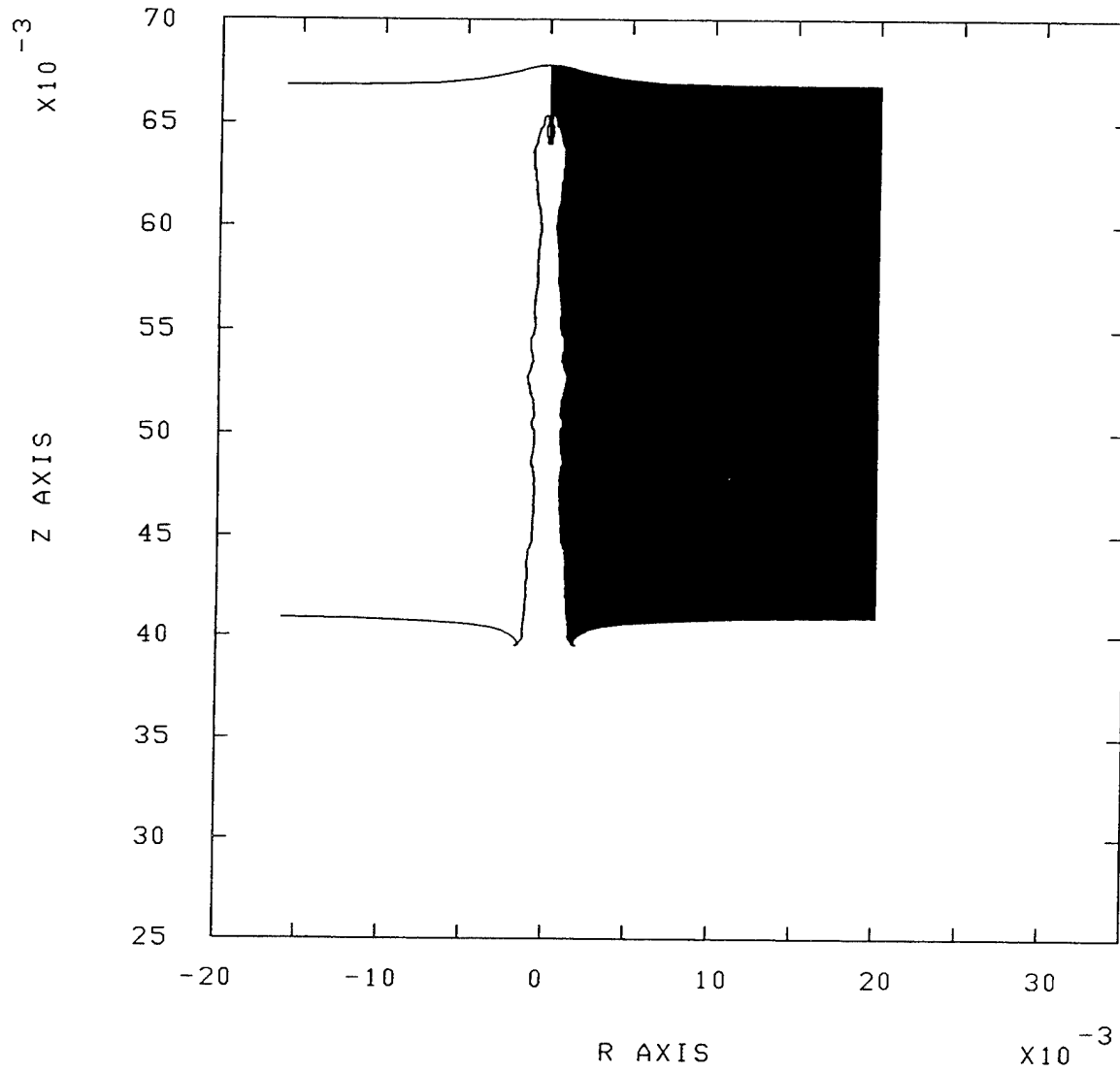
EPIC POST PROCESSOR, POST1 (1992-2) 08:05:14 12-Aug-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00002500; CYCLE = 29139



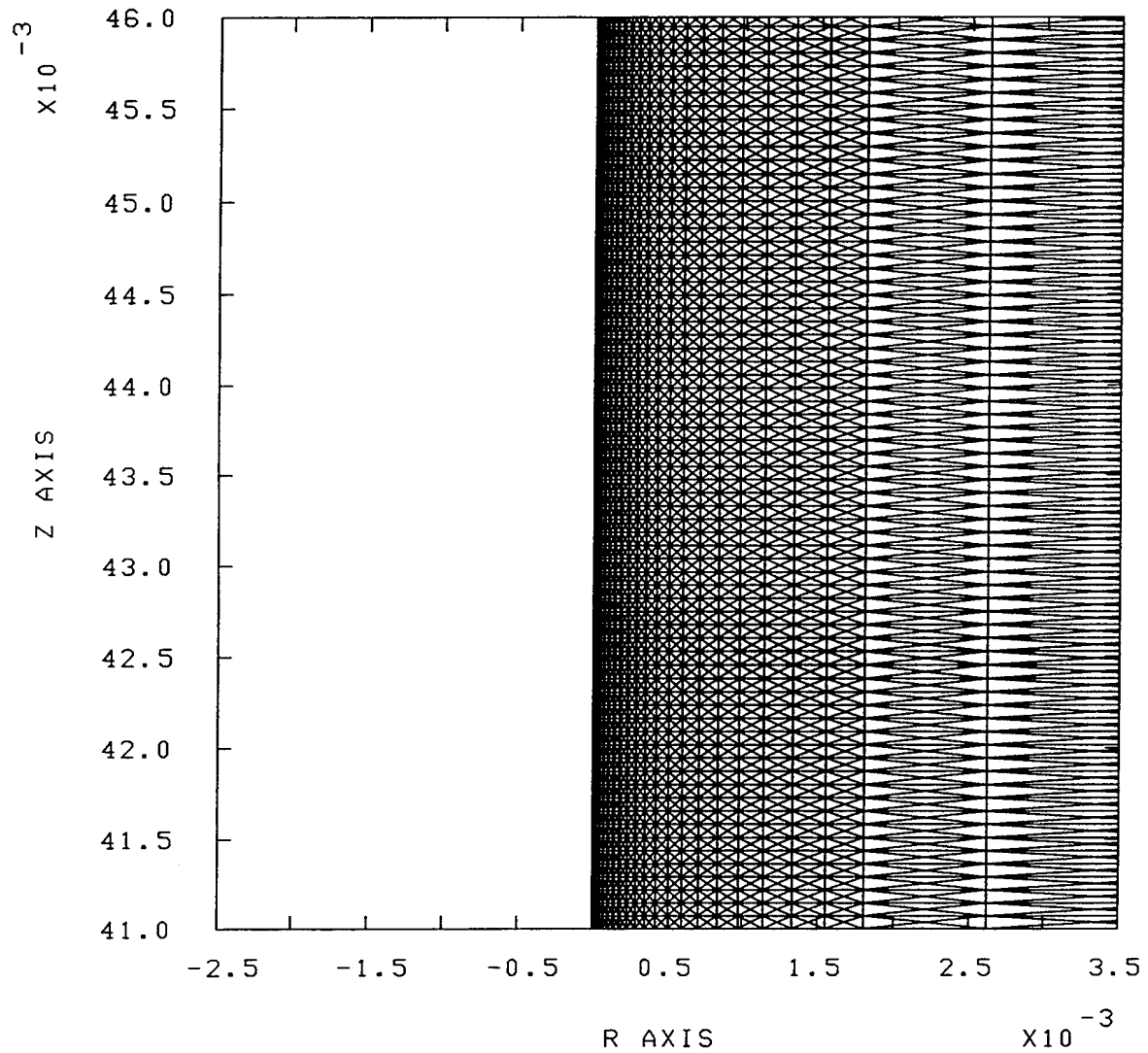
EPIC POST PROCESSOR, POST1 (1992-2) 08:05:32 12-Aug-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00003000; CYCLE = 33752



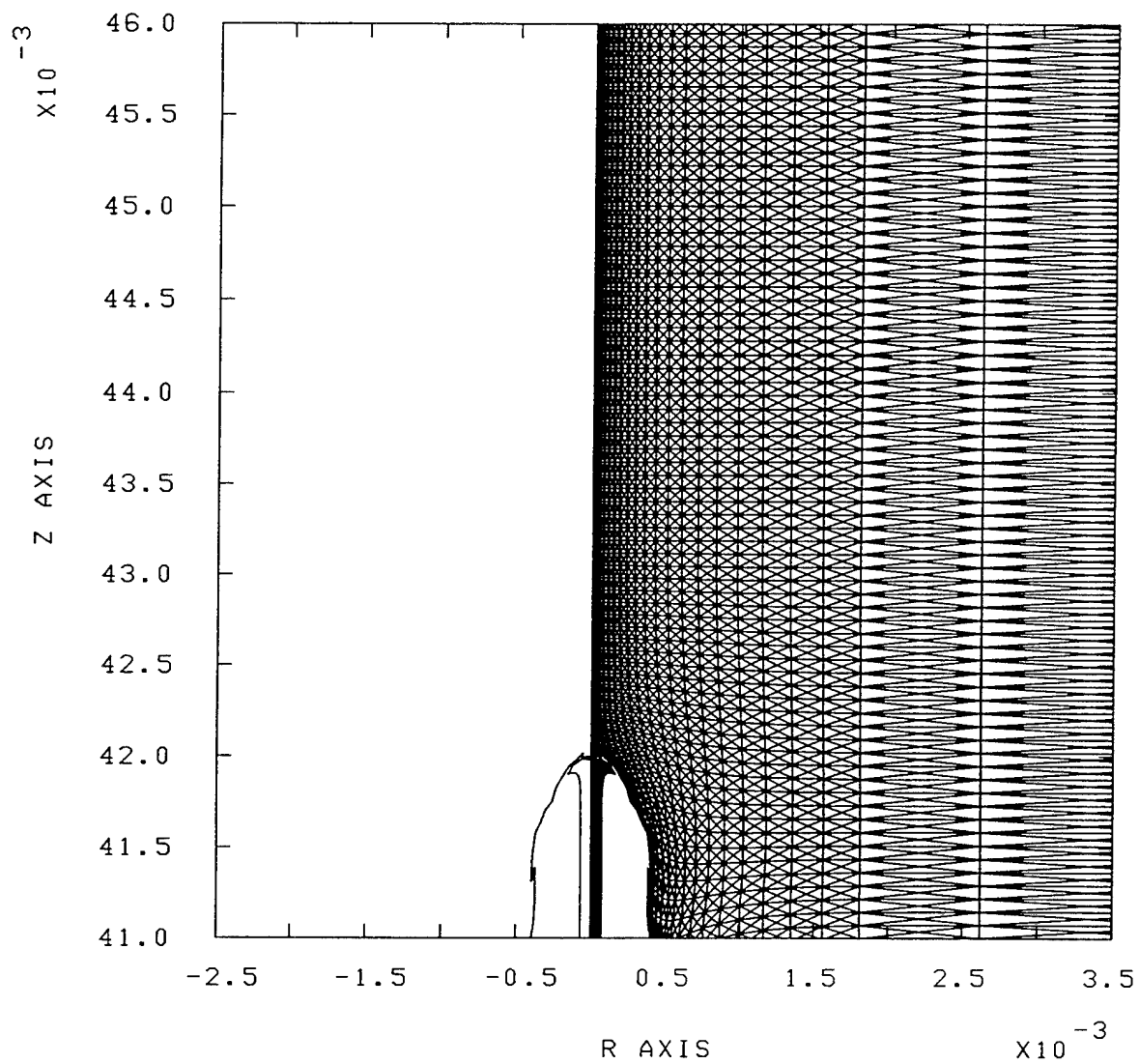
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2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00000000; CYCLE = 0



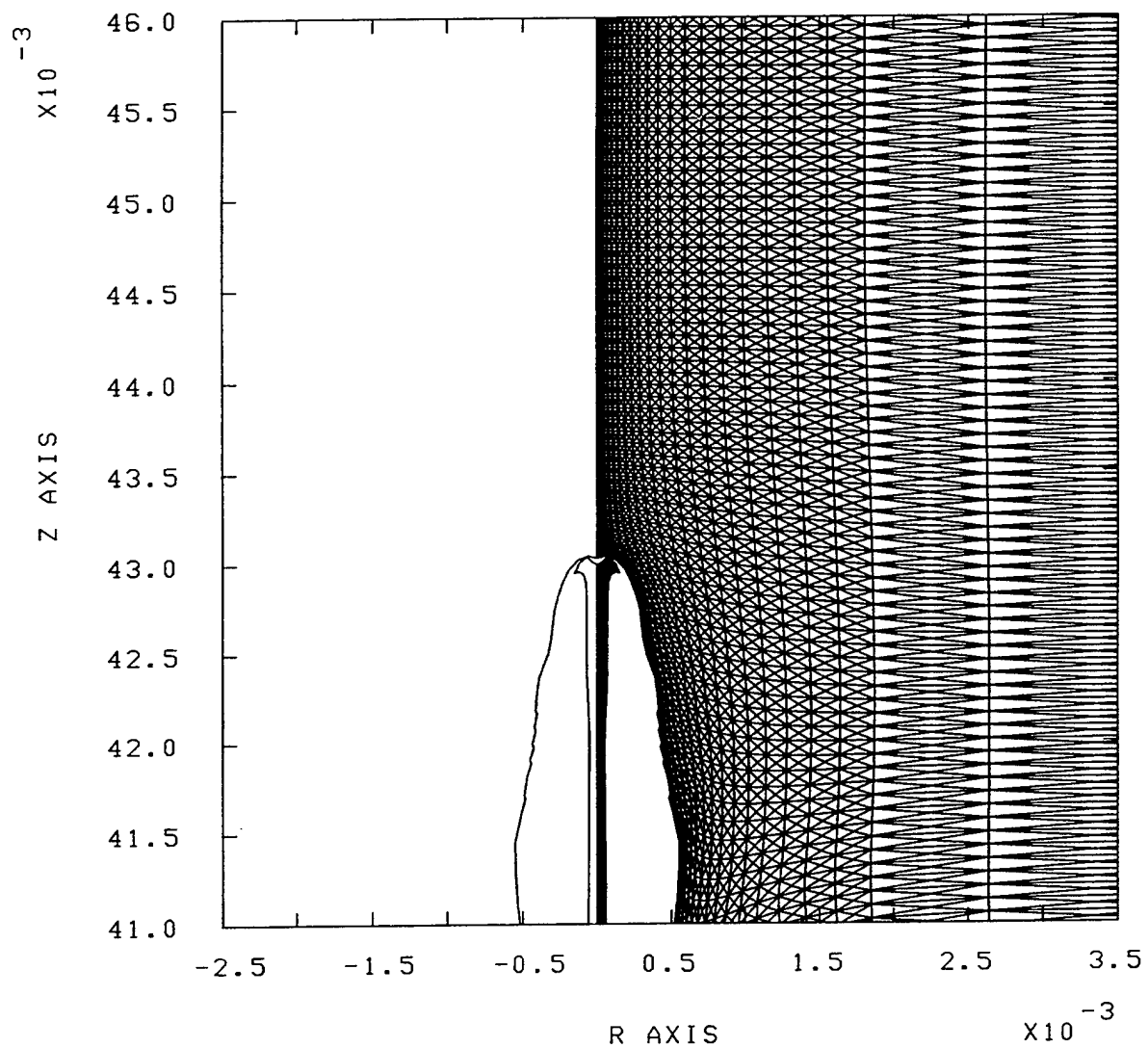
EPIC POST PROCESSOR, POST1 (1992-2) 09:31:55 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME =0.00000040; CYCLE = 809



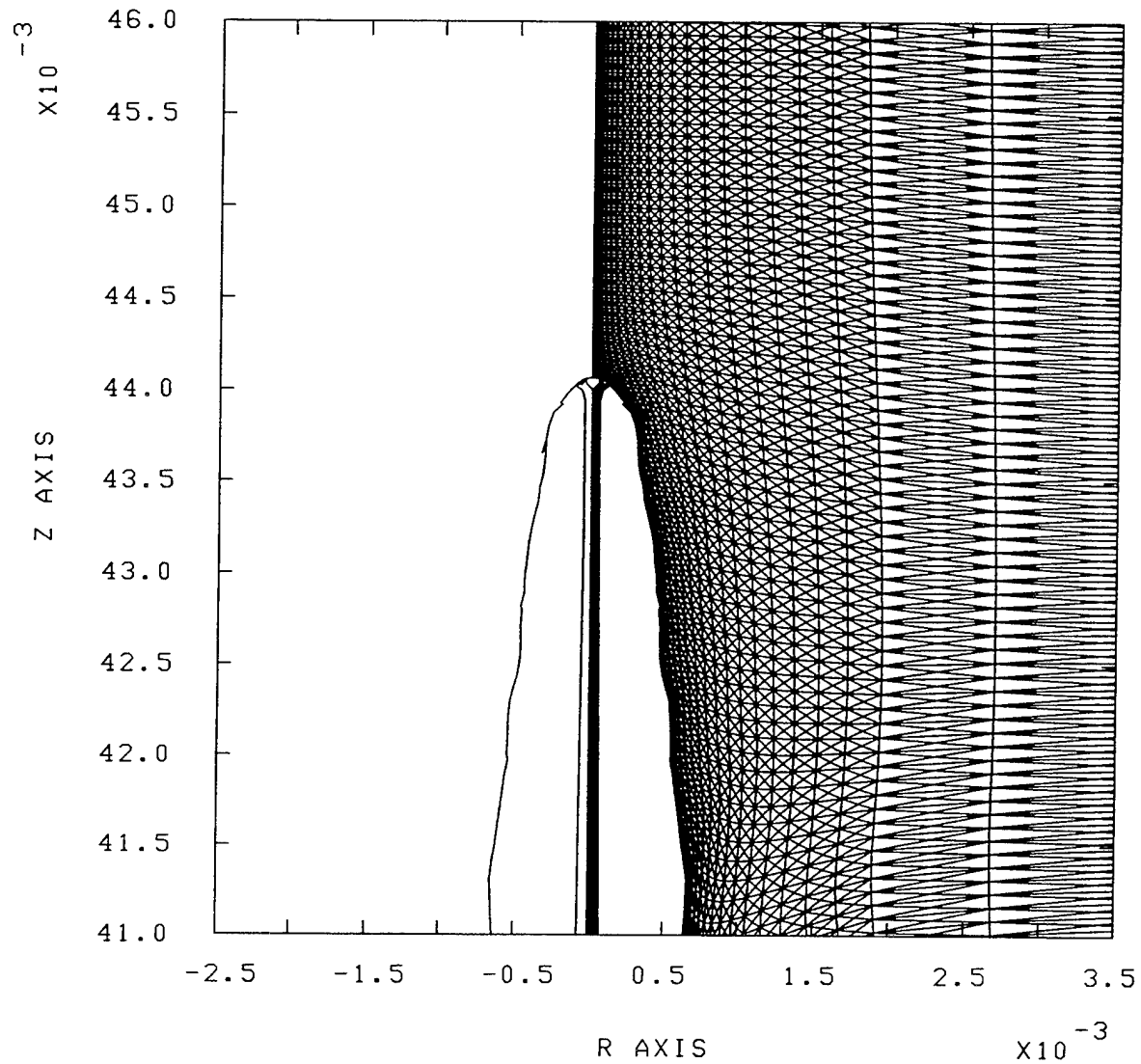
EPIC POST PROCESSOR, POST1 (1992-2) 09:32:36 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00000080; CYCLE = 1601



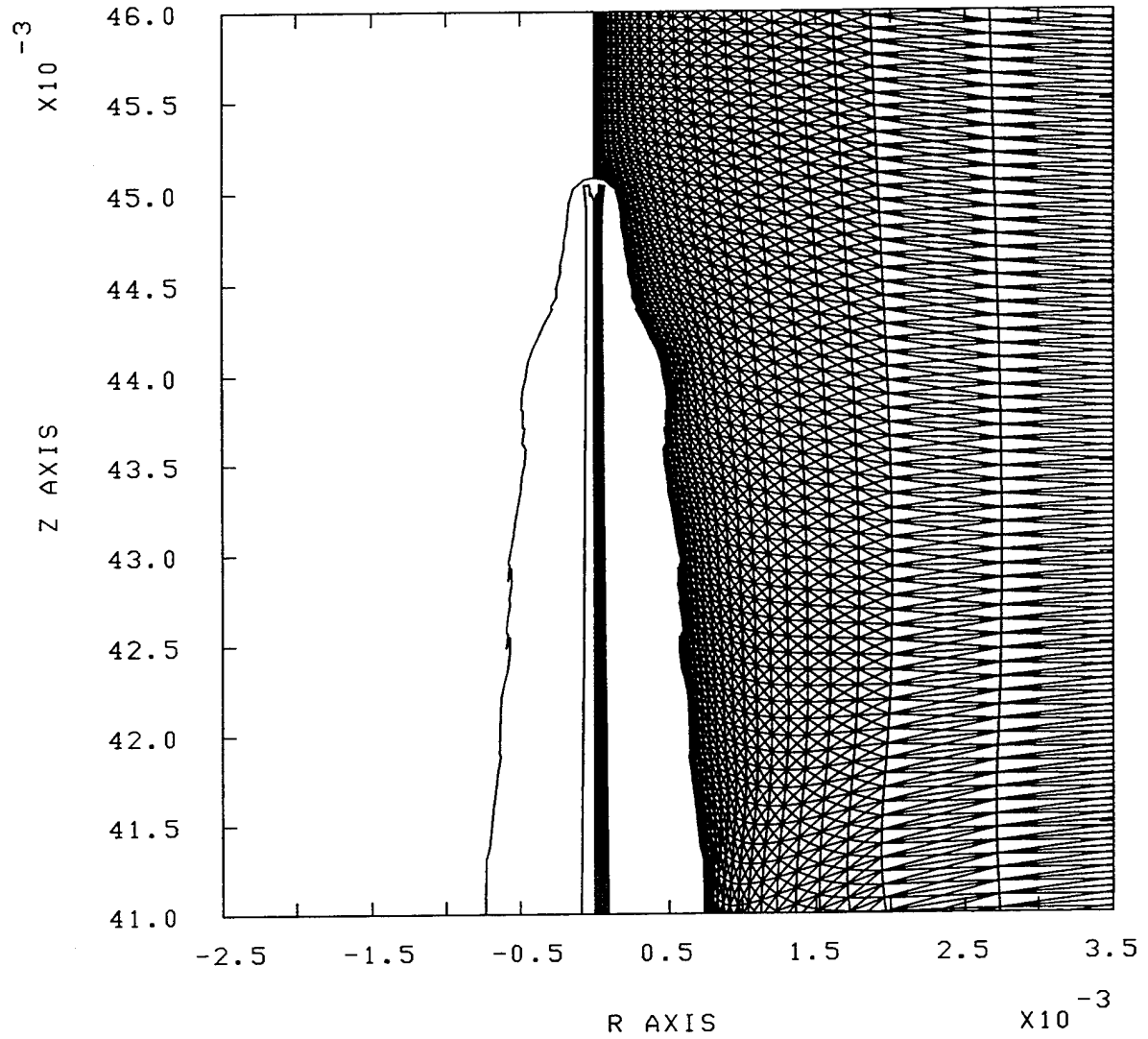
EPIC POST PROCESSOR, POST1 (1992-2) 09:33:16 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00000120; CYCLE = 2339



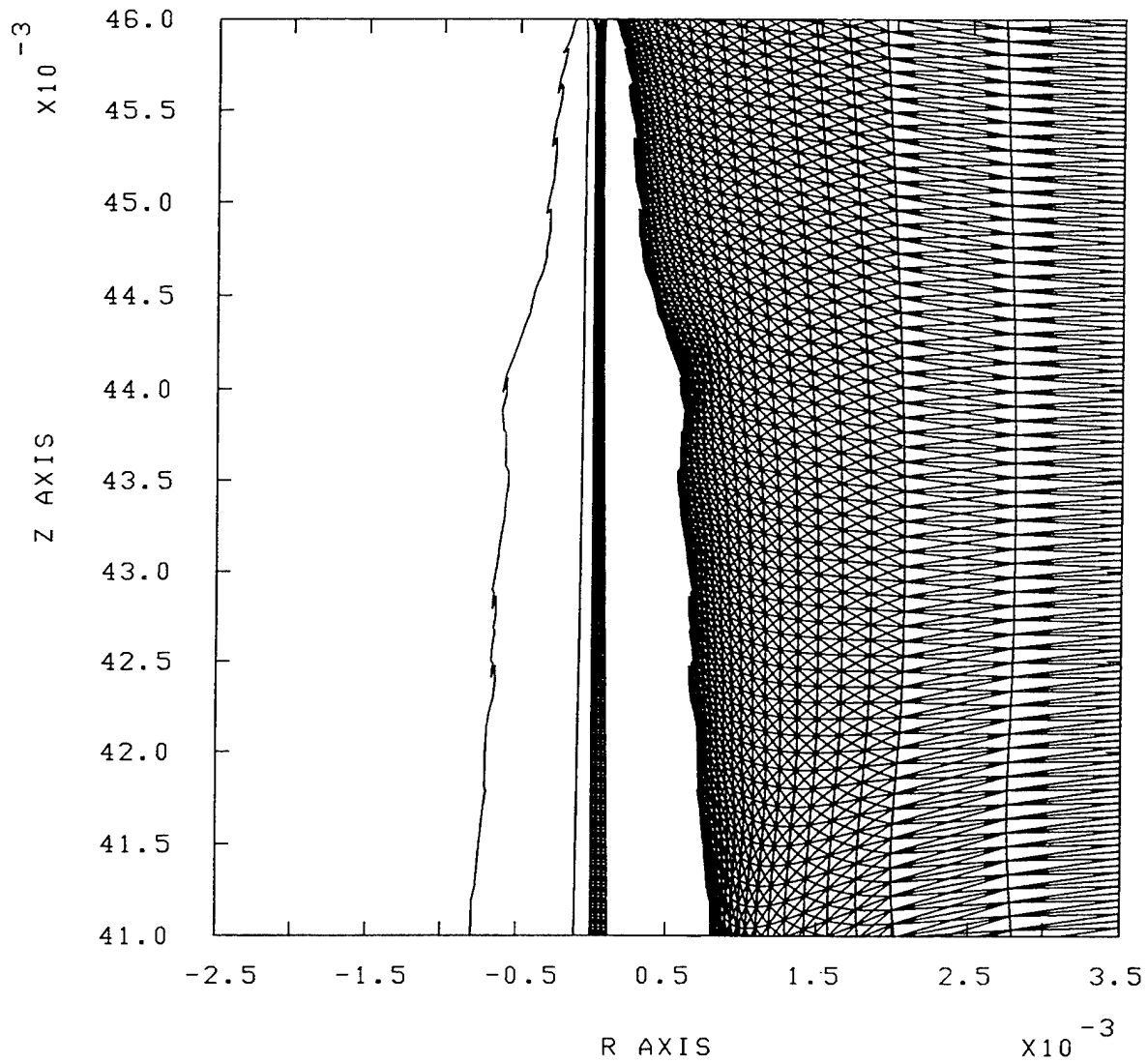
EPIC POST PROCESSOR, POST1 (1992-2) 09:33:52 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00000160; CYCLE = 2910



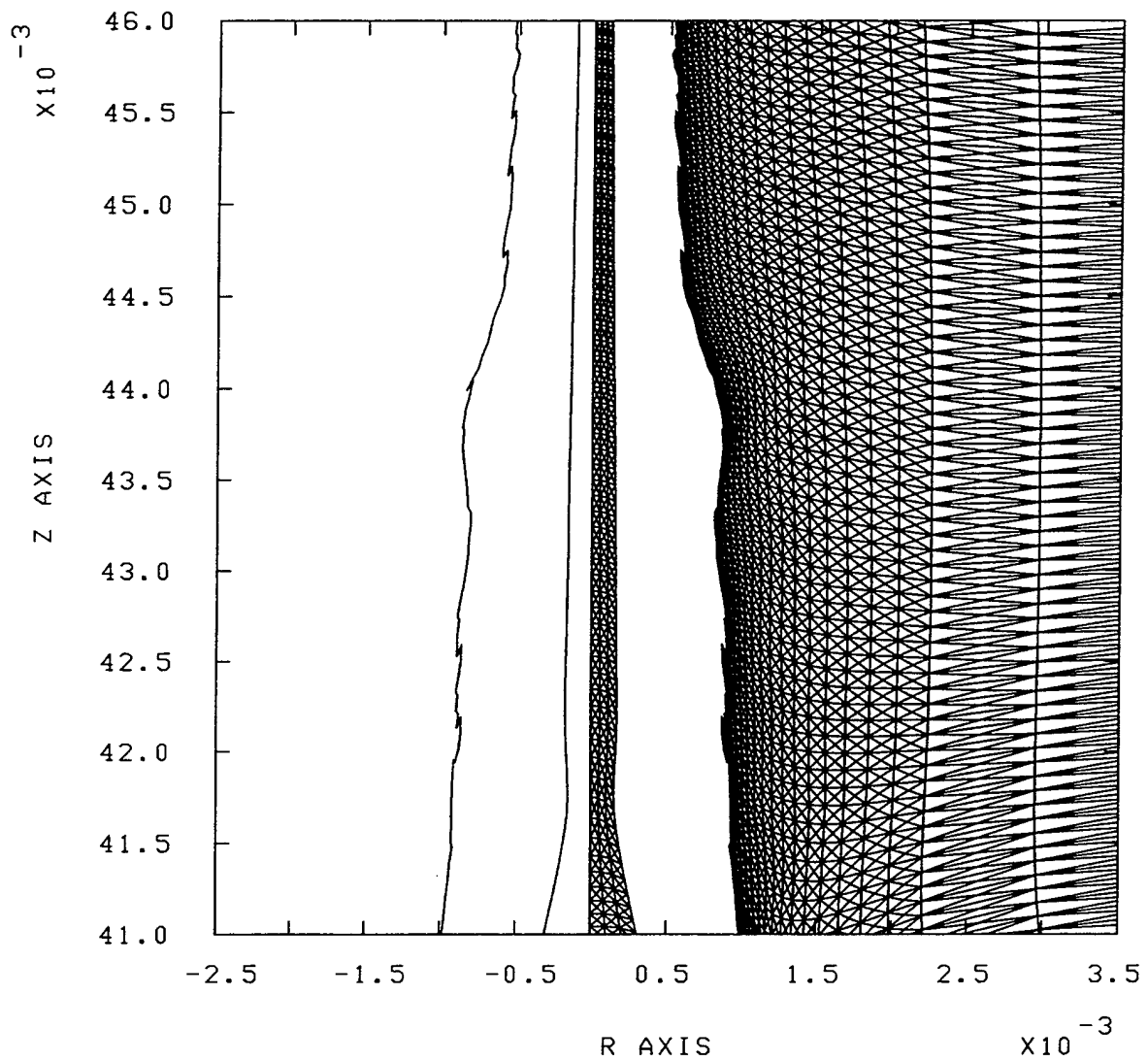
EPIC POST PROCESSOR, POST1 (1992-2) 09:34:40 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00000200; CYCLE = 3474



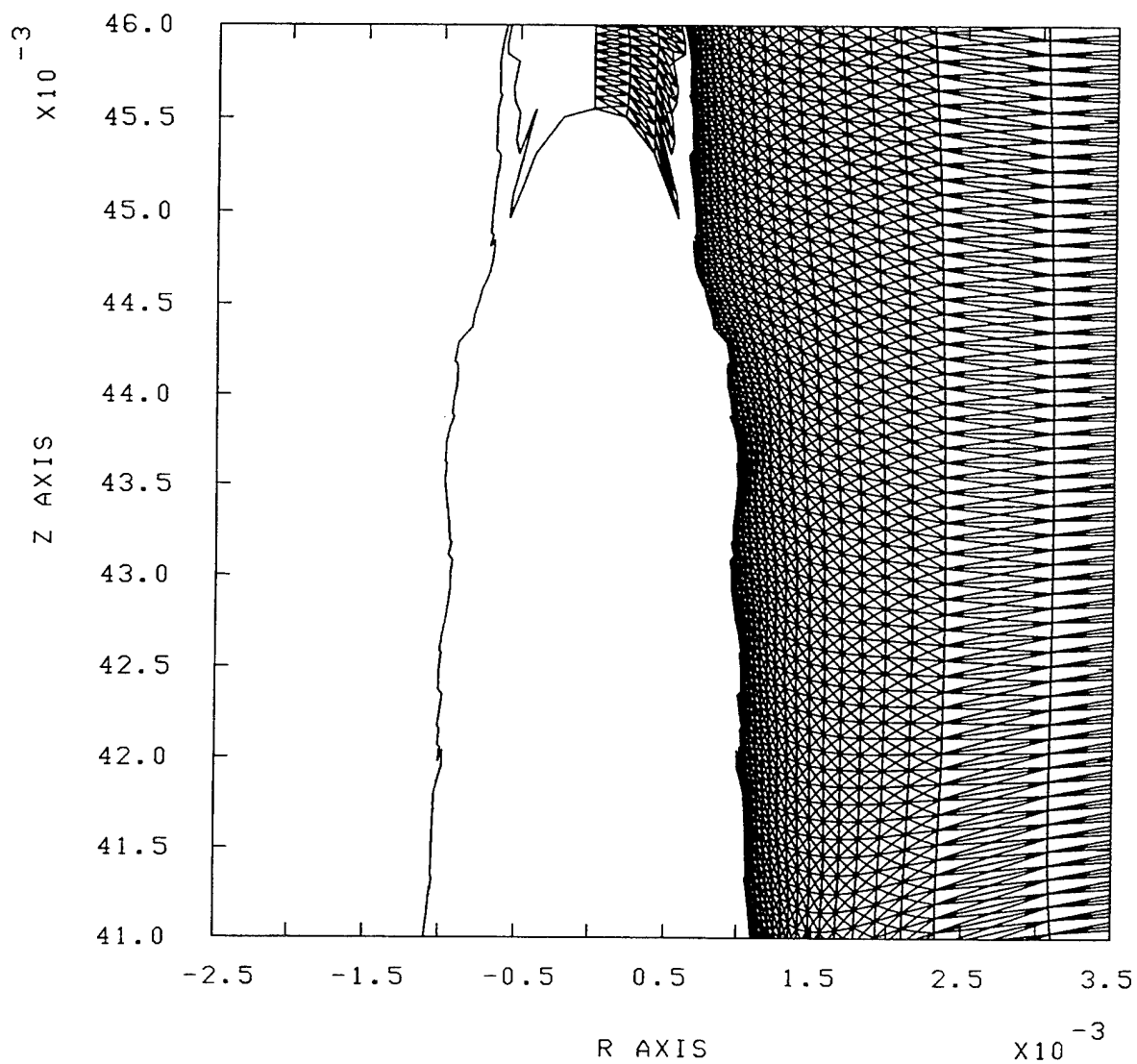
EPIC POST PROCESSOR, POST1 (1992-2) 09:35:26 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME =0.00000400; CYCLE = 6111



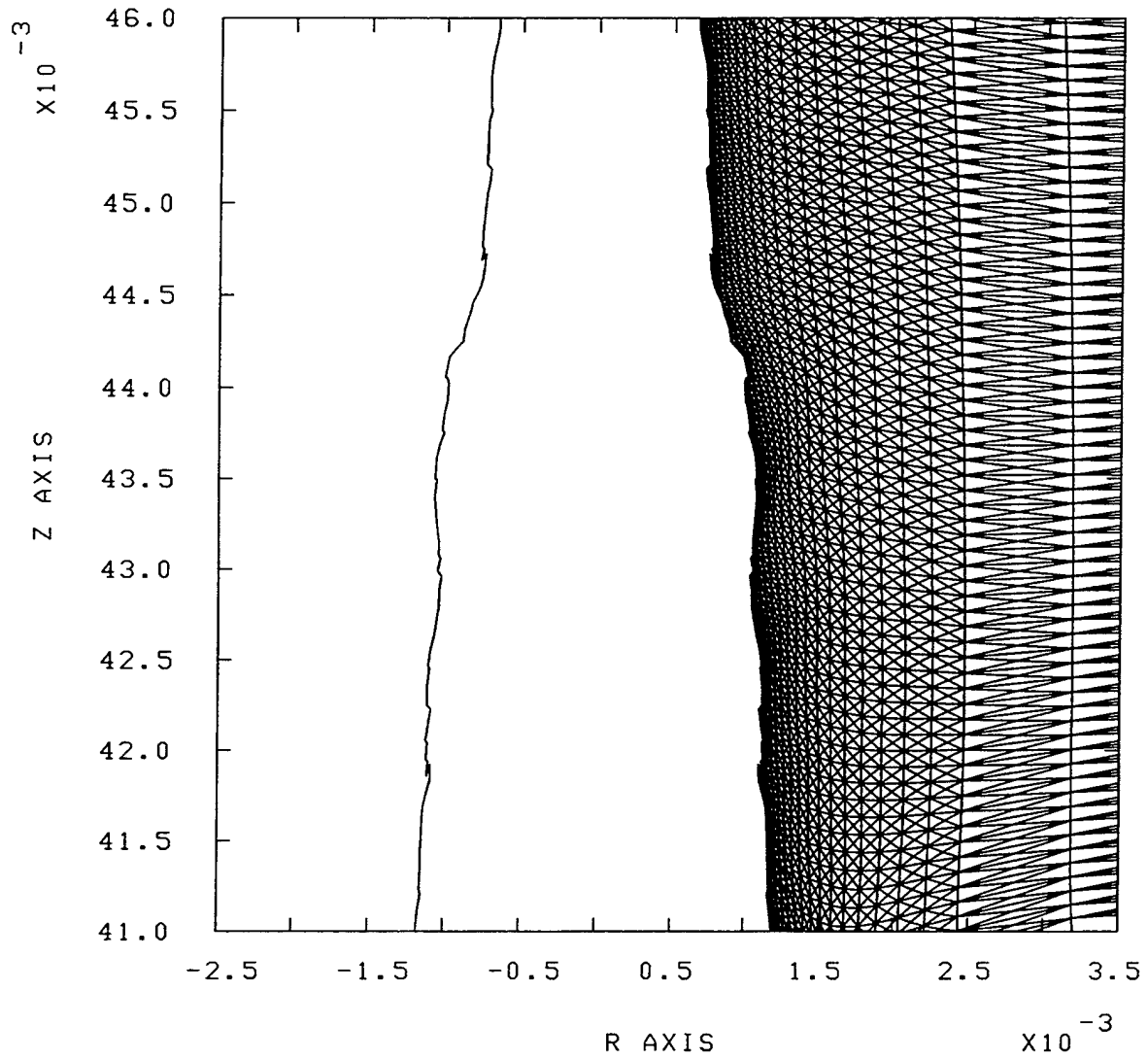
EPIC POST PROCESSOR, POST1 (1992-2) 09:35:58 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME =0.00000600; CYCLE = 8646



EPIC POST PROCESSOR, POST1 (1992-2) 09:36:22 25-Jul-94
2-D PLANE STRAIN GEOMETRY

Linear SC Jet Penetration ; CASE = 1; TIME = 0.00000800; CYCLE = 11163



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